Causal Inference: Estimation via Z Estimators

Hyunseung Kang

April 24, 2024

Abstract

Once the causal estimand is identified (i.e. the causal estimand is a function of the observed data), the next natural step is to estimate it with data. Here, we discuss an estimation approach using Z estimators. We'll first review Z estimators. Next, we'll show how to frame estimation of causal estimands as an instance of an Z estimation problem. This document assumes that you have taken an undergraduate course in mathematical statistics and an undergraduate course in linear algebra.

1 Review: Causal Identification

Causal identification is the exercise of equating a causal estimand into another estimand that is defined with only the observed data only. For example, we identified the average treatment effect under strong ignorability (i.e. $Y(1), Y(0) \perp A \mid X$ and $0 < P(A = 1 \mid X = x) < 1$ for all x) and SUTVA (i.e. Y = AY(1) + (1 - A)Y(0)) as follows:

ATE =
$$\mathbb{E}[Y(1) - Y(0)] = \mathbb{E}[\mu_1(X) - \mu_0(X)], \quad \mu_a(X) = \mathbb{E}[Y \mid A = a, X]$$

Once the causal estimands is identified, estimation focuses on estimating the estimand defined with the observed data, often referred to as a functional of the observed data. In the ATE example above, estimation involves estimating the functional $\mathbb{E}[\mu_1(X) - \mu_0(X)]$, which only consists of the observed data. We discuss how to do this using Z estimators. Throughout the document, we assume that we collect n i.i.d. samples from some common distribution.

2 Review: Z Estimators

2.1 Definition and Examples

Suppose we observe *n* i.i.d. samples of data $O_1, \ldots, O_n \stackrel{\text{iid}}{\sim} F$ from some distribution, denoted as *F*; note that O_i can be a scalar or a vector. Consider an estimator $\hat{\theta}$ that satisfies the following equation:

$$\frac{1}{n}\sum_{i=1}^{n}f(O_{i},\hat{\theta})=0, \quad f(O_{i},\boldsymbol{\theta})\in\mathbb{R}^{m}, \ \boldsymbol{\theta}\in\mathbb{R}^{d}$$

$$\tag{1}$$

where R_n is a sequence of random variables. Some estimators that satisfy equation (1) include

1. The sample mean can be written as

$$\frac{1}{n}\sum_{i=1}^{n}O_{i} - \hat{\theta} = 0, \quad f(O_{i}, \mu) = O_{i} - \theta, \ m = d = 1$$

Notice that this form remain the same for any distribution F (e.g. Normal, Poisson, Exponential, Exponential family, etc.).

2. The sample variance where the mean of F is unknown

$$\begin{pmatrix} \frac{1}{n} \sum_{i=1}^{n} O_i - \hat{\theta}_1 = 0\\ \frac{1}{n} \sum_{i=1}^{n} (O_i - \hat{\theta}_1)^2 - \hat{\theta}_2 = 0 \end{pmatrix}, \quad f(O_i, \theta) = \begin{pmatrix} O_i - \theta_1\\ (O_i - \theta_1)^2 - \theta_2 \end{pmatrix}, m = d = 2$$

Notice again that this form remains the same for any distribution F.

3. The maximum likelihood estimator (MLE) for a parametric distribution of O_i with density $p(o, \theta), \theta \in \mathbb{R}^d$:

$$\hat{\theta} = \underset{\theta \in \mathbb{R}^d}{\operatorname{argmax}} \prod_{i=1}^n p(O_i.\theta) = \underset{\theta \in \mathbb{R}^d}{\operatorname{argmax}} \sum_{i=1}^n \log(p(O_i,\theta))$$

To solve the optimization problem, we usually have to take the partial derivative of the log likelihood with respect to θ and set it equal to zero:

$$\frac{1}{n}\sum_{i=1}^{n}\frac{1}{p(O_{i},\hat{\theta})}\nabla_{\theta}p(O_{i},\hat{\theta}) = 0, \quad f(O_{i},\theta) = \frac{1}{p(O_{i},\theta)}\nabla_{\theta}p(O_{i},\theta), \ m = d$$

The function f above (i.e. the derivative of the log likelihood) is called the *score function*. The score function has the unique property that at the true value of the density, denoted as $p(o, \theta^*)$, its expectation is

$$\mathbb{E}\left[\frac{1}{p(O_i,\theta^*)}\nabla_{\theta}p(O_i,\theta^*)\right] = \int \frac{1}{p(o,\theta^*)}\nabla_{\theta}p(o,\theta^*)p(o,\theta^*)do =_a \int \nabla_{\theta}p(o,\theta^*)do = \nabla_{\theta} \int p(o,\theta^*)do = \nabla_{\theta} 1 = 0$$

The equality $=_a$ assumes that we can switch integration with differentiation.

4. Linear regression where given the outcome $Y_i \in \mathbb{R}$ and d predictors $X_i \in \mathbb{R}^d$, we solve the following optimization problem:

$$\hat{\theta} = \underset{\theta \in \mathbb{R}^d}{\operatorname{argmax}} \frac{1}{n} \sum_{i=1}^n (Y_i - X_i^{\mathsf{T}} \theta)^2.$$

We usually find the OLS estimator by taking the partial derivative of the objective with respect to θ and setting it equal to zero:

$$\frac{1}{n}\sum_{i=1}^{n}X_{i}(Y_{i}-X_{i}^{\mathsf{T}}\hat{\theta})=0, \quad f(O_{i},\theta)=X_{i}(Y_{i}-X_{i}^{\mathsf{T}}\theta), \ m=d$$

Note that $O_i = (Y_i, X_i)$.

5. Logistic regression where given a binary outcome A and d predictors $X \in \mathbb{R}^d$, we solve the following likelihood problem:

$$\hat{\theta} = \underset{\theta \in \mathbb{R}^d}{\operatorname{argmax}} \prod_{i=1}^n \pi(X_i, \theta)_i^A (1 - \pi(X_i, \theta)^{1 - A_i})$$
$$= \underset{\theta \in \mathbb{R}^d}{\operatorname{argmax}} \sum_{i=1}^n A_i \log(\pi(X_i, \theta)) + (1 - A_i) \log(1 - \pi(X_i, \theta)), \quad \pi(X_i, \theta) = \frac{\exp(X_i^\mathsf{T}\theta)}{1 + \exp(X_i^\mathsf{T}\theta)}$$

We can solve the above optimization by taking the derivative with respect to θ , i.e.

$$\begin{aligned} \nabla_{\theta} \sum_{i=1}^{n} A_{i} \log(\pi(X_{i},\theta)) + (1-A_{i}) \log(1-\pi(X_{i},\theta)) &= \sum_{i=1}^{n} \nabla_{\theta} \pi(X_{i},\theta) \left(\frac{A_{i}}{\pi(X_{i},\theta)} - \frac{1-A_{i}}{1-\pi(X_{i},\theta)}\right) \\ &= \sum_{i=1}^{n} \pi(X_{i},\theta) (1-\pi(X_{i},\theta)) X_{i} \left(\frac{A_{i}}{\pi(X_{i},\theta)} - \frac{1-A_{i}}{1-\pi(X_{i},\theta)}\right) \\ &= \sum_{i=1}^{n} X_{i} (A_{i} - \pi(X_{i},\theta)), \end{aligned}$$

and setting the above to zero, i.e.

$$\frac{1}{n}\sum_{i=1}^{n} X_i(A_i - \pi(X_i, \theta)) = 0, \quad f(O_i, \theta) = X_i(A_i - \pi(X_i, \theta)), \ m = d = p$$

2.2 Key Result

The following theorem characterize the asymptotic behavior of estimators that satisfy equation (1). Throughout all the theory, we'll let θ^* be a solution to the equation:

$$\mathbb{E}[f(O_i, \theta^*)] = 0 \tag{2}$$

You want θ^* to be equal to the true parameter you want to estimate (e.g. population mean, population variance, true β in regression). We'll show that the estimator $\hat{\theta}$ in equation (1) is asymptotically Normal around θ^* .

Theorem 1. Consider the case when m = d. Suppose (A1) there exists $\theta^* \in \mathbb{R}^d$ where $\mathbb{E}[f(O_i, \theta^*)] = 0$, (A2) $\mathbb{E}[\|f(O_i, \theta^*)\|_2^2] < \infty$, (A3) $\mathbb{E}[\nabla_{\theta} f(O_i, \theta) |_{\theta=\theta^*}]$ exists and is non-singular, (A4) for each θ in an open subset of \mathbb{R}^d , $\frac{\delta^2}{\delta \theta_j \theta_k} f(o, \theta)$ exists for every j, k, o and is continuous in θ , and (A5) for every $h = 1, \ldots, m$, there exists a fixed function g(o) where $\mathbb{E}[|g(O_i)|] < \infty$ and $|\frac{\delta^2}{\delta \theta_j \theta_k} f_h(o, \theta)| \le g(o)$ for every θ in a neighborhood of θ^* . Then, as long as the solution to $n^{-1} \sum_{i=1}^n f(O_i, \hat{\theta}) = 0$ is unique for every n, we have $\hat{\theta} \to \theta^*$ and

 $\sqrt{n}(\hat{\theta} - \theta^*) \to N\left(0, \mathbb{E}[\nabla_{\theta} f(O_i, \theta) \mid_{\theta = \theta^*}]^{-1} \mathbb{E}[f(O_i, \theta^*) f^{\mathsf{T}}(O_i, \theta^*)] \mathbb{E}[\nabla_{\theta} f(O_i, \theta) \mid_{\theta = \theta^*}]^{-\mathsf{T}}\right)$

Proof. See van der vaart, Theorem 5.41 and Theorem 5.42. In particular, the condition that there is a unique root to $n^{-1} \sum_{i=1}^{n} f(O_i, \hat{\theta}) = 0$ guarantees that the estimator $\hat{\theta}$ that the statistician actually obtains is consistent. \Box

This is not the most general theorem for Z estimators, but it's the easiest to understand¹. For causal inference, the goal is to apply this theorem by checking the conditions (A1)-(A5) and if necessary, making additional assumptions to make sure (A1)-(A5) are satisfied.

[add next year: asymptotic efficiency via MLE; local asymptotic minimaxity from Chamberlain 1987]

2.3 Application of Theorem 1

2.3.1 Sample Mean

For the sample mean, we show that (A1)-(A5) in Theorem 1 are satisfied if O_i has a finite second moment.

- (A1) We can take the expectation of f, i.e. $\mathbb{E}[f(O_i, \theta)] = \mathbb{E}[O_i] \theta = 0$. The values of θ that will make this equation equal to zero is $\theta = \mathbb{E}[O_i]$. In other words, $\theta^* = \mathbb{E}[O_i]$.
- (A2) We can evaluate $\mathbb{E}[(O_i \theta^*)^2] = \operatorname{Var}(O_i)$, which is finite because O_i has second moments.
- (A3) We have $\frac{\delta}{\delta\theta}f(O_i,\theta)|_{\theta=\theta^*} = -1$. An expectation of this derivative is finite and this value is non-singular.
- (A4) We have $\frac{\delta^2}{\delta^2 \theta} f(O_i, \theta) |_{\theta=\theta^*} = 0$ and thus, the second derivative s continuous for every θ .
- (A5) From (A4), since the second derivative is zero, it is dominated by a function g(o) = 1.

Also, for every *n*, the solution to $\frac{1}{n} \sum_{i=1}^{n} O_i - \hat{\theta} = 0$ is unique, namely that $\hat{\theta} = \frac{1}{n} \sum_{i=1}^{n} O_i$.

2.3.2 Sample Variance

For the sample variance, we show that (A1)-(A5) in Theorem 1 are satisfied if O_i has a finite fourth moment. (A1) We can take the expectation of f:

$$\mathbb{E}[f(O_i, \theta)] = \begin{pmatrix} \mathbb{E}[O_i] - \theta_1 \\ \mathbb{E}[(O_i - \theta_1)^2] - \theta_2 \end{pmatrix} = 0.$$

The values of θ_1, θ_2 that will make the above equation equal to zero is $\theta_1 = \mathbb{E}[O_i]$ and $\theta_2 = \operatorname{Var}[O_i]$. In other words, $\theta^* = (\mathbb{E}[O_i], \operatorname{Var}[O_i])$.

- (A2) For the first component of f, we have $\mathbb{E}[(O_i \theta_1^*)^2] = \operatorname{Var}(O_i)$, which is finite because O_i has finite fourth moments. For the second component of f, $\mathbb{E}[((O_i \theta_1^*)^2 \theta_2^*)^2] = \operatorname{Var}[(O_i \theta_1^*)^2]$ where the equality is by the definition of variance. If the fourth moment of O_i exists, $\operatorname{Var}[(O_i \theta_1^*)^2] \leq \mathbb{E}[(O_i \theta_1^*)^4]$ is finite.
- (A3) For each partial derivative, we have

$$\frac{\delta}{\delta\theta_1} f(O_i, \theta) \mid_{\theta=\theta^*} = \begin{pmatrix} -1 \\ -2(O_i - \theta_1^*) \end{pmatrix}, \quad \frac{\delta}{\delta\theta_2} f(O_i, \theta) \mid_{\theta=\theta^*} = \begin{pmatrix} 0 \\ -1 \end{pmatrix}$$

The expectation of these quantities are finite. Also, the matrix $E[\nabla_{\theta} f(O_i, \theta) |_{\theta=\theta^*}] = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$ is non-singular.

- (A4) From (A3), we see that any second partial derivatives of $f(o, \theta)$ with respect to θ will be constant and hence, is continuous.
- (A5) From (A4), since all second partial derivatives will be constant, they will be dominated by a function g(o) = 1.

Also, for every *n*, the solution to $\frac{1}{n} \sum_{i=1}^{n} f(O_i, \hat{\theta}) = 0$ is unique since $\hat{\theta}_1 = \frac{1}{n} \sum_{i=1}^{n} O_i$ and thus, $\hat{\theta}_2 = \frac{1}{n} \sum_{i=1}^{n} (O_i - \hat{\theta}_1)^2$

¹In Theorem 1, for those with a weak background in real analysis, you can replace "for each θ in an open subset of \mathbb{R}^{d} " with "for every $\theta \in \mathbb{R}^{d}$ " and "for every θ in a neighborhood of θ^* " with "for every θ ." These changes are more stringent than Theorem 1.

2.3.3 Linear Regression

For linear regression, we show that if

- (a) (Y_i, X_i) is generated from the following model: $Y_i = X_i^{\mathsf{T}} \theta^* + \epsilon_i$ where $\mathbb{E}[\epsilon_i \mid X_i] = 0$ and $\operatorname{Var}[\epsilon_i \mid X_i] = (\sigma^*)^2 < \infty$
- (b) the covariance matrix of X, denoted as $\Sigma_X = \mathbb{E}[X_i X_i^{\mathsf{T}}]$, is finite and positive definite
- (c) for every n, the matrix $\frac{1}{n} \sum_{i=1}^{n} X_i X_i^{\mathsf{T}}$ is invertible

the conditions (A1)-(A5) are satisfied.

- (A1) The values of θ that satisfies $\mathbb{E}[f(O_i, \theta)] = \mathbb{E}[X_i(Y_i X_i^{\mathsf{T}}\theta)] = 0$ is $\theta^* = \beta^*$ because $\mathbb{E}[X_i(Y_i X_i^{\mathsf{T}}\beta^*)] = \mathbb{E}[X_i\epsilon_i] = \mathbb{E}[X_i\mathbb{E}[\epsilon_i \mid X_i]] = 0$
- (A2) We have

$$\mathbb{E}[\|X_i(Y_i - X_i^{\mathsf{T}}\beta^*)\|_2^2] = \mathbb{E}[\|X_i\|_2^2\epsilon_i^2] = \mathbb{E}[\|X_i\|_2^2\mathbb{E}[\epsilon_i^2 \mid X_i]\|] = \mathbb{E}[\|X_i\|_2^2](\sigma^*)^2$$

Since Σ_X is finite, $\mathbb{E}[||X_i||_2^2]$ is bounded and thus, the whole expression is bounded.

- (A3) We have $\nabla_{\theta} f(O_i, \theta) = -X_i X_i^T$, whose expectation exists and is non-singular by assumption on Σ_X
- (A4) From (A3), $\frac{\delta^2}{\delta\theta_i\theta_k}f(o,\theta) = 0$ for any j, k, o and is trivially continuous for all θ .
- (A5) From (A4), the second partial derivatives are all bounded above by the constant function g(o) = 1.

Finally, the solution $\frac{1}{n} \sum_{i=1}^{n} X_i (Y_i - X_i^{\mathsf{T}} \hat{\theta}) = 0$ is unique because $\frac{1}{n} \sum_{i=1}^{n} X_i Y_i = \frac{1}{n} \sum_{i=1}^{n} X_i X_i^{\mathsf{T}} \hat{\theta}$ and so long as $\frac{1}{n} \sum_{i=1}^{n} X_i X_i^{\mathsf{T}}$ is invertible for every n, we have $\hat{\theta} = (\sum_{i=1}^{n} X_i X_i^{\mathsf{T}})^{-1} \sum_{i=1}^{n} X_i Y_i$.

3 Z Estimators of Causal Estimands

3.1 Basic Idea

We can construct a Z estimator of the ATE as follows. Suppose we pretend for a moment that we actually know the true $\mu_a(X)$. Then, a natural estimator of the ATE, denoted as $\hat{\theta}$, is simply the sample equivalent of $\mathbb{E}[\mu_1(X) - \mu_0(X)]$ or

$$\frac{1}{n}\sum_{i=1}^{n}\mu_1(X_i) - \mu_0(X_i) - \hat{\theta} = 0, \quad f(O_i, \theta) = \mu_1(X_i) - \mu_0(X_i) - \theta, \ m = d = 1.$$
(3)

Note that $O_i = X_i \in \mathbb{R}^p$. In other words, the estimator the ATE is equivalent to the sample mean of $\mu_1(X_i) - \mu_0(X_i)$. Then, applying Theorem 1, we arrive at the following corollary

Corollary 1 (Asymptotic Normality Under Known μ_a). Suppose the function $\mu_a(x) = \mathbb{E}[Y \mid A = a, X = x]$ is known a priori. Let $\hat{\theta} = n^{-1} \sum_{i=1}^{n} \mu_1(X_i) - \mu_0(X_i)$ and $\theta^* = \mathbb{E}[\mu_1(X_i) - \mu_0(X_i)]$, which also equal the ATE under SUTVA and strong ignorability. If $\mu_1(X_i) - \mu_0(X_i)$ have finite second moments, we have

$$\sqrt{n}(\hat{\theta} - \theta^*) \rightarrow N(0, \operatorname{Var}[\mu_1(X_i) - \mu_0(X_i)]).$$

Proof. This is a direct consequence of the sample mean example in Section 2.3.1 where $\mu_1(X_i) - \mu_0(X_i)$ is the new O_i .

Also, let $e(X_i) = P(A_i = 1 | X_i)$ be the propensity score and suppose this function is known; this would be the case in a randomized experiment. Consider the following estimator of the ATE, sometimes referred to as the inverses probability weighted (IPW) estimator:

$$\frac{1}{n}\sum_{i=1}^{n}\frac{Y_{i}A_{i}}{e(X_{i})} - \frac{Y_{i}(1-A_{i})}{1-e(X_{i})} - \hat{\theta} = 0, \quad f(O_{i},\theta) = \frac{Y_{i}A_{i}}{e(X_{i})} - \frac{Y_{i}(1-A_{i})}{1-e(X_{i})} - \theta, \quad m = d = 1$$
(4)

Note that $O_i = (Y_i, A_i, X_i)$. We can apply Theorem 1 and arrive at the following:

Corollary 2 (Asymptotic Normality Under Known Propensity Score). Suppose the function $\pi(x) = P(A_i = 1 | X_i = x)$ is known a priori and $0 < \pi(x) < 1$. Let $\hat{\theta} = n^{-1} \sum_{i=1}^{n} \frac{Y_i A_i}{e(X_i)} - \frac{Y_i (1-A_i)}{1-e(X_i)}$. If $\mathbb{E}[Y^2 | A = a, X]$ has finite second moments for a = 0, 1, we have

$$\begin{split} \sqrt{n}(\hat{\theta}-\theta^*) &\to N\left(0, \mathbb{E}\left[\frac{\mathbb{E}[Y_i^2 \mid A_i = 1, X]}{e(X_i)}\right] + \mathbb{E}\left[\frac{\mathbb{E}[Y_i^2 \mid A_i = 0, X]}{1 - e(X_i)}\right] - \left(\mathbb{E}[\mathbb{E}[Y \mid A = 1, X]] - \mathbb{E}[\mathbb{E}[Y \mid A = 0, X]]\right)^2\right) \\ where \ \theta^* &= \mathbb{E}[\mathbb{E}[Y_i \mid A_i = 1, X_i] - \mathbb{E}[Y_i \mid A_i = 1, X_i]] \end{split}$$

Proof. We go through each of the conditions in Theorem 1 below.

(A1) We see that

$$\mathbb{E}\left[\frac{Y_iA_i}{e(X_i)}\right] = \mathbb{E}\left[\frac{1}{e(X_i)}\mathbb{E}[Y_iA_i \mid X_i]\right] = \mathbb{E}\left[\frac{1}{e(X_i)}\mathbb{E}[Y_i \mid X_i, A_i = 1]P(A_i = 1 \mid X_i)\right] = \mathbb{E}[\mathbb{E}[Y_i \mid X_i, A_i = 1]]$$

A similar logic reveals $\mathbb{E}\left[\frac{Y_i(1-A_i)}{1-e(X_i)}\right] = \mathbb{E}[\mathbb{E}[Y_i \mid X_i, A_i = 0]]$. Then, the solution to the equation $\mathbb{E}[f(O_i, \theta^*)] = \mathbb{E}[\mathbb{E}[Y_i \mid X_i, A_i = 1]] - [\mathbb{E}[Y_i \mid X_i, A_i = 0]] - \theta^* = 0$ is equal to $\theta^* = \mathbb{E}[\mathbb{E}[Y_i \mid X_i, A_i = 1] - \mathbb{E}[Y_i \mid X_i, A_i = 0]]$

(A2) We have $\mathbb{E}[f(O_i, \theta^*)^2] = \operatorname{Var}\left[\frac{Y_i A_i}{e(X_i)} - \frac{Y_i(1-A_i)}{1-e(X_i)}\right]$, which is bounded by assumption.

(A3) We have $\frac{\delta}{\delta\theta} f(O_i, \theta) = -1$, which is non-singular.

(A4) The second partial derivative $\frac{\delta^2}{\delta^2 \theta} f(O_i, \theta) = 0$, which is continuous for all θ

(A5) The second partial derivative is always bounded above by the constant function g(o) = 1

Finally, it's obvious that the solution to $\frac{1}{n}\sum_{i=1}^{n} f(O_i, \hat{\theta}) = 0$ is unique. For the asymptotic variance, we have

$$\operatorname{Var}\left[\frac{Y_i A_i}{e(X_i)}\right] = \mathbb{E}\left[\frac{Y_i^2 A_i}{e^2(X_i)}\right] - \mathbb{E}\left[\frac{Y_i A_i}{e(X_i)}\right]^2 = \mathbb{E}\left[\frac{\mathbb{E}[Y_i^2 \mid A_i = 1, X]}{e(X_i)}\right] - \mathbb{E}[\mathbb{E}[Y \mid A = 1, X]]^2$$
$$\operatorname{Var}\left[\frac{Y_i(1 - A_i)}{1 - e(X_i)}\right] = \mathbb{E}\left[\frac{\mathbb{E}[Y_i^2 \mid A_i = 0, X]}{1 - e(X_i)}\right] - \mathbb{E}[\mathbb{E}[Y \mid A = 0, X]]^2$$
$$\operatorname{Cov}\left[\frac{Y_i A_i}{e(X_i)}, \frac{Y_i(1 - A_i)}{1 - e(X_i)}\right] = -\mathbb{E}\left[\frac{Y_i A_i}{e(X_i)}\right] \mathbb{E}\left[\frac{Y_i(1 - A_i)}{1 - e(X_i)}\right] = -\mathbb{E}[\mathbb{E}[Y \mid A = 1, X]] \cdot \mathbb{E}[\mathbb{E}[Y \mid A = 0, X]]$$

Combining the above results, we get

$$\begin{aligned} &\operatorname{Var}\left[\frac{Y_{i}A_{i}}{e(X_{i})} - \frac{Y_{i}(1 - A_{i})}{1 - e(X_{i})}\right] \\ = &\operatorname{Var}\left[\frac{Y_{i}A_{i}}{e(X_{i})}\right] + \operatorname{Var}\left[\frac{Y_{i}(1 - A_{i})}{1 - e(X_{i})}\right] - 2\operatorname{Cov}\left[\frac{Y_{i}A_{i}}{e(X_{i})}, \frac{Y_{i}(1 - A_{i})}{1 - e(X_{i})}\right] \\ = &\mathbb{E}\left[\frac{\mathbb{E}[Y_{i}^{2} \mid A_{i} = 1, X]}{e(X_{i})}\right] + \mathbb{E}\left[\frac{\mathbb{E}[Y_{i}^{2} \mid A_{i} = 0, X]}{1 - e(X_{i})}\right] - \left(\mathbb{E}[\mathbb{E}[Y \mid A = 1, X]] - \mathbb{E}[\mathbb{E}[Y \mid A = 0, X]]\right)^{2} \end{aligned}$$

3.2Estimation of the ATE with Estimated Nuisance Functions

Now, consider a more realistic scenario where $\mu_a(X)$ is unknown and must be estimated. For each A = a, suppose we use OLS to estimate $\mu_a(X)$, which can be written as the following Z estimators

$$\begin{pmatrix} \frac{1}{n} \sum_{i=1}^{n} X_i (Y_i - X_i^{\mathsf{T}} \hat{\beta} - \hat{\theta}) = 0 \\ \frac{1}{n} \sum_{i=1}^{n} A_i X_i (Y_i - X_i^{\mathsf{T}} \hat{\beta}_1) = 0 \end{pmatrix}, \quad f(O_i, (\beta_0, \beta_1)) = \begin{pmatrix} (1 - A_i) X_i (Y_i - X_i^{\mathsf{T}} \beta_0) \\ A_i X_i (Y_i - X_i^{\mathsf{T}} \beta_1) \end{pmatrix}, \quad m = d = 2p$$

We then plug in the predictions from the OLS estimator into equation (3). This plug-in estimator plus the OLS estimators of $\mu_a(\cdot)$ can be written as a Z estimator

$$\begin{pmatrix} \frac{1}{n} \sum_{i=1}^{n} X_{i}^{\mathsf{T}} \hat{\beta}_{1} - X_{i}^{\mathsf{T}} \hat{\beta}_{0} - \hat{\theta} = 0\\ \frac{1}{n} \sum_{i=1}^{n} (1 - A_{i}) X_{i} (Y_{i} - X_{i}^{\mathsf{T}} \hat{\beta}_{0}) = 0\\ \frac{1}{n} \sum_{i=1}^{n} A_{i} X_{i} (Y_{i} - X_{i}^{\mathsf{T}} \hat{\beta}_{1}) = 0 \end{pmatrix}, \quad f(O_{i}, (\theta, \beta_{0}, \beta_{1})) = \begin{pmatrix} X_{i}^{\mathsf{T}} \beta_{1} - X_{i}^{\mathsf{T}} \beta_{0} - \theta\\ (1 - A_{i}) X_{i} (Y_{i} - X_{i}^{\mathsf{T}} \beta_{0})\\ A_{i} X_{i} (Y_{i} - X_{i}^{\mathsf{T}} \beta_{1}) \end{pmatrix}, \quad m = d = 2p \quad (5)$$

Here, $O_i = (Y_i, A_i, X_i)$ and the first element of the vector f is the plug-in estimator $\hat{\theta}$ based on the OLS estimates of $\mu_a(X_i)$. In other words, the only difference between equation (3) and the equation (5) is that we are taking an average of estimated $\mu_a(X_i)$.

The following corollary shows that $\hat{\theta}$ in equation 5 is asymptotically Normal.

Proposition 1. Consider the estimator $\hat{\theta} = \frac{1}{n} \sum_{i=1}^{n} X_i^{\mathsf{T}} \hat{\beta}_1 - X_i^{\mathsf{T}} \hat{\beta}_0$ where $\hat{\beta}_a$ is defined in equation 3. Suppose the following conditions hold:

• (a) (Y_i, X_i, A_i) follows the model

$$Y_{i} = \begin{cases} X_{i}^{\mathsf{T}}\beta_{0}^{*} + \epsilon_{0,i}, \ \mathbb{E}[\epsilon_{0,i} \mid X_{i}, A_{i} = 0] = 0, \ \operatorname{Var}[\epsilon_{0,i} \mid X_{i}, A_{i} = 0] = (\sigma_{0}^{*})^{2} & \text{if } A_{i} = 0 \\ X_{i}^{\mathsf{T}}\beta_{1}^{*} + \epsilon_{1,i}, \ \mathbb{E}[\epsilon_{0,i} \mid X_{i}, A_{i} = 1] = 0, \ \operatorname{Var}[\epsilon_{0,i} \mid X_{i}, A_{i} = 1] = (\sigma_{1}^{*})^{2} & \text{if } A_{i} = 1 \end{cases}$$

and the variances $(\sigma_a^*)^2$ are finite. Note that this assumption implicitly assumes positivity, i.e. $0 < P(A_i \mid X_i = x) < 1$ for every x

- (b) The covariance matrix of X given A = a, denoted as $\Sigma_{X|a} = \text{Cov}[X_i \mid A_i = a]$, is finite and is non-singular for each a = 0, 1
- (c) For every n, the matrices $\frac{1}{n}\sum i = 1^n A_i X_i X_i^{\mathsf{T}}$ and $\frac{1}{n}\sum_{i=1}^n (1-A_i) X_i X_i^{\mathsf{T}}$ are invertible.

Then, we have

$$\sqrt{n}(\hat{\theta} - \theta^*) \to N\left(0, \operatorname{Var}[X_i^{\mathsf{T}}(\beta_1^* - \beta_0^*)]\right)$$

where $\theta^* = \mathbb{E}[X_i^\mathsf{T}\beta_1^* - X_i^\mathsf{T}\beta_0^*]$

Proof. We show that the five conditions in Theorem 1 hold for the Z-estimator written in equation (5).

(A1) If we define $\theta^* = (\mathbb{E}[X_i^{\mathsf{T}}\beta_1^* - X_i^{\mathsf{T}}\beta_0^*], \beta_0^*, \beta_1^*)$, the first element of f is zero. The other parts of f become zero because

$$\mathbb{E}[(1 - A_i)X_i(Y_i - X_i^{\mathsf{T}}\beta_0^*)] = \mathbb{E}[X_i(Y_i - X_i^{\mathsf{T}}\beta_0) \mid A_i = 0]\mathbb{P}(A_i = 0)$$

= $\mathbb{E}[X_i(\mathbb{E}[Y_i \mid X_i, A_i = 0] - X_i^{\mathsf{T}}\beta_0^*) \mid A_i = 0]\mathbb{P}(A_i = 0)$
= $\mathbb{E}[X_i(X_i^{\mathsf{T}}\beta_0^* - X_i^{\mathsf{T}}\beta_0^*) \mid A_i = 0]\mathbb{P}(A_i = 0)$
= 0,

and the same argument can show that $\mathbb{E}[A_i X_i (Y_i - X_i^{\mathsf{T}} \beta_1^*)] = 0.$

(A2) Let $q = \max((\sigma_0^*)^2, (\sigma_1^*)^2)$, which must be bounded. Then,

$$\begin{split} & \mathbb{E}[\|f(O_{i},\theta^{*})\|_{2}^{2}] \\ = & \operatorname{Var}[X_{i}^{\mathsf{T}}(\beta_{1}^{*}-\beta_{0}^{*})] + \mathbb{E}[\|X_{i}\|_{2}^{2}(1-A_{i})(Y_{i}-X_{i}^{\mathsf{T}}\beta_{0}^{*})^{2}] + \mathbb{E}[\|X_{i}\|_{2}^{2}A_{i}(Y_{i}-X_{i}^{\mathsf{T}}\beta_{1}^{*})^{2}] \\ = & \operatorname{Var}[X_{i}^{\mathsf{T}}(\beta_{1}^{*}-\beta_{0}^{*})] + \mathbb{E}[\|X_{i}\|_{2}^{2}(Y_{i}-X_{i}^{\mathsf{T}}\beta_{0}^{*})^{2} \mid A_{i}=0]\mathbb{P}(A_{i}=0) + \mathbb{E}[\|X_{i}\|_{2}^{2}(Y_{i}-X_{i}^{\mathsf{T}}\beta_{1}^{*})^{2} \mid A_{i}=1]\mathbb{P}(A_{i}=1) \\ = & \operatorname{Var}[X_{i}^{\mathsf{T}}(\beta_{1}^{*}-\beta_{0}^{*})] + \mathbb{E}[\|X_{i}\|_{2}^{2} \mid A_{i}=0](\sigma_{0}^{*})^{2}\mathbb{P}(A_{i}=0) + \mathbb{E}[\|X_{i}\|_{2}^{2} \mid A_{i}=1](\sigma_{1}^{*})^{2}\mathbb{P}(A_{i}=1) \end{split}$$

Since $\Sigma_{X|a}$ is finite, the above term are bounded.

(A3) The partial derivatives with respect to θ , β_1 , β_0 yield

$$\frac{\delta}{\delta\theta} f(O_i, \theta) \mid_{\theta=\theta^*} = (-1, \mathbf{0}) \in \mathbb{R}^{2p+1}$$

$$\frac{\delta}{\delta\beta_{1,k}} f(O_i, \theta) \mid_{\theta=\theta^*} = (X_{ik}, -A_i X_i X_{ik}, \mathbf{0}) \in \mathbb{R}^{2p+1}, \quad k = 1, \dots, p$$

$$\frac{\delta}{\delta\beta_{0,k}} f(O_i, \theta) \mid_{\theta=\theta^*} = (-X_{ik}, \mathbf{0}, -(1-A_i) X_i X_{ik}) \in \mathbb{R}^{2p+1}, \quad k = 1, \dots, p$$

This implies the gradient

$$\mathbb{E}[\nabla_{\theta} f(O_i, \theta) \mid_{\theta=\theta^*}] = \begin{pmatrix} -1 & \mathbb{E}[X_i] & -\mathbb{E}[X_i] \\ \mathbf{0} & -\mathbb{E}[A_i X_i X_i^{\mathsf{T}}] & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & -\mathbb{E}[(1-A_i) X_i X_i^{\mathsf{T}}] \end{pmatrix} = \begin{pmatrix} -1 & \mathbb{E}[X_i] & -\mathbb{E}[X_i] \\ \mathbf{0} & -\Sigma_{X|1} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & -\Sigma_{X|0} \end{pmatrix}$$

Using the property of determinants, the determinant of the above matrix is $-1 * \det(\Sigma_{X|1}) \det(\Sigma_{X|0})$, which is non-zero by the non-singularity of the covariance matrices and thus, the expectation of the gradient is non-singular.

(A4) From (A3), all of the second partial derivatives must be zero and thus, is continuous in θ

(A5) From (A4), every second partial derivative is uniformly bounded above by the function q(0) = 1

Finally, for every *n*, the solutions to $\hat{\beta}_1$ and $\hat{\beta}_0$ are unique in the equation $\frac{1}{n} \sum_{i=1}^n f(O_i, (\hat{\theta}, \hat{\beta}_1, \hat{\beta}_0)) = 0$ based on the arguments in the linear regression example. If $\hat{\beta}_1$ and $\hat{\beta}_0$ are unique, then the solution $\hat{\theta}$ is also unique.

Finally, the asymptotic variance can be derived as follows. First, inverting the gradient gives us equal to

$$\mathbb{E}[\nabla_{\theta} f(O_{i},\theta) \mid_{\theta=\theta^{*}}]^{-1} = \begin{pmatrix} -1 & \mathbb{E}[X_{i}] & -\mathbb{E}[X_{i}] \\ \mathbf{0} & -\Sigma_{X|1} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & -\Sigma_{X|0} \end{pmatrix}^{-1} = \begin{pmatrix} -1 & -\mathbb{E}[X_{i}]\Sigma_{X|1}^{-1} & \mathbb{E}[X_{i}]\Sigma_{X|0}^{-1} \\ \mathbf{0} & -\Sigma_{X|1}^{-1} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & -\Sigma_{X|1}^{-1} \end{pmatrix}$$

Second, the inner matrix $\mathbb{E}[f(O_i, \theta^*)f(O_i, \theta^*)^{\mathsf{T}}]$ simplifies to

$$\mathbb{E}[f(O_i, \theta^*)f(O_i, \theta^*)^{\mathsf{T}}] = \begin{pmatrix} \operatorname{Var}[X_i^{\mathsf{T}}(\beta_1^* - \beta_0^*)] & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \Sigma_{X|1}(\sigma_1^*)^2 & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \Sigma_{X|0}(\sigma_0^*)^2 \end{pmatrix}$$

The off-diagonal elements use the fact that

$$\mathbb{E}[(X_i^{\mathsf{T}}\beta_1^* - X_i^{\mathsf{T}}\beta_0^* - \theta^*)(1 - A_i)(Y_i - X_i^{\mathsf{T}}\beta_0^*)] = \mathbb{E}[(X_i^{\mathsf{T}}\beta_1^* - X_i^{\mathsf{T}}\beta_0^* - \theta^*)\mathbb{E}[(Y_i - X_i^{\mathsf{T}}\beta_0^*) \mid X_i, A_i = 0]] = 0 \\ \mathbb{E}[(X_i^{\mathsf{T}}\beta_1^* - X_i^{\mathsf{T}}\beta_0^* - \theta^*)A_i(Y_i - X_i^{\mathsf{T}}\beta_1^*)] = \mathbb{E}[(X_i^{\mathsf{T}}\beta_1^* - X_i^{\mathsf{T}}\beta_0^* - \theta^*)\mathbb{E}[(Y_i - X_i^{\mathsf{T}}\beta_1^*) \mid X_i, A_i = 1]] = 0 \\ \mathbb{E}[A_i(Y_i - X_i^{\mathsf{T}}\beta_1^*)(1 - A_i)(Y_i - X_i^{\mathsf{T}}\beta_0^*)] = 0$$

Third, multiplying the matrices above and extracting the (1, 1) element gives us the desired result.

An interesting phenomena occurs for the IPW estimator if we use an estimated $\hat{e}(X_i)$ instead of the true \hat{e} .

Proposition 2. Consider the IPW estimator $\hat{\theta} = \frac{1}{n} \sum_{i=1}^{n} \frac{Y_i A_i}{\hat{e}(X_i)} - \frac{Y_i(1-A_i)}{1-\hat{e}(X_i)}$ where $\hat{e}(X_i) = \hat{p} = \frac{1}{n} \sum_{i=1}^{n} A_i$. Suppose the following conditions hold: (a) $\mathbb{E}[Y^2 \mid A = a]$ is bounded for a = 0, 1, (b) $\mathbb{E}[A_i]$ is far from 0 and 1, and (c) for every n, \hat{p} is far from 0 and 1. Let $\theta^* = \mathbb{E}[\mathbb{E}[Y_i \mid A_i = 1] - \mathbb{E}[Y_i \mid A_i = 0]]$. Let σ^2 be the asymptotic variance under Corollary 2 where we use the true $e(X_i)$. Then, we have

$$\sqrt{n}(\hat{\theta} - \theta^*) \to N(0, \sigma^2 - q^2)$$

where $q^2 \ge 0$.

Proposition 2 shows that the asymptotic variance of the IPW estimator is less than or equal to the asymptotic variance of the IPW estimator with a known p^* . This does not occur with the estimator based on the outcome regression.

Proof. The corresponding Z estimator is

$$\begin{pmatrix} \frac{1}{n} \sum_{i=1}^{n} \frac{Y_{i}A_{i}}{\hat{p}} - \frac{Y_{i}(1-A_{i})}{1-\hat{p}} - \hat{\theta} = 0\\ \frac{1}{n} \sum_{i=1}^{n} A_{i} - \hat{p} = 0 \end{pmatrix}, \quad f(O_{i}, \theta, p) = \begin{pmatrix} \frac{Y_{i}A_{i}}{p} - \frac{Y_{i}(1-A_{i})}{1-p} - \theta\\ A_{i} - p \end{pmatrix}, \ m = d = 2$$

We show that the five conditions in Theorem 1 hold.

(A1) The solution to $\mathbb{E}[f(O_i, \theta^*, p^*)] = 0$ exists and they are $p^* = \mathbb{E}[A_i]$ and $\theta^* = \mathbb{E}[\mathbb{E}[Y \mid A = 1] - \mathbb{E}[Y \mid A = 0]]$. (A2) We have

$$\mathbb{E}[\|f(O_i, \theta^*, p^*)\|_2^2] = \mathbb{E}\left[\left(\frac{Y_i A_i}{p^*} - \frac{Y_i(1 - A_i)}{1 - p^*} - \theta^*\right)^2\right] + \mathbb{E}[(A_i - p^*)^2]$$
$$= \operatorname{Var}\left[\frac{Y_i A_i}{p^*} - \frac{Y_i(1 - A_i)}{1 - p^*}\right] + p^*(1 - p^*)$$

The last expression is bounded above by assumption.

(A3) The first-order partial derivatives are

$$\begin{split} \frac{\delta}{\delta\theta} f(O_i,\theta,p) \mid_{\theta=\theta^*,p=p^*} &= \{-1,0\} \\ \frac{\delta}{\delta p} f(O_i,\theta,p) \mid_{\theta=\theta^*,p=p^*} &= \left\{-1\left(\frac{Y_iA_i}{(p^*)^2} + \frac{Y_i(1-A_i)}{(1-p^*)^2}\right), -1\right\} \\ \mathbb{E}\left[\frac{\delta}{\delta p} f(O_i,\theta,p) \mid_{\theta=\theta^*,p=p^*}\right] &= \left\{-1\left(\frac{\mathbb{E}[\mathbb{E}[Y_i \mid A_i=1]]}{p^*} + \frac{\mathbb{E}[\mathbb{E}[Y_i \mid A_i=0]]}{(1-p^*)}\right), -1\right\} \end{split}$$

Thus, $\mathbb{E}[\nabla_{\theta,\beta}f(O_i,\theta,p)|_{\theta=\theta^*,p=p^*}]$ exists and is non-singular.

(A4) All of the second partial derivatives are zero except

$$\frac{\delta}{\delta^2 p} f(O_i, \theta, p) = \left\{ -2\left(\frac{Y_i(1-A_i)}{(1-p)^3} - \frac{Y_iA_i}{p^3}\right), 0 \right\}$$

This exists and is continuous within a neighborhood of p^* that is far from 0 and 1.

(A5) All elements of the Hessian matrix is bounded above by g(o) = 1 except for the Hessian corresponding to the second partial derivatives of p. For that component, since $\mathbb{E}[A_i]$ is far from 0 and 1, there exists $\delta > 0$ such that $\delta < \mathbb{E}[A_i] < 1 - \delta$. Consider a function g such that $g(o) = 2 * Y_i((1 - A_i)(1 - \delta)^3 + A_i\delta^3)$. This g function satisfies

$$\left| -2\left(\frac{Y_i(1-A_i)}{(1-p)^3} - \frac{Y_iA_i}{p^3}\right) \right| \le 2*|Y_i| \cdot |(1-A_i)(1-\delta)^3 + A_i\delta^3|$$

Furthermore, we have $\mathbb{E}[|g(O_i)|] = 2\mathbb{E}[(1-\delta)^3\mathbb{E}[|Y_i| \mid A_i = 0](1-p^*) + \delta^*\mathbb{E}[|Y_i| \mid A_i = 1]p^*]$, which is bounded above by the finite moment assumption on Y_i given $A_i = a$.

We also guarantee that the solution is unique at every n by ensuring that \hat{p} is far from 0 and 1. For the asymptotic variance, we get

$$\begin{split} & \mathbb{E}[\nabla_{\theta,p}f(O_{i},\theta,p)\mid_{\theta=\theta^{*},p=p^{*}}] = \begin{pmatrix} -1 & -1\left(\frac{\mathbb{E}[\mathbb{E}[Y_{i}|A_{i}=1]]}{p^{*}} + \frac{\mathbb{E}[\mathbb{E}[Y_{i}|A_{i}=0]]}{(1-p^{*})}\right) \\ & 0 & -1 \end{pmatrix} \\ & \mathbb{E}[\nabla_{\theta,p}f(O_{i},\theta,p)\mid_{\theta=\theta^{*},p=p^{*}}]^{-1} = \begin{pmatrix} -1 & \left(\frac{\mathbb{E}[\mathbb{E}[Y_{i}|A_{i}=1]]}{p^{*}} + \frac{\mathbb{E}[\mathbb{E}[Y_{i}|A_{i}=0]]}{(1-p^{*})}\right) \\ & 0 & -1 \end{pmatrix} \\ & \mathbb{E}[f(O_{i},\theta^{*},p^{*})f(O_{i},\theta^{*},p^{*})^{\mathsf{T}}] = \begin{pmatrix} \operatorname{Var}\left[\frac{Y_{i}A_{i}}{p^{*}} - \frac{Y_{i}(1-A_{i})}{1-p^{*}}\right] \\ & \mathbb{E}[Y_{i}\mid A_{i}=1](1-p^{*}) + \mathbb{E}[Y_{i}\mid A_{i}=0]p^{*} \end{pmatrix} \\ & \mathbb{E}[Y_{i}\mid A_{i}=1](1-p^{*}) + \mathbb{E}[Y_{i}\mid A_{i}=0]p^{*} \end{pmatrix} \end{split}$$

Putting it all together and some painful algebra leads to

$$\mathbb{E}[f(O_i, \theta^*, p^*)f(O_i, \theta^*, p^*)^{\mathsf{T}}]^{-1} \mathbb{E}[f(O_i, \theta^*, p^*)f(O_i, \theta^*, p^*)^{\mathsf{T}}] \mathbb{E}[f(O_i, \theta^*, p^*)f(O_i, \theta^*, p^*)^{\mathsf{T}}]^{-\mathsf{T}}$$
$$= \operatorname{Var}\left[\frac{Y_i A_i}{p^*} - \frac{Y_i(1 - A_i)}{1 - p^*}\right] - \frac{(\mathbb{E}[Y \mid A = 1](1 - p^*) + \mathbb{E}[Y \mid A = 0]p^*)^2}{p^*(1 - p^*)}$$