

CS 540 Introduction to Artificial Intelligence Search III: Advanced Search (aka Optimization) University of Wisconsin-Madison

Spring 2023

Homeworks:

- Homework 10 due Thursday
- Course evaluation due Friday

Class roadmap:

Tuesday, May 2	Advanced Search
Thursday, May 4	Ethics and Review
Friday, May 12 5:05 - 7:05pm	Final Exam

Problem Setting

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How is a search problem defined?

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How is a search problem defined? How different from other search types?

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Hill Climbing

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Genetic Algorithms

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Neighbors Local vs. global optima

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Neighbors Local vs. global optima Genetic Algorithms

What is difference between two?

Fitness
Population
Cross-over
Mutation

- Advanced Search & Hill-climbing
 - More difficult problems, basics, local optima, variations

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 - More difficult problems, basics, local optima, variations
- Hill Climbing
 - Basic algorithm, local optima
- Genetic Algorithms
 - Basics of evolution, fitness, natural selection

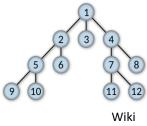
Before: wanted a **path** from start state to goal state

Before: wanted a path from start state to goal state

Uninformed search, informed search

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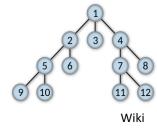
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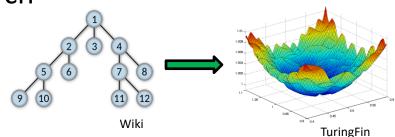
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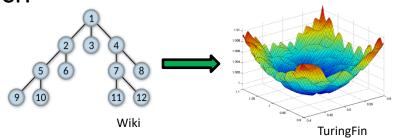


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States s have values f(s)

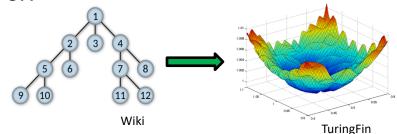


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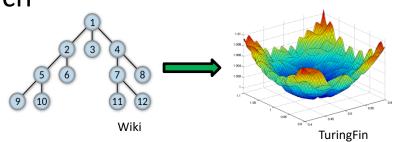


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New setting: optimization

- States s have values f(s)
- Want: Find s with optimal value f(s) (i.e, optimize over states)
- Challenging settings: too many states for previous search approaches, but maybe not a differentiable function for gradient descent.



A classic puzzle:

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• Place 8 queens on 8 x 8 chessboard so that no two have same row, column, or diagonal.

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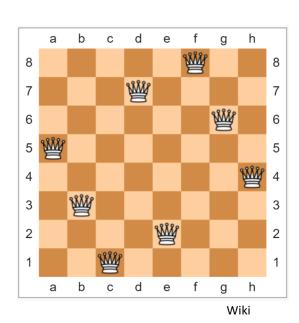
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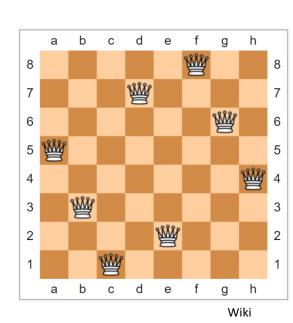
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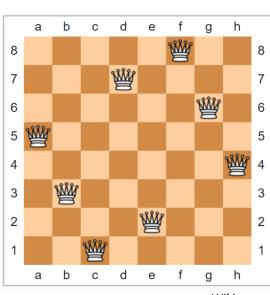
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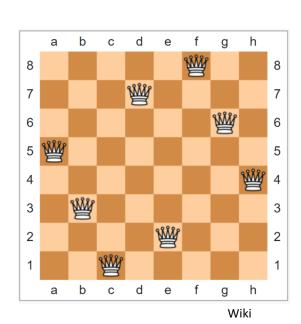
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Can generalize to n x n chessboard.

- What are states s? Values f(s)?
 - State: configuration of the board
 - f(s): # of non-conflicting queens

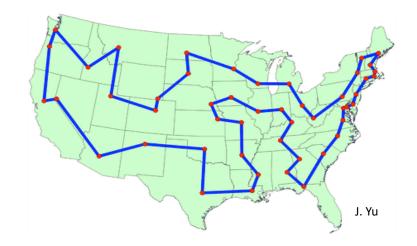


Famous graph theory problem.

• Get a graph G = (V,E). **Goal**: a path that visits each node exactly once and returns to the initial node (a **tour**).

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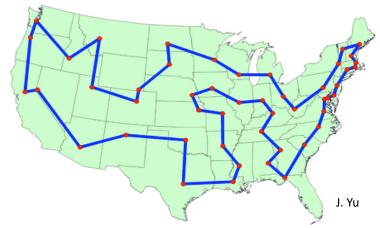
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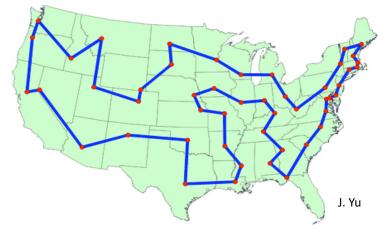
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 - f(s): total weight of the tour(e.g., total miles traveled)



Boolean satisfiability (e.g., 3-SAT)

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$$(A \lor \neg B \lor C) \land (\neg A \lor C \lor D) \land (B \lor D \lor \neg E) \land (\neg C \lor \neg D \lor \neg E) \land (\neg A \lor \neg C \lor E)$$

Boolean satisfiability (e.g., 3-SAT)

Recall our logic lecture. Conjunctive normal form

$$(A \lor \neg B \lor C) \land (\neg A \lor C \lor D) \land (B \lor D \lor \neg E) \land (\neg C \lor \neg D \lor \neg E) \land (\neg A \lor \neg C \lor E)$$

Goal: find if satisfactory assignment exists.

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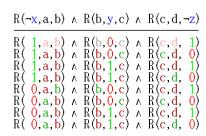
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R(x,a,d)	٨	R(y,b,d)	٨	R(a,b,e)	Λ	R(c,d,f)	٨	R(z,c,0)
R(0,a,d) R(1,a,d) R(1,a,d)	V V	R(1,b,d) R(0,b,d) R(0,b,d)	V V	K(a,b,e) R(a,b,e) R(a,b,e)	V V	R(c,d,f) R(c,d,f) R(c,d,f) R(c,d,f) R(c,d,f) R(c,d,f) R(c,d,f) R(c,d,f)	٨	R(1,c,0) R(0,c,0) R(1,c,0)



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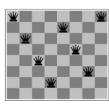
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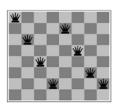
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 - Not as obvious as our successors in search
 - Problem-specific
 - As we'll see, needs a careful choice



In n Queens, a simple possibility:



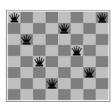


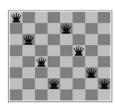


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• Look at the most-conflicting column (ties? right-most one)



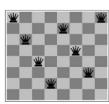


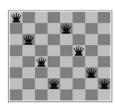


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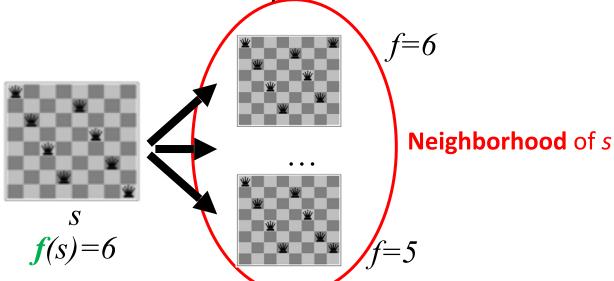




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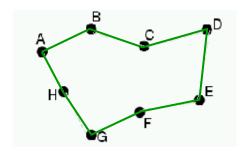


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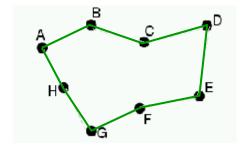
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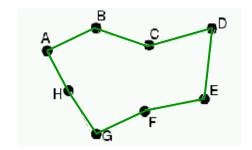
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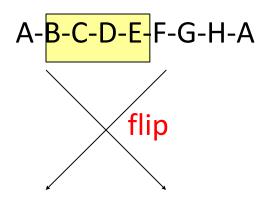
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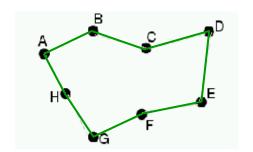


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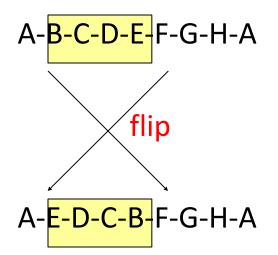


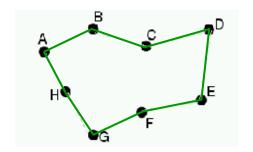
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A v ¬B v C
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- Tradeoff!



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Neighborhood too small? Will get struck.



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Hill Climbing Neighbors

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- Q: how to pick a neighbor? Greedy
- Q: terminate? When no neighbor has better value



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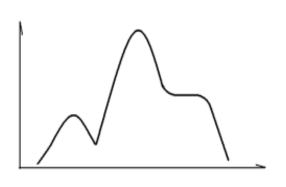
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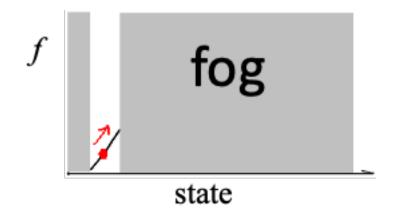
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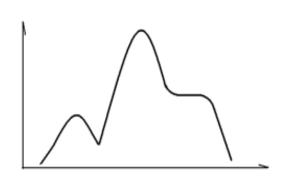


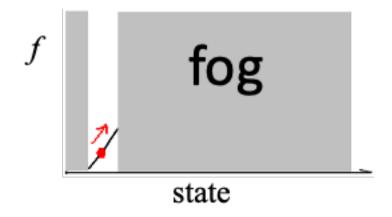
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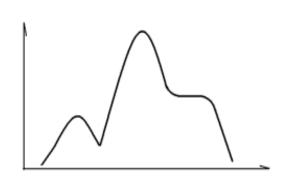


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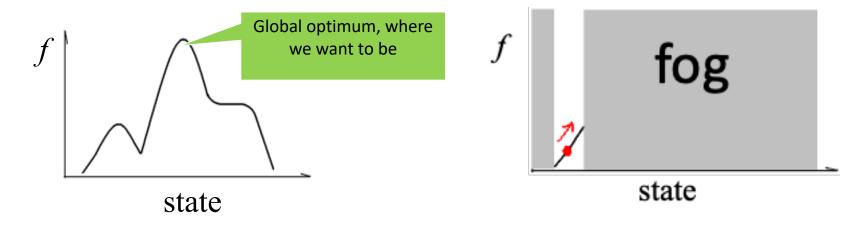


fog

L: What's actually going on.

R: What we get to see.

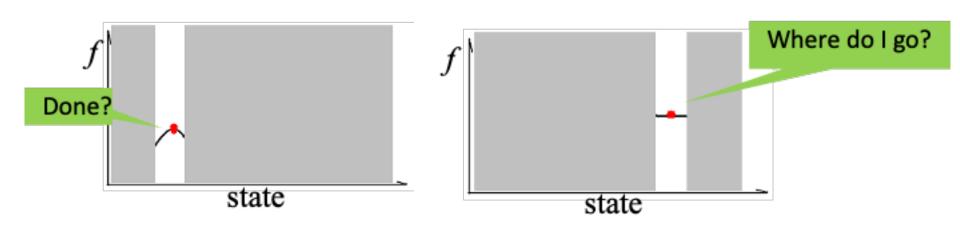
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Note the local optima. How do we handle them?



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Simple idea 2: reduce greed

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Simple idea 2: reduce greed

- "Stochastic" hill climbing: randomly select between neighbors.
- Probability of selecting a neighbor should be proportional to the value of that neighbor.

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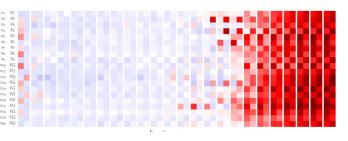
Often useful for harder problems

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Often useful for harder problems



- **Q 1.1**: Hill climbing and stochastic gradient descent are related by
- (i) Both head towards optima
- (ii) Both require computing a gradient
- (iii) Both will find the global optimum for a convex problem (problem where all optima have the same value).

- A. (i)
- B. (i), (ii)
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- A. (i)
- B. (i), (ii) (No: (ii) is false. Hill-climbing looks at neighbors only.)
- C. (i), (iii)
- D. All of the above

Q 2.2: Which of the following would be better to solve with hill climbing rather than A* search?

- i. Finding the smallest set of vertices in a graph that involve all edges
- ii. Finding the fastest way to schedule jobs with varying runtimes on machines with varying processing power
- iii. Finding the fastest way through a maze

- A. (i)
- B. (ii)
- C. (i) and (ii)
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- A. (i) (No, (ii) better: huge number of states, don't care about path)
- B. (ii) (No, (i) complete graph might have too many edges for A*)
- C. (i) and (ii)
- D. (ii) and (iii) (No, (iii) is good for A*: few successors, want path)

Genetic Algorithms

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Optimization approach based on nature

Survival of the fittest!

Genetic Algorithms

Optimization approach based on nature

• Survival of the fittest!



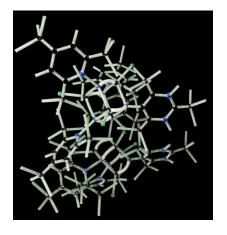
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A/C/T/G: nucleobases acting as symbols

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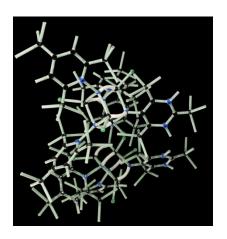
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Encode genetic information in DNA (four bases)

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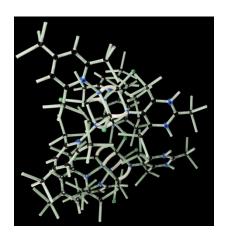
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A/C/T/G: nucleobases acting as symbols

- Two types of changes
 - Crossover: exchange between parents' codes

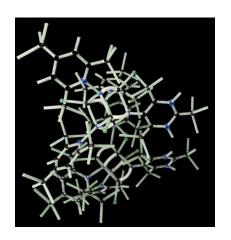


Evolution Review

Encode genetic information in DNA (four bases)

A/C/T/G: nucleobases acting as symbols

- Two types of changes
 - Crossover: exchange between parents' codes
 - Mutation: rarer random process

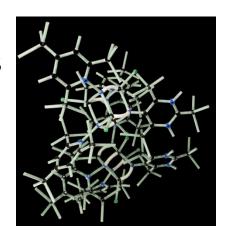


Evolution Review

Encode genetic information in DNA (four bases)

A/C/T/G: nucleobases acting as symbols

- Two types of changes
 - Crossover: exchange between parents' codes
 - Mutation: rarer random process
 - Happens at individual level



Competition for resources

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 Organisms with better fitness → better probability of reproducing

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- Repeated process: fit become larger proportion of population

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Goal: use these principles for optimization

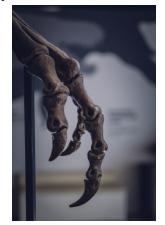


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— New terminology: state is 'individual'



Competition for resources

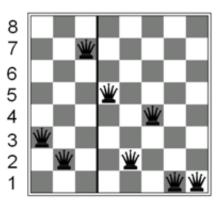
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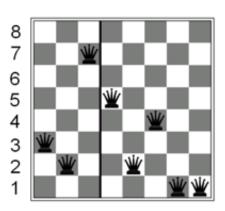
- New terminology: state is 'individual'
- Value f(s) is now the 'fitness'



Keep around a fixed number of states/individuals



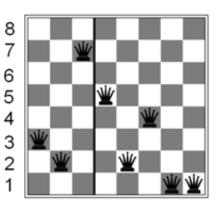
Keep around a fixed number of states/individuals





Keep around a fixed number of states/individuals

• Call this the **population**

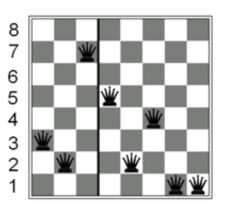




Keep around a fixed number of states/individuals

• Call this the **population**

For our n Queens game example, an individual:

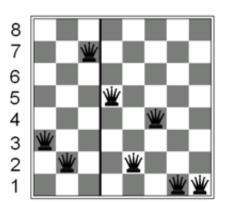




Keep around a fixed number of states/individuals

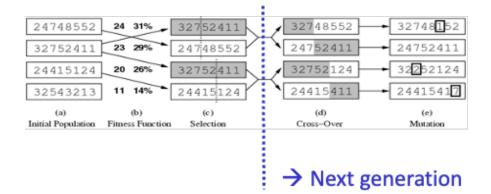
Call this the population

For our n Queens game example, an individual:



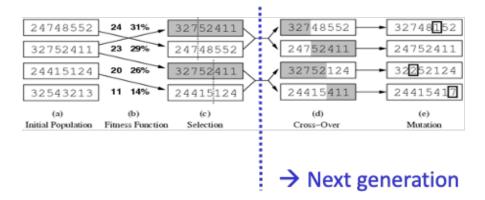
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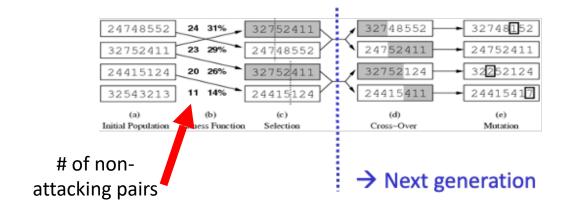
Goal of genetic algorithms: optimize using principles inspired by mechanism for evolution

Analogous to natural selection, cross-over, and mutation



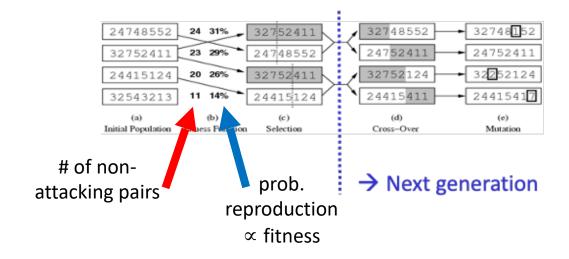
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Goal of genetic algorithms: optimize using principles inspired by mechanism for evolution

Analogous to natural selection, cross-over, and mutation



Genetic Algorithms Pseudocode

Just one variant:

- 1. Let $s_1, ..., s_N$ be the current population
- 2. Let $p_i = f(s_i) / \sum_i f(s_i)$ be the reproduction probability
- 3. for k = 1; k < N; k + = 2
 - parent1 = randomly pick according to p
 - parent2 = randomly pick another
 - randomly select a crossover point, swap strings of parents 1, 2 to generate children t[k], t[k+1]
- 4. for k = 1; k <= N; k++
 - Randomly mutate each position in t[k] with a small probability (mutation rate)
- 5. The new generation replaces the old: $\{s\} \leftarrow \{t\}$. Repeat

Reproduction probability: $p_i = f(s_i) / \sum_i f(s_i)$

Reproduction probability: $p_i = f(s_i) / \Sigma_i f(s_i)$

Individual	Fitness	Prob.	
Α	5	10%	
В	20	40%	
С	11	22%	
D	8	16%	
E	6	12%	

Reproduction probability: $p_i = f(s_i) / \Sigma_i f(s_i)$

• **Example**: $\Sigma_i f(s_i) = 5+20+11+8+6=50$

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Reproduction probability: $p_i = f(s_i) / \Sigma_i f(s_i)$

• **Example**: $\Sigma_i f(s_i) = 5+20+11+8+6=50$

•
$$p_1 = 5/50 = 10\%$$

Individual	Fitness	Prob.
Α	5	10%
В	20	40%
С	11	22%
D	8	16%
E	6	12%



Let's run through an example:

• 5 courses: A,B,C,D,E

- 5 courses: A,B,C,D,E
- 3 time slots: Mon/Wed, Tue/Thu, Fri/Sat

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Students
2
7
3
4
10
5

- 5 courses: A,B,C,D,E
- 3 time slots: Mon/Wed, Tue/Thu, Fri/Sat
- Students wish to enroll in three courses
- Goal: maximize student enrollment

Courses	Students
АВС	2
ABD	7
ADE	3
BCD	4
BDE	10
CDE	5

Courses	Students
АВС	2
ABD	7
ADE	3
BCD	4
BDE	10
CDE	5

Let's run through an example:

• State: course assignment to time slot

Courses	Students
АВС	2
ABD	7
ADE	3
BCD	4
BDE	10
CDE	5

Let's run through an example:

• State: course assignment to time slot

М	М	F	Т	М
Α	В	С	D	E

Courses	Students
АВС	2
ABD	7
ADE	3
BCD	4
BDE	10
CDE	5

Let's run through an example:

State: course assignment to time slot

М	М	F	Т	М
Α	В	С	D	E

= MMFTM

Courses	Students
АВС	2
ABD	7
ADE	3
BCD	4
BDE	10
CDE	5

Let's run through an example:

State: course assignment to time slot

М	М	F	Т	М
Α	В	С	D	E

Here:

Courses	Students
АВС	2
ABD	7
ADE	3
BCD	4
BDE	10
CDE	5

Let's run through an example:

State: course assignment to time slot

М	М	F	Т	М
Α	В	С	D	E

- Here:
 - Courses A, B, E scheduled Mon/Wed

Courses	Students
АВС	2
ABD	7
ADE	3
BCD	4
BDE	10
CDE	5

Let's run through an example:

• State: course assignment to time slot

М	М	F	Т	М
Α	В	С	D	E

- Here:
 - Courses A, B, E scheduled Mon/Wed
 - Course D scheduled Tue/Thu

Courses	Students
АВС	2
ABD	7
ADE	3
BCD	4
BDE	10
CDE	5

Let's run through an example:

• State: course assignment to time slot

М	М	F	Т	М
Α	В	С	D	E

- Here:
 - Courses A, B, E scheduled Mon/Wed
 - Course D scheduled Tue/Thu
 - Course C scheduled Fri/Sat

Courses	Students
АВС	2
ABD	7
ADE	3
BCD	4
BDE	10
CDE	5

Courses	Students	Can enroll?
АВС	2	No
ABD	7	No
ADE	3	No
BCD	4	Yes
BDE	10	No
CDE	5	Yes

Value of a state? Say MMFTM

Courses	Students	Can enroll?
АВС	2	No
ABD	7	No
ADE	3	No
BCD	4	Yes
BDE	10	No
CDE	5	Yes

Here 4+5=9 students can enroll in desired courses

First step:

Courses	Students
АВС	2
ABD	7
ADE	3
BCD	4
BDE	10
CDE	5

First step:

Randomly initialize and evaluate states

Courses	Students
АВС	2
ABD	7
ADE	3
BCD	4
BDE	10
CDE	5

First step:

Randomly initialize and evaluate states

MMFTM = 9

TTFMM = 4

FMTTF = 19

MTTTF = 3

Courses	Students
АВС	2
ABD	7
ADE	3
BCD	4
B D E	10
CDE	5

First step:

Randomly initialize and evaluate states

MMFTM = 9

TTFMM = 4

FMTTF = 19

MTTTF = 3

Calculate reproduction probabilities

Courses	Students
АВС	2
ABD	7
ADE	3
BCD	4
BDE	10
CDE	5
A B D A D E B C D B D E	7 3 4 10

First step:

Randomly initialize and evaluate states

MMFTM = 9	MMFTM = 26%
TTFMM = 4	TTFMM = 11%
FMTTF = 19	FMTTF = 54 %
MTTTF = 3	MTTTF = 9%

Calculate reproduction probabilities

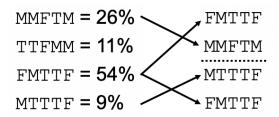
Students
2
7
3
4
10
5

Next steps:

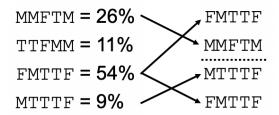
Select parents using reproduction probabilities

Next steps:

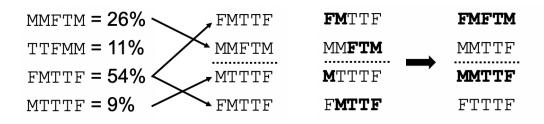
Select parents using reproduction probabilities



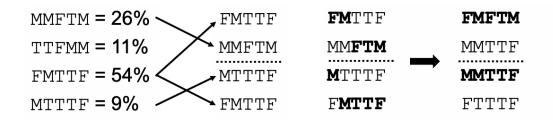
- Select parents using reproduction probabilities
- Perform crossover



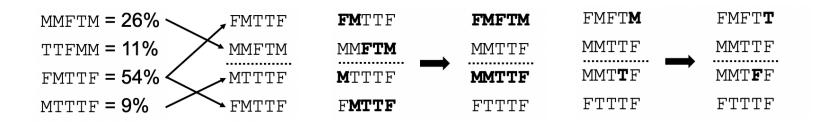
- Select parents using reproduction probabilities
- Perform crossover



- Select parents using reproduction probabilities
- Perform crossover
- Randomly mutate new children



- Select parents using reproduction probabilities
- Perform crossover
- Randomly mutate new children



Continue:

Courses	Students
АВС	2
ABD	7
ADE	3
BCD	4
BDE	10
CDE	5

Continue:

Now, get our function values for updated population

Courses	Students
АВС	2
ABD	7
ADE	3
BCD	4
BDE	10
CDE	5

Continue:

Now, get our function values for updated population

	N /Т Т.	т	¬ _	1	1
Γ.	ΓΛΤΓ	$\Gamma T'$. –	Τ	Τ

$$MMTTF = 13$$

$$MMTFF = 4$$

$$FTTTF = 0$$

Courses	Students
АВС	2
ABD	7
ADE	3
B C D	4
BDE	10
CDE	5

Continue:

- Now, get our function values for updated population
- Calculate reproduction probabilities

$$FMFTT = 11$$

$$MMTTF = 13$$

$$MMTFF = 4$$

$$FTTTF = 0$$

Courses	Students
АВС	2
ABD	7
ADE	3
BCD	4
B D E	10
CDE	5

Continue:

- Now, get our function values for updated population
- Calculate reproduction probabilities

FMFTT = 11	FMFTT = 39%
MMTTF = 13	MMTTF = 46 %
MMTFF = 4	MMTFF = 14%
FTTTF = 0	FTTTF = 0%

	_
Courses	Students
АВС	2
ABD	7
ADE	3
B C D	4
B D E	10
CDE	5

Many possibilities:



Many possibilities:

Parents survive to next generation



Many possibilities:

- Parents survive to next generation
- Use ranking instead of exact value of f(s) for reproduction probabilities (reduce influence of extreme f values)



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Some challenges

- Formulating a good state encoding
- Lack of diversity: converge too soon



Many possibilities:

- Parents survive to next generation
- Use ranking instead of exact value of f(s) for reproduction probabilities (reduce influence of extreme f values)

Some challenges

- Formulating a good state encoding
- Lack of diversity: converge too soon
- Must pick a lot of parameters



Summary

- Challenging optimization problems
 - First, try hill climbing. Simplest solution
- Genetic algorithms
 - Biology-inspired optimization routine