



CS 760: Machine Learning **Neural Networks II**

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February 27, 2023

Logistics

- **Announcements:**
 - HW 3 was due today
 - HW 4 will be out soon
- **Midterm**
 - 90 minutes
 - Cheat sheet: one sheet of paper (no larger than Legal size), both sides, printed or hand-written
 - Will cover material up to next Monday's class.
 - Email me about alternative dates by tonight.

Outline

- **Neural Networks**

- Introduction, Setup, Components, Activations

- **Training Neural Networks**

- SGD, Computing Gradients, Backpropagation

- **Regularization**

- Views, Data Augmentation, Other approaches

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Multilayer Neural Network

- Input: two features from spectral analysis of a spoken sound
- Output: vowel sound occurring in the context “h d”

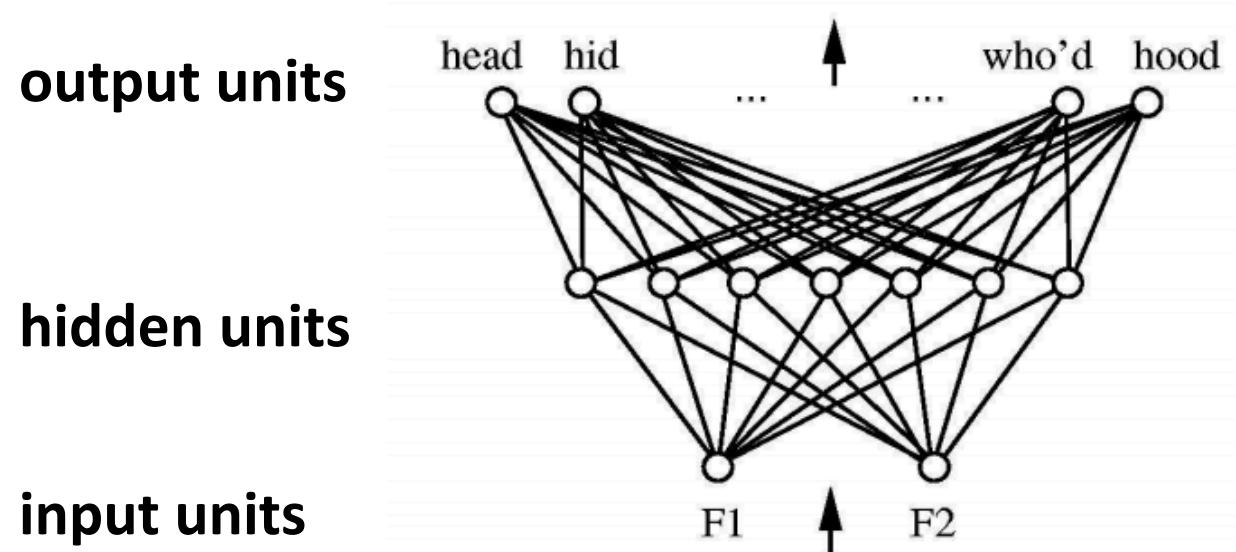


figure from Huang & Lippmann, NIPS 1988

Neural Network Decision Regions

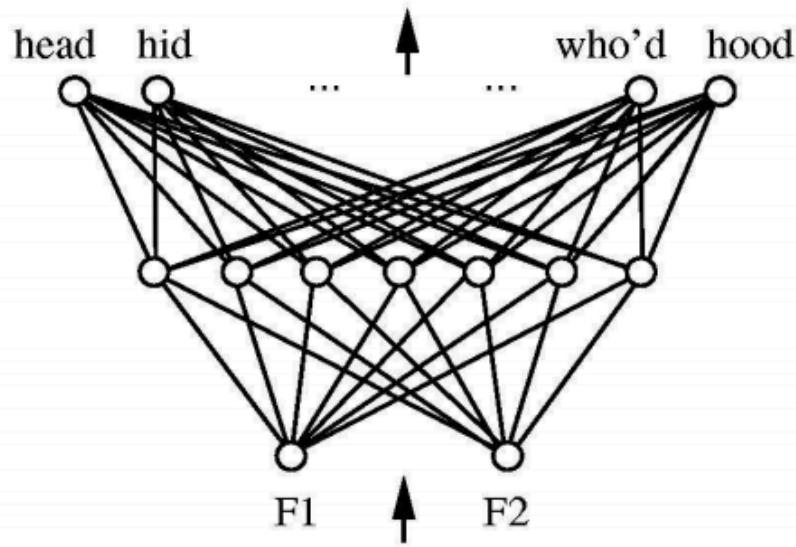
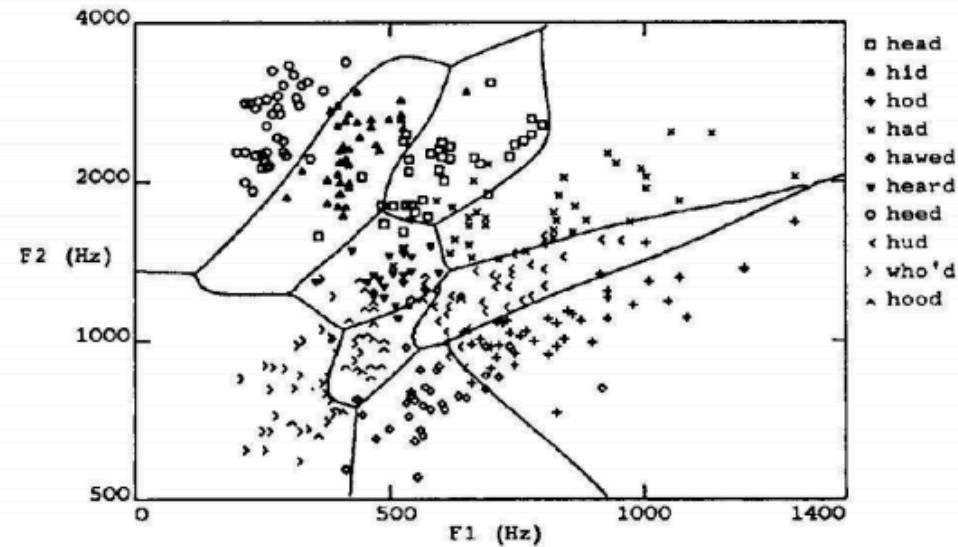
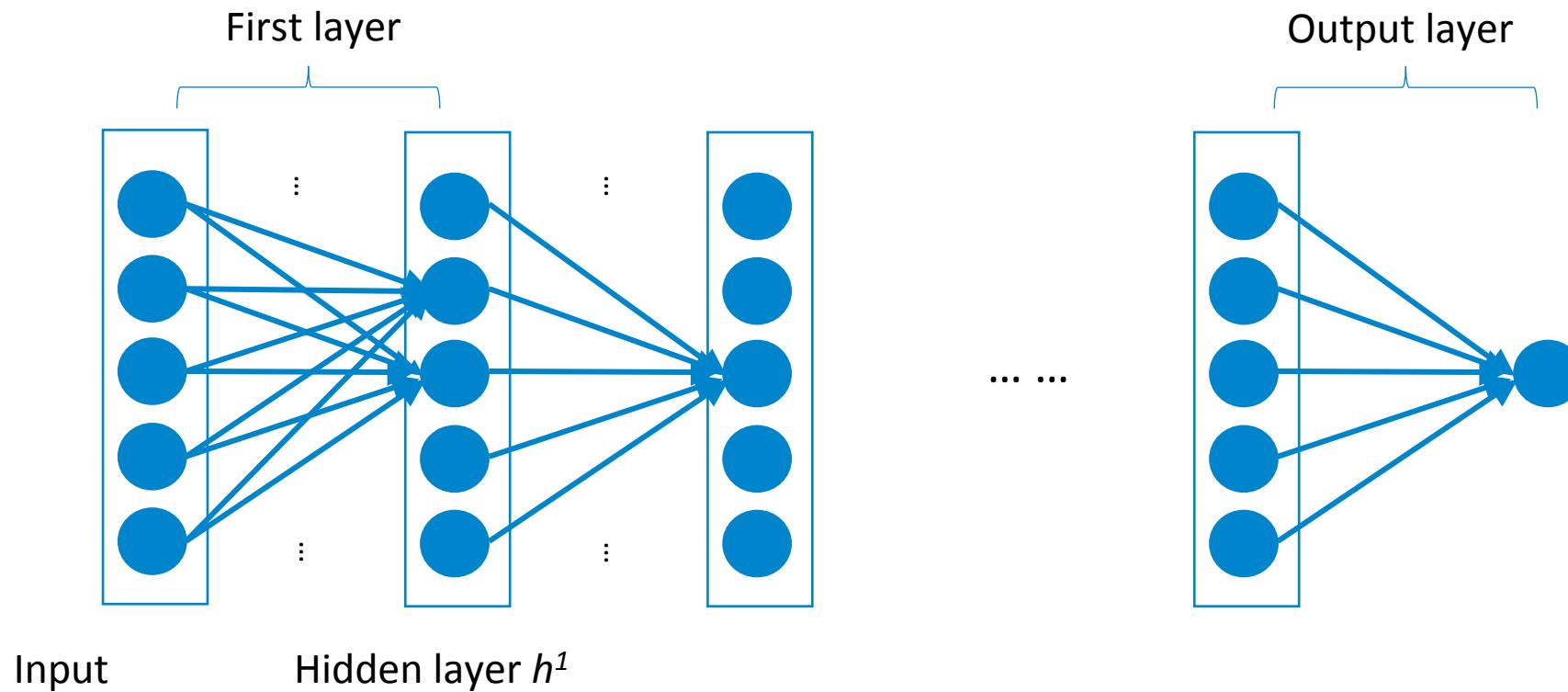


Figure from Huang & Lippmann, NIPS 1988



Neural Network Components

An $(L+1)$ -layer network



Feature Encoding for NNs

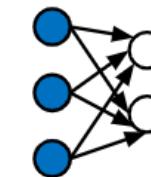
- Nominal features usually a one hot encoding

$$A = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad C = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} \quad G = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} \quad T = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$



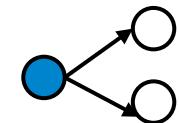
- Ordinal features: use a *thermometer* encoding

$$\text{small} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad \text{medium} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \quad \text{large} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$



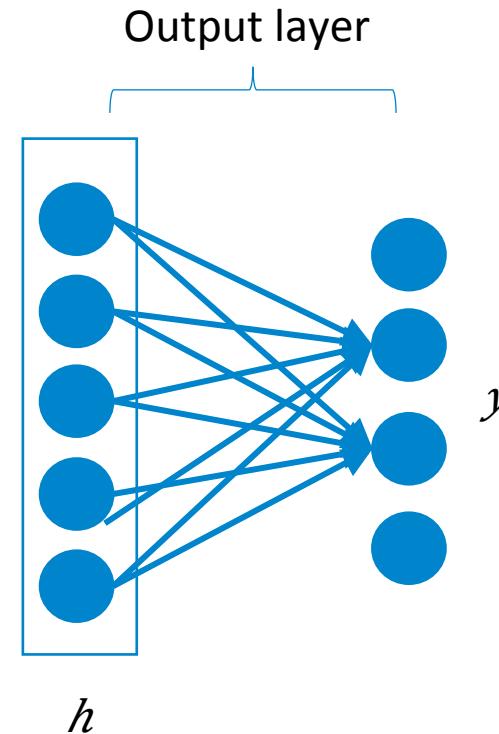
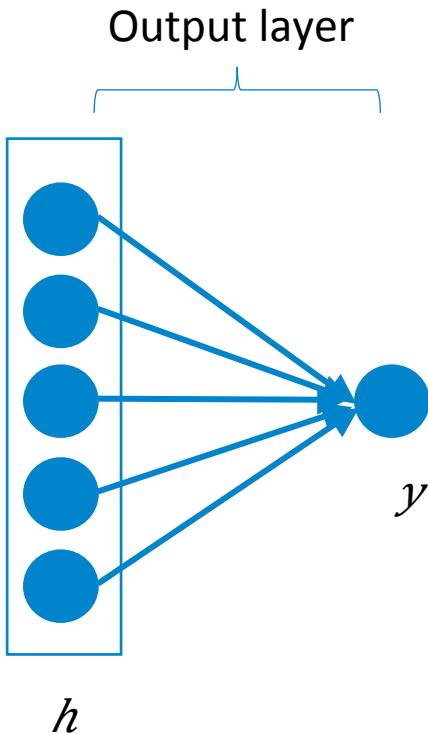
- Real-valued features use individual input units (may want to scale/normalize them first though)

$$\text{precipitation} = [0.68]$$



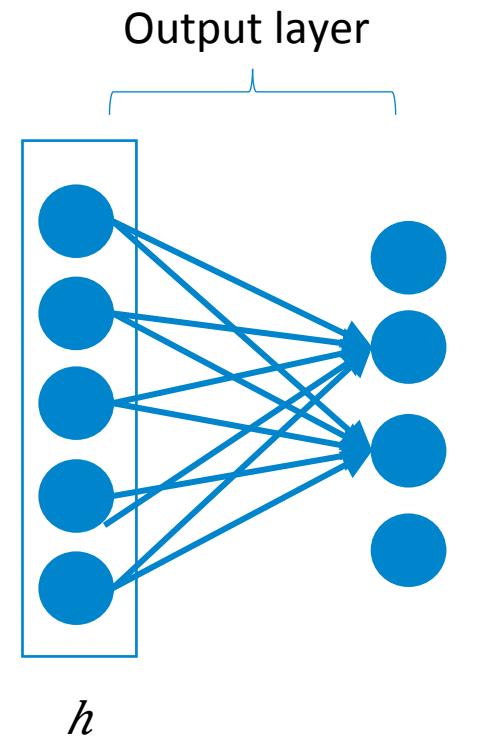
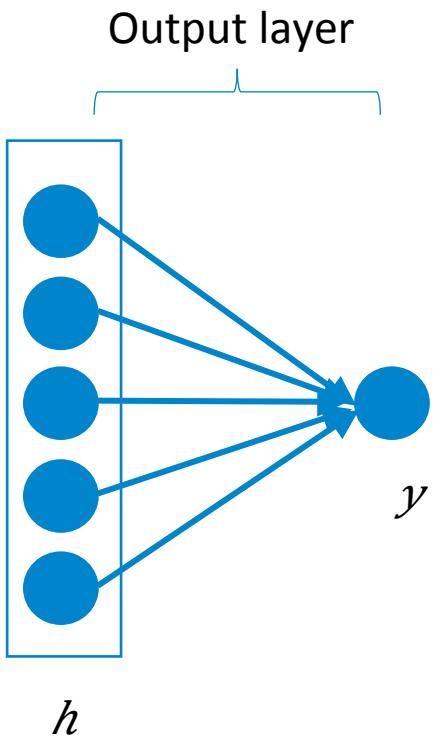
Output Layer: Examples

- Regression: $y = w^\top h + b$
 - Linear units: no nonlinearity
- Multi-dimensional regression: $Y = W^\top h + b$
 - Linear units: no nonlinearity



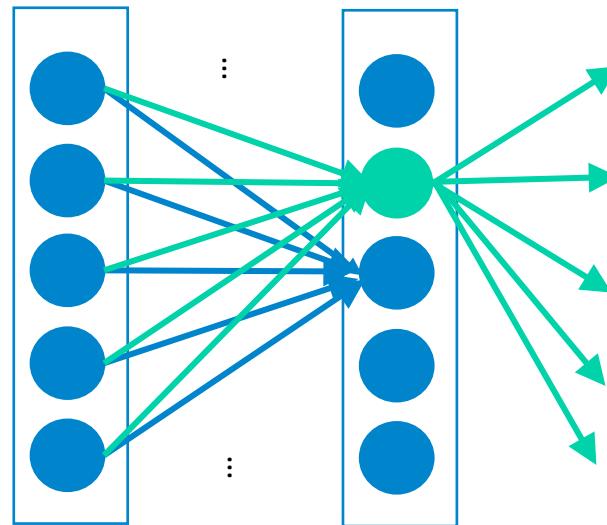
Output Layer: Examples

- Binary classification: $y = \text{sigmoid}(w^\top h + b)$
 - Corresponds to using logistic regression on
- Multiclass classification: $Y = \text{sigmoid}(W^\top h + b)$



Hidden Layers

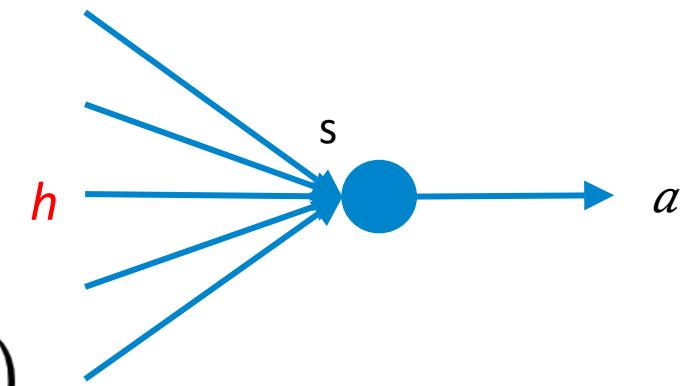
- Neuron takes weighted linear combination of the previous representation layer
 - Outputs one value for the next layer



Hidden Layers

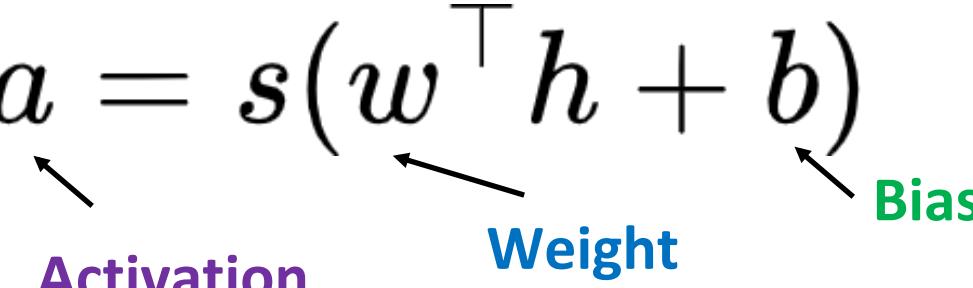
- Outputs $a = s(w^\top h + b)$

- Typical activation function
 - Threshold: $s(z) = 1(z \geq 0)$
 - Sigmoid: $s(z) = \sigma(z) = 1/(1 + e^{-z})$
 - Tanh: $s(z) = 2\sigma(2z) - 1$

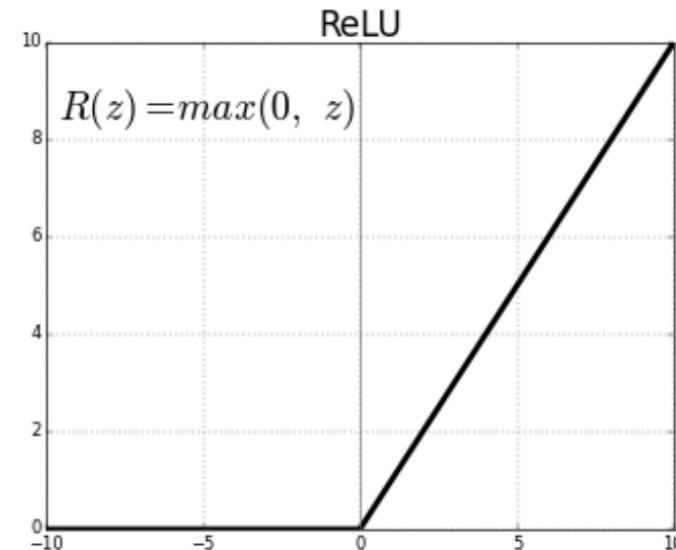
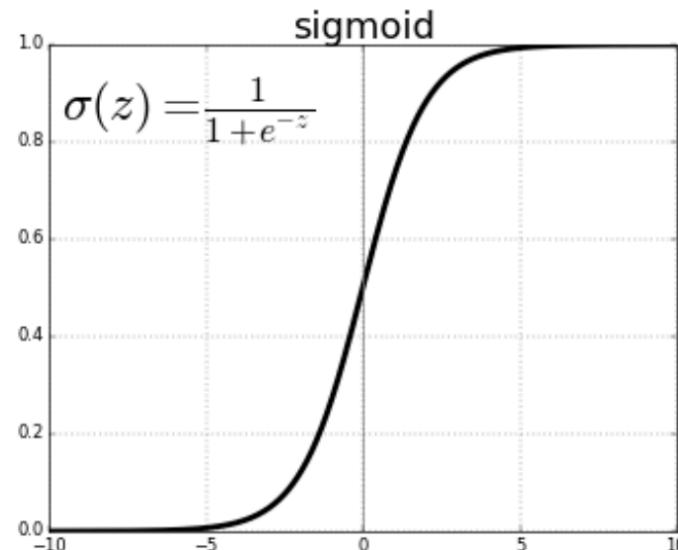


- Why not **linear activation** functions?
 - Model would be linear.

More on Activations

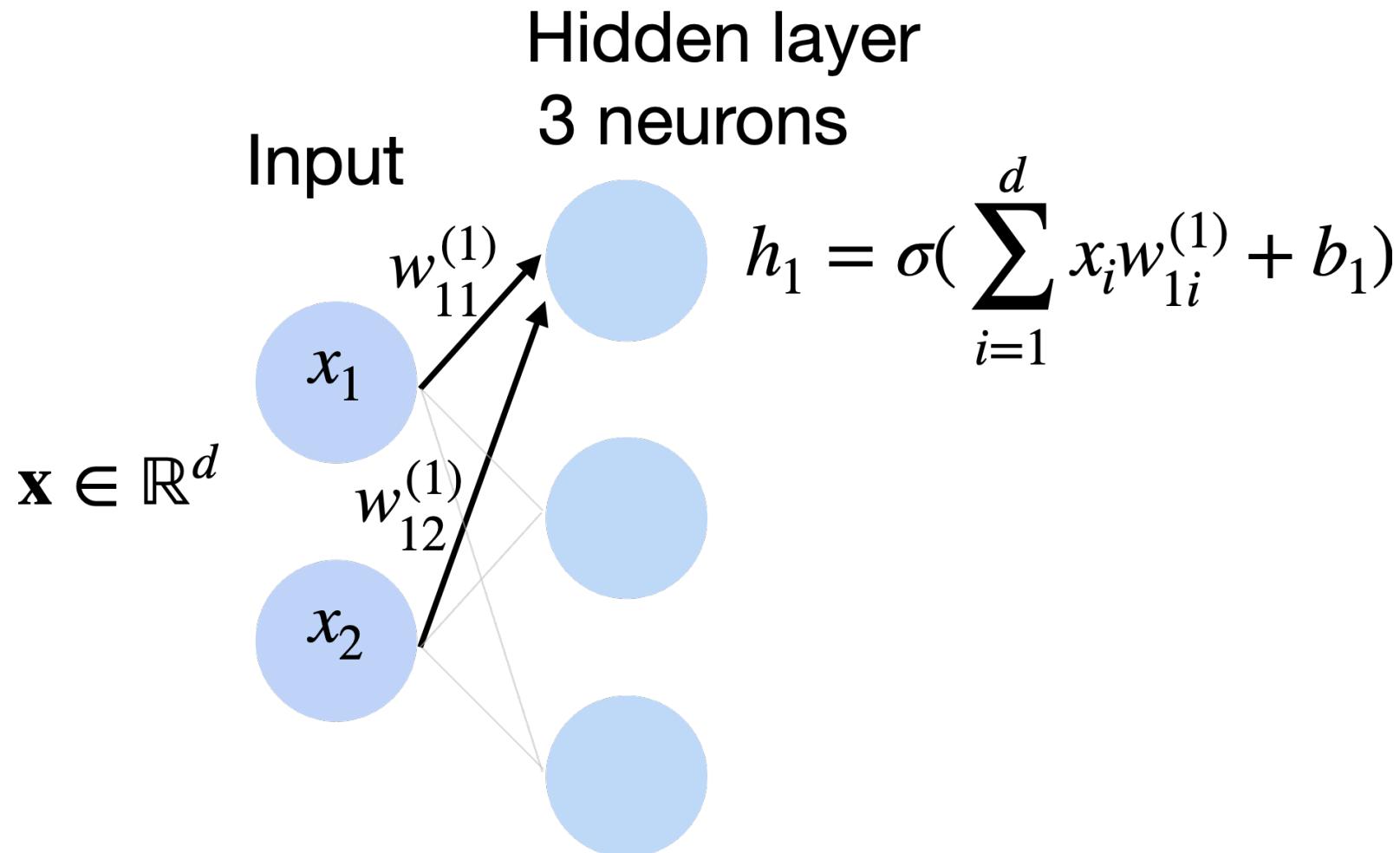
- Outputs $a = s(w^\top h + b)$


- Consider gradients... saturating vs. nonsaturating



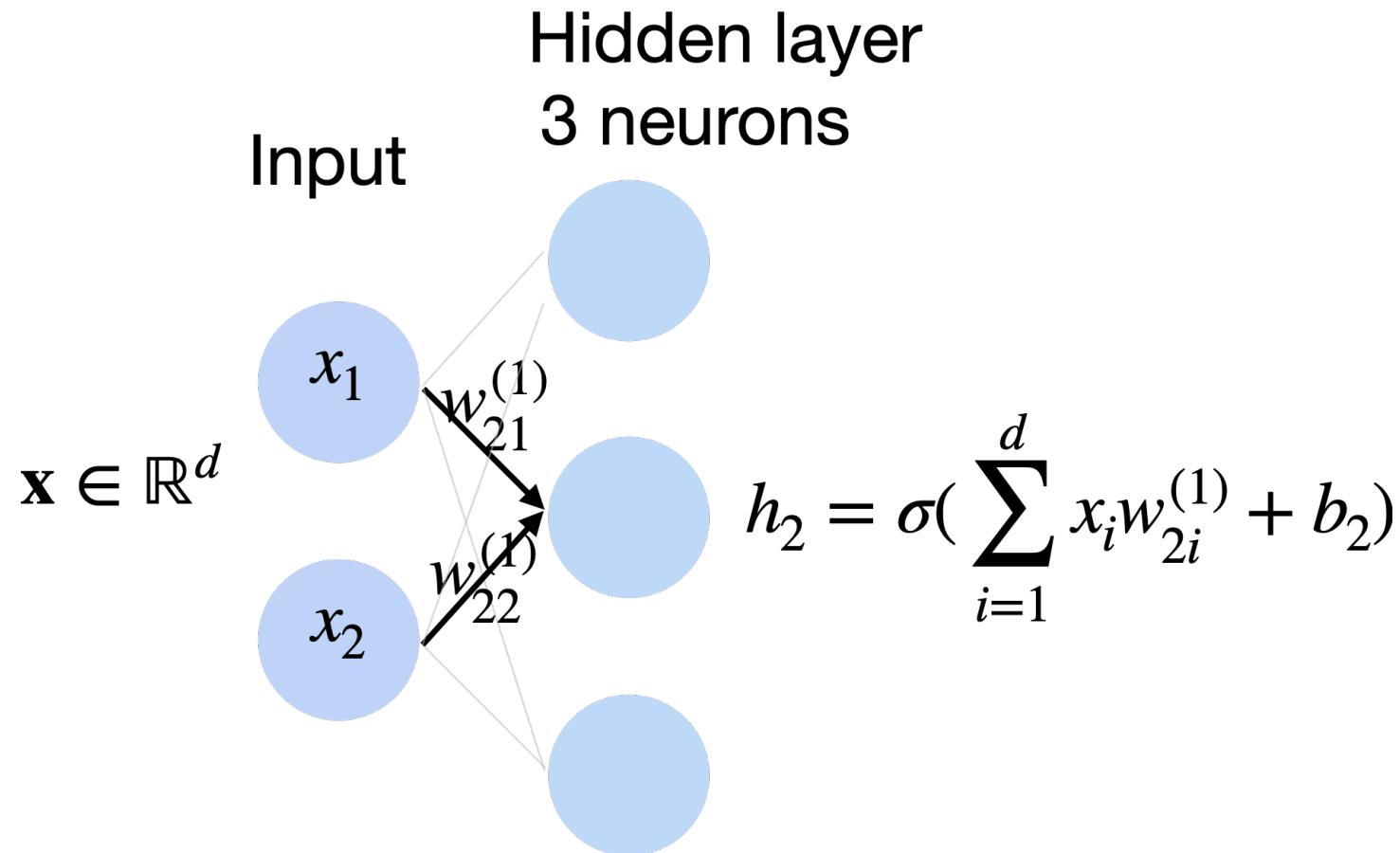
MLPs: Multilayer Perceptron

- Ex: 1 hidden layer, 1 output layer: depth 2



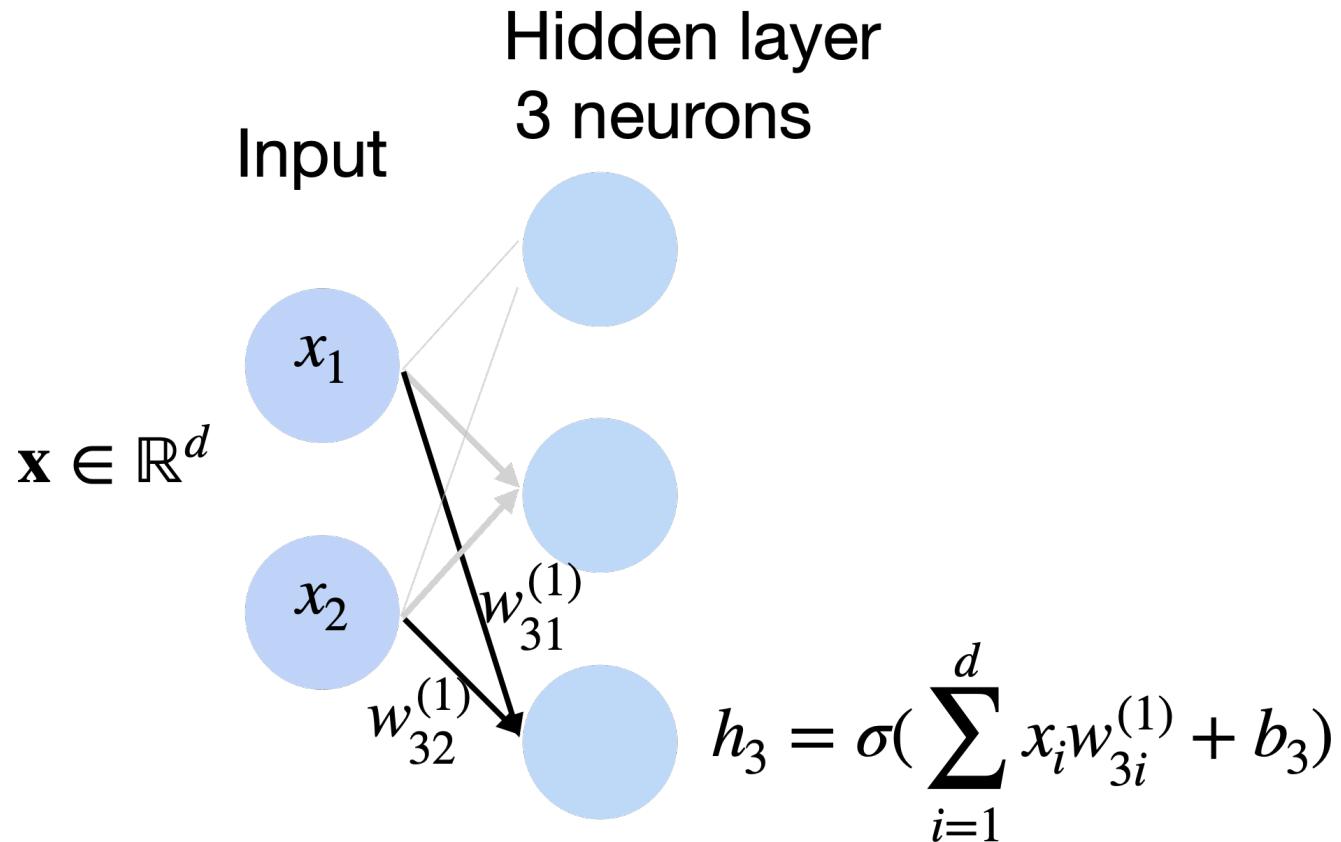
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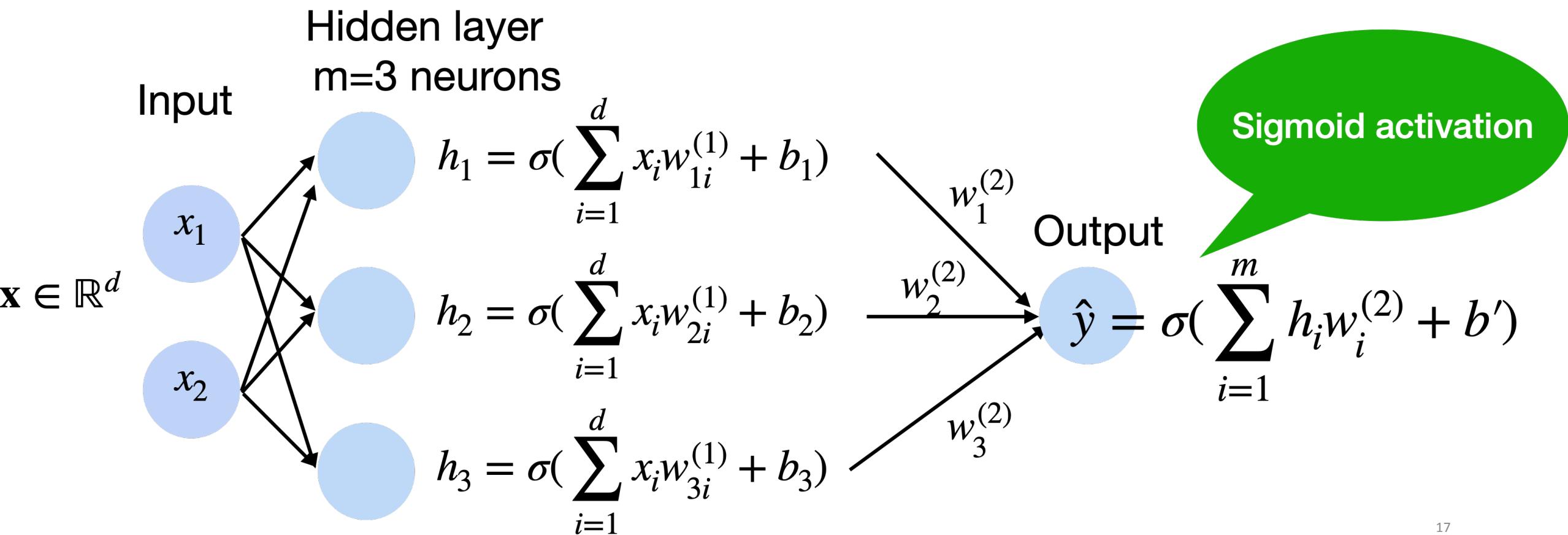
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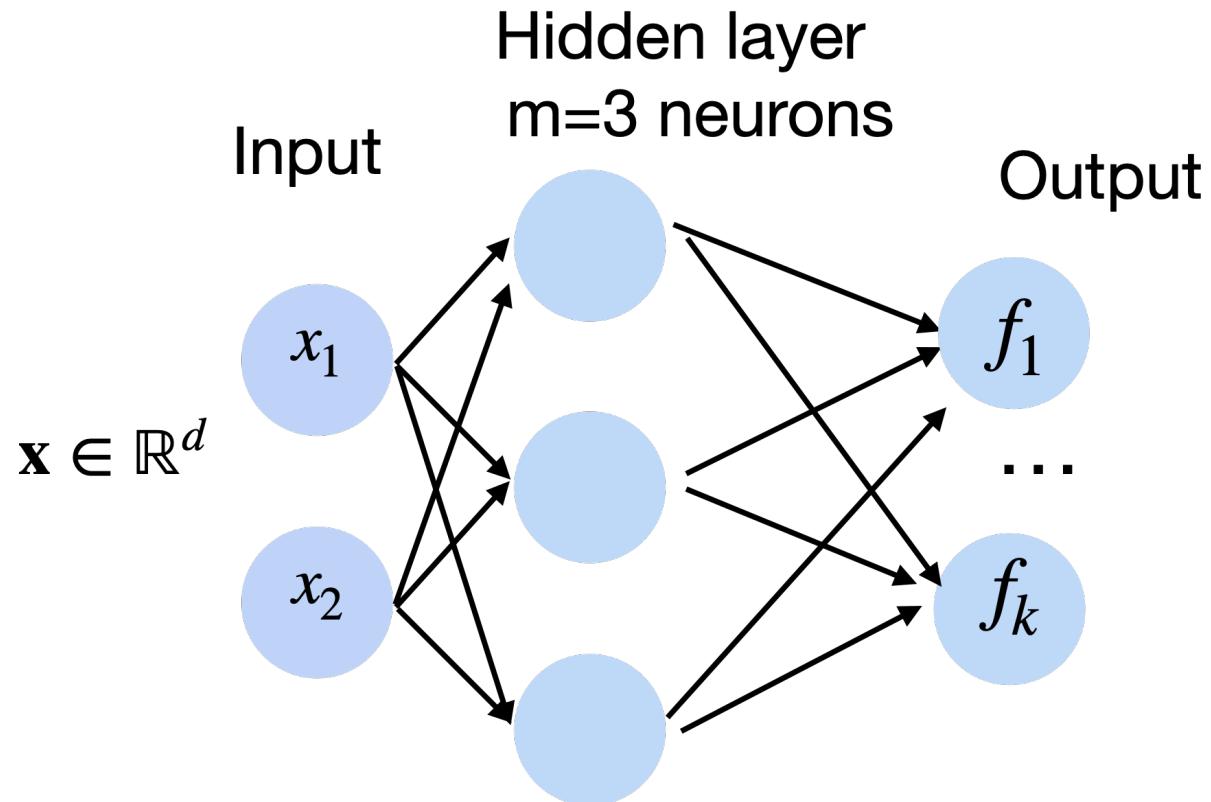
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Multiclass Classification Output

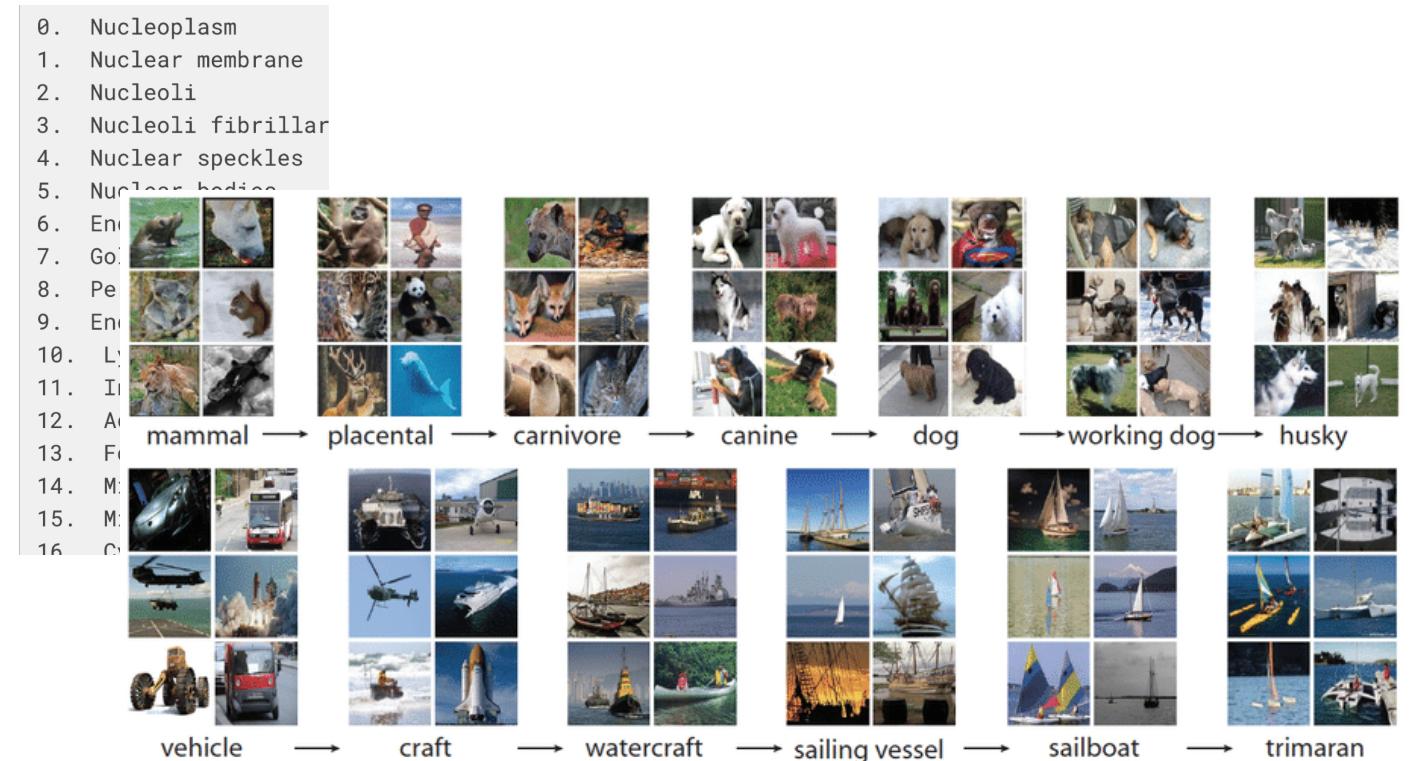
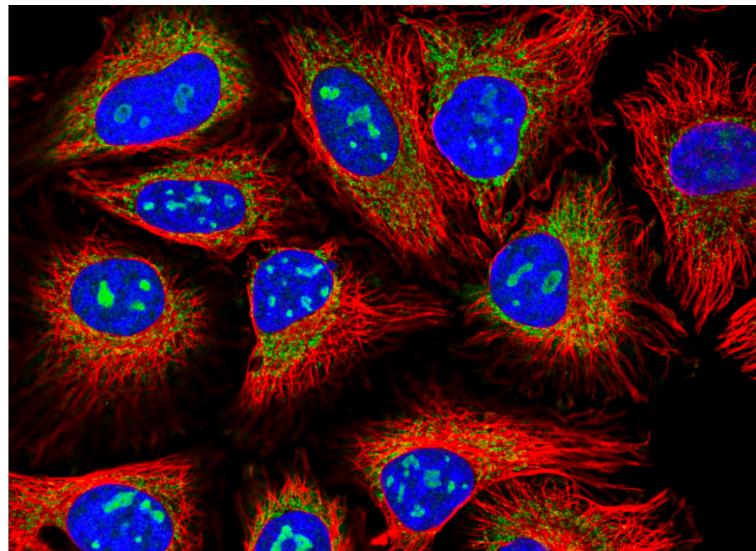
- Create k output units
- Use softmax (just like logistic regression)



$$\begin{aligned} p(y | \mathbf{x}) &= \text{softmax}(f) \\ &= \frac{\exp f_y(\mathbf{x})}{\sum_i^k \exp f_i(\mathbf{x})} \end{aligned}$$

Multiclass Classification Examples

- Protein classification (Kaggle challenge)
- ImageNet





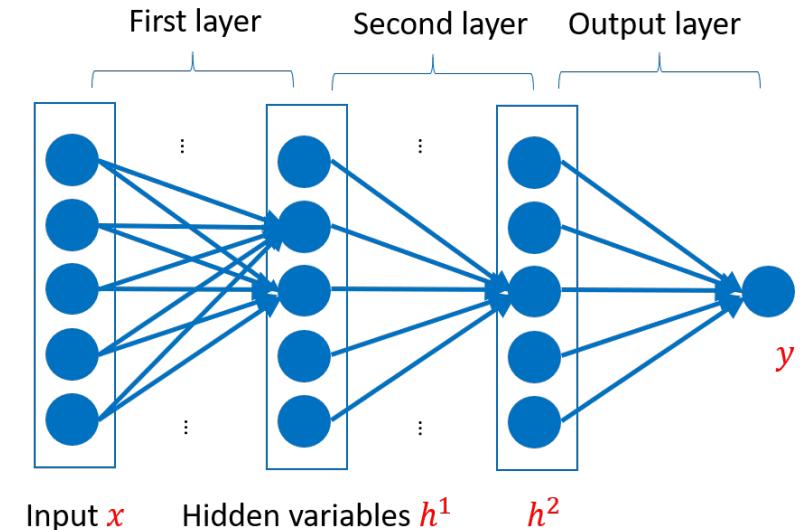
Break & Quiz

Q: Select the correct option.

- A. *The more hidden-layer units a Neural Network has, the better it can predict desired outputs for new inputs that it was not trained with.*
 - B. *A 3-layers Neural Network with 5 neurons in the input and hidden representations and 1 neuron in the output has a total of 55 connections.*
-
- 1. Both statements are true.
 - 2. Both statements are false.
 - 3. Statement A is true, Statement B is false.
 - 4. Statement B is true, Statement A is false.

Q: Select the correct option.

- A. *The more hidden-layer units a Neural Network has, the better it can predict desired outputs for new inputs that it was not trained with.*
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- **Training Neural Networks**
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 - Views, Data Augmentation, Other approaches

Training Neural Networks

- Training the usual way. Pick a loss and optimize
- **Example:** 2 scalar weights

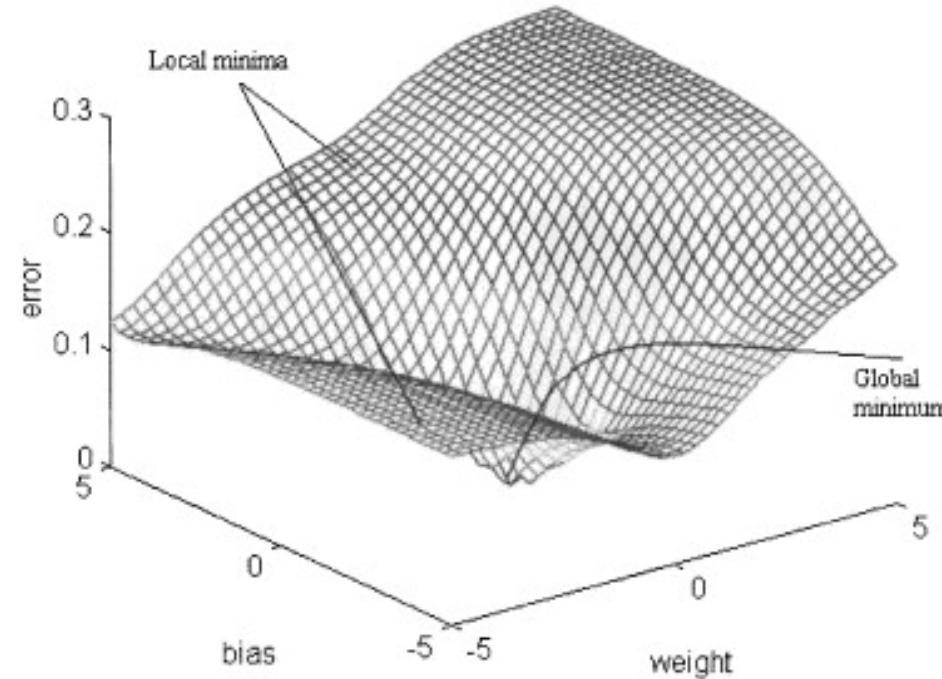


figure from Cho & Chow, *Neurocomputing* 1999

Training Neural Networks: SGD

- Algorithm:

- Get

$$D = \{(x^{(1)}, y^{(1)}), \dots, (x^{(n)}, y^{(n)})\}$$

- Initialize weights

- Until stopping criteria met,

- Sample training point. $(x^{(i)}, y^{(i)})$ without replacement

- Compute: $f_{\text{network}}(x^{(i)})$ ← Forward Pass

- Compute gradient: $\nabla L^{(i)}(w) = \left[\frac{\partial L^{(d)}}{\partial w_0}, \frac{\partial L^{(d)}}{\partial w_1}, \dots, \frac{\partial L^{(d)}}{\partial w_m} \right]^T$ ← Backward Pass

- Update weights: $w \leftarrow w - \alpha \nabla L^{(i)}(w)$

Training Neural Networks: Minibatch SGD

- Algorithm:
 - Get $D = \{(x^{(1)}, y^{(1)}), \dots, (x^{(n)}, y^{(n)})\}$
 - Initialize weights
 - Until stopping criteria met,
 - Sample b points j_1, j_2, \dots, j_b
 - Compute: $f_{\text{network}}(x^{(j_1)}), \dots, f_{\text{network}}(x^{(j_b)})$ ← **Forward Pass**
 - Compute gradients: $\nabla L^{(j_1)}(w), \dots, \nabla L^{(j_b)}(w)$ ← **Backward Pass**
 - Update weights:
- $$w \leftarrow w - \frac{\alpha}{b} \sum_{k=1}^b \nabla L^{(j_k)}(w)$$

Training Neural Networks: Chain Rule

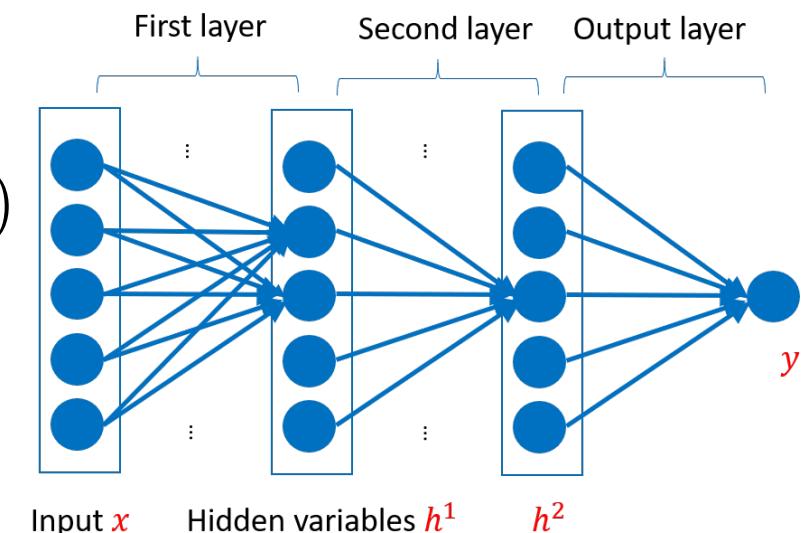
- Will need to compute terms like: $\frac{\partial L}{\partial w_1}$
- But, L is a composition of:
 - Loss with output y
 - Output itself a composition of softmax with outer layer
 - Outer layer a combination of outputs from previous layer
 - Outputs from prev. layer a composition of activations and linear functions...

- Need the **chain rule!**

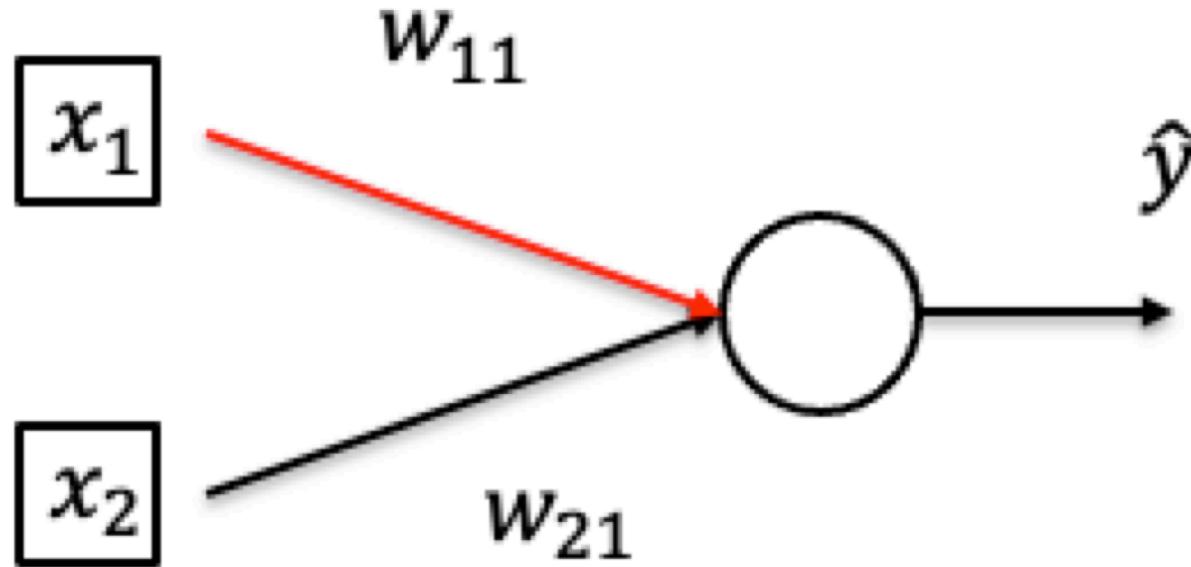
- Suppose $L = L(g_1, \dots, g_k)$ $g_j = g_j(w_1, \dots, w_p)$

- Then,

$$\frac{\partial L}{\partial w_i} = \sum_{j=1}^k \frac{\partial L}{\partial g_j} \frac{\partial g_j}{\partial w_i}$$

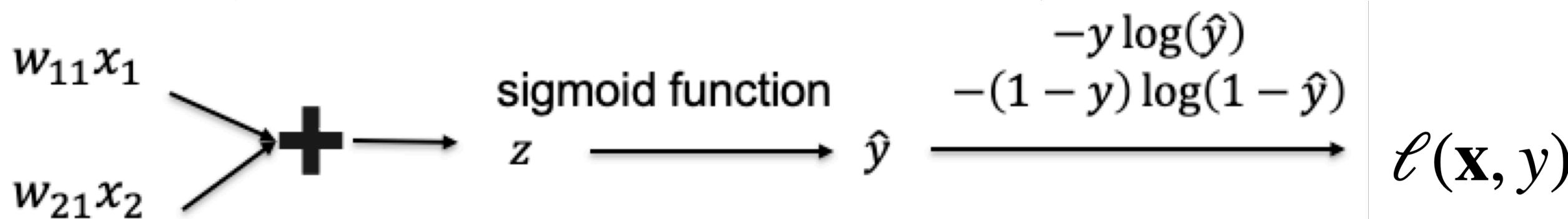
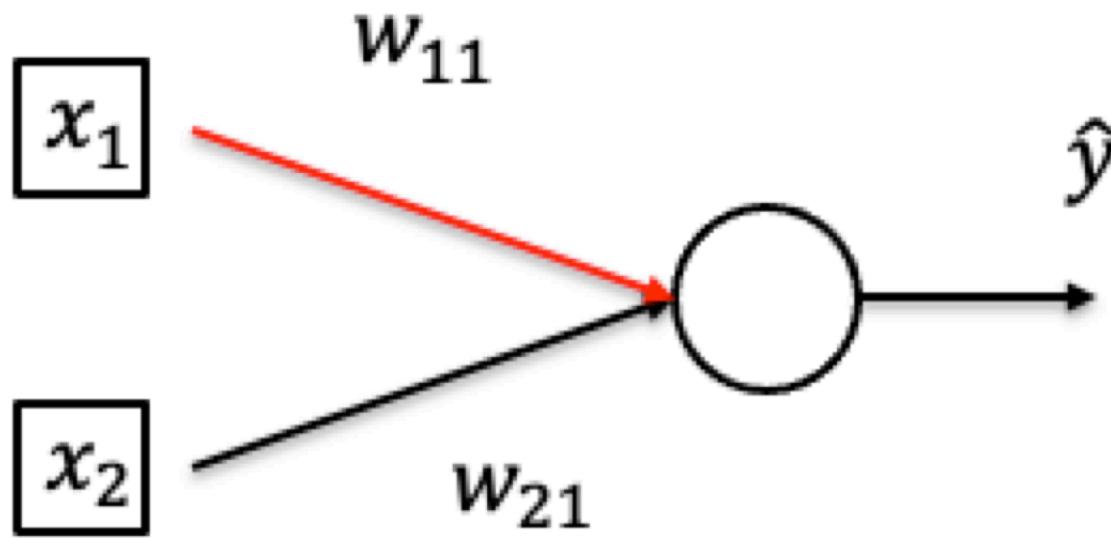


Computing Gradients

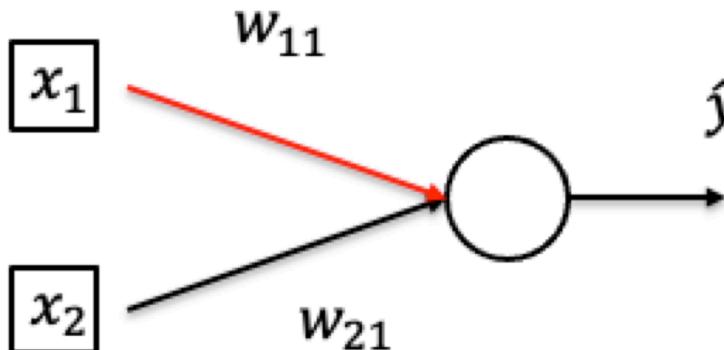


- Want to compute $\frac{\partial \ell(\mathbf{x}, y)}{\partial w_{11}}$

Computing Gradients



Computing Gradients

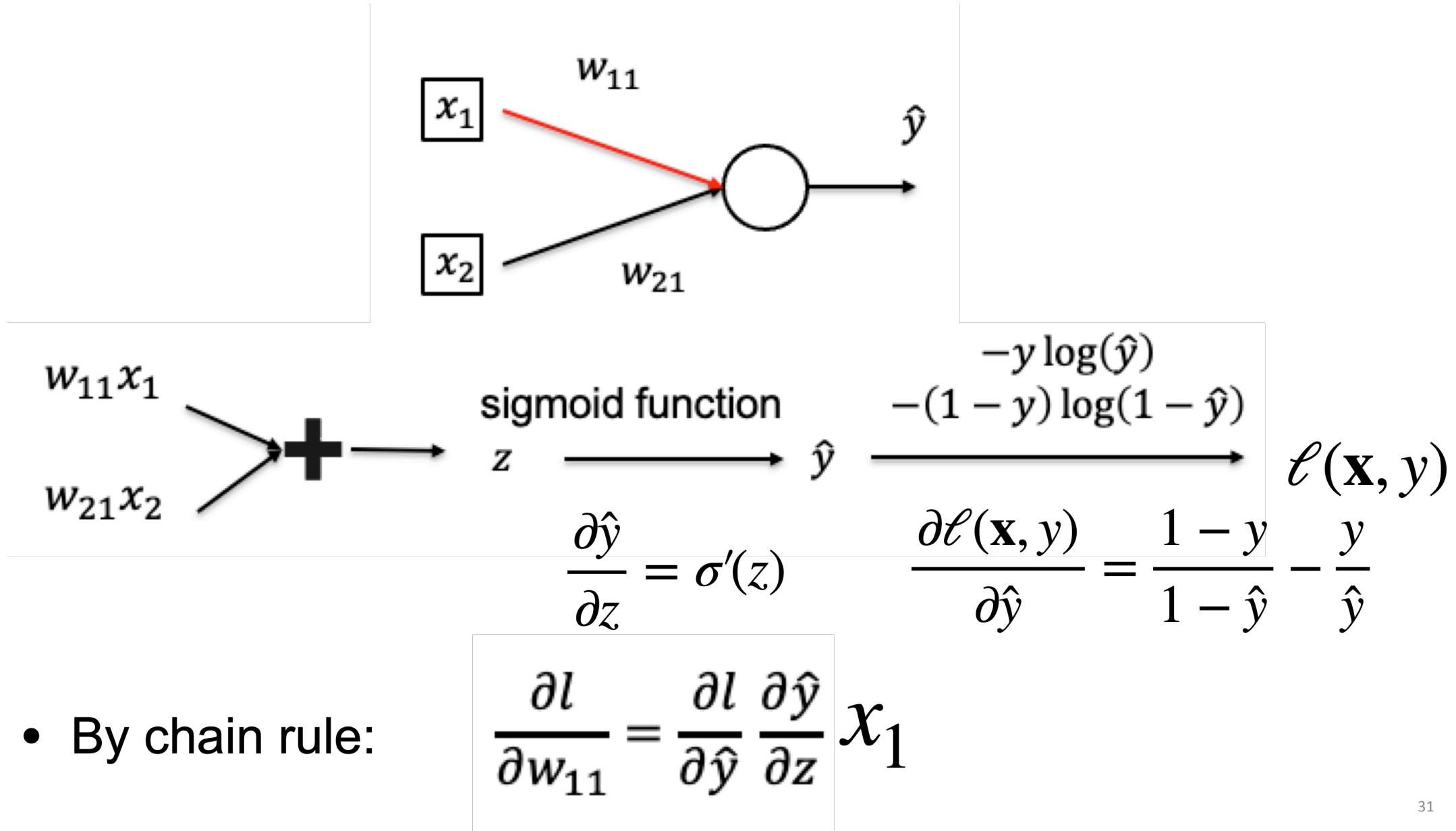


$$\begin{array}{c} w_{11}x_1 \\ w_{21}x_2 \end{array} \rightarrow \begin{array}{c} + \\ \text{sigmoid function} \end{array} \rightarrow z \rightarrow \hat{y} \rightarrow \ell(\mathbf{x}, y)$$
$$\frac{\partial \hat{y}}{\partial z} = \sigma'(z) \quad \frac{\partial \ell(\mathbf{x}, y)}{\partial \hat{y}} = \frac{-y \log(\hat{y})}{-(1 - y) \log(1 - \hat{y})}$$
$$\frac{\partial \ell(\mathbf{x}, y)}{\partial z} = \frac{\partial \ell(\mathbf{x}, y)}{\partial \hat{y}} \cdot \frac{\partial \hat{y}}{\partial z} = \frac{1 - y}{1 - \hat{y}} - \frac{y}{\hat{y}}$$

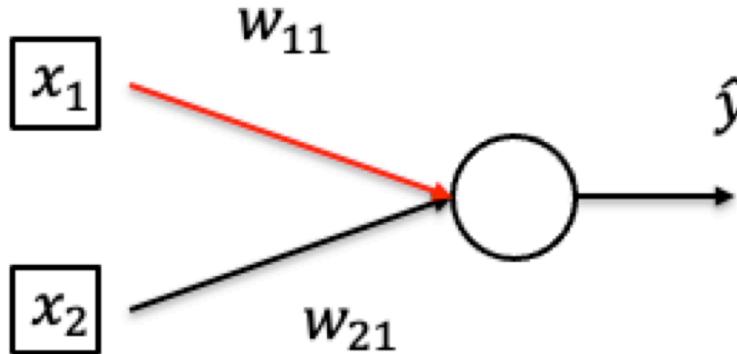
- By chain rule:

$$\frac{\partial l}{\partial w_{11}} = \frac{\partial l}{\partial \hat{y}} \frac{\partial \hat{y}}{\partial z} \frac{\partial z}{\partial w_{11}}$$

Computing Gradients



Computing Gradients

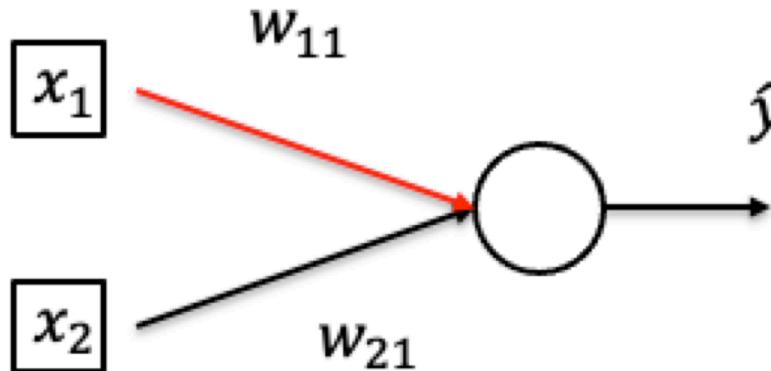


A computational graph illustrating the forward pass of a neural network. It starts with two inputs, $w_{11}x_1$ and $w_{21}x_2$, which are summed at a large black plus sign. The result is passed through a sigmoid function, labeled $\sigma(z)$, to produce the output \hat{y} . Finally, the output \hat{y} is passed through a loss function, labeled $-(y \log(\hat{y}) + (1 - y) \log(1 - \hat{y}))$, to produce the final result $\ell(\mathbf{x}, y)$. Below the graph, the derivative of the sigmoid function is given as $\frac{\partial \hat{y}}{\partial z} = \sigma'(z) = \sigma(z)(1 - \sigma(z))$.

- By chain rule:

$$\frac{\partial l}{\partial w_{11}} = \frac{\partial l}{\partial \hat{y}} \hat{y}(1 - \hat{y})x_1$$

Computing Gradients



The diagram illustrates the computation of gradients for a sigmoid function. It shows the forward pass and the backward pass (gradient flow) through the sigmoid function and the loss function.

Forward pass:

- Inputs: $w_{11}x_1$ and $w_{21}x_2$ are summed at a black plus sign node.
- The result z is passed through a "sigmoid function" to produce the output \hat{y} .
- The output \hat{y} is then passed through a linear function to produce the loss $\ell(\mathbf{x}, y)$.

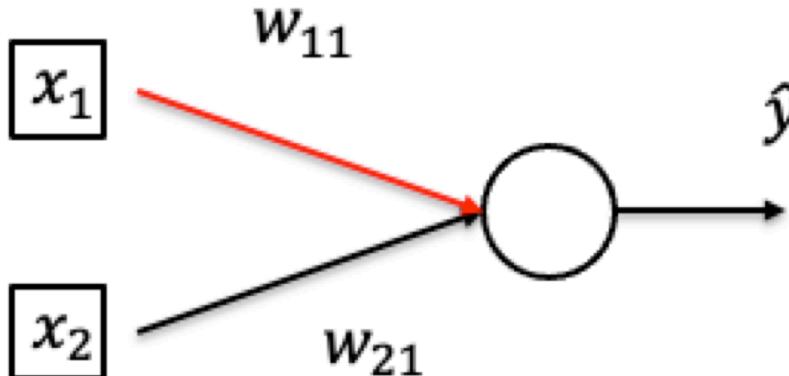
Backward pass (gradients):

- The gradient of the loss with respect to \hat{y} is given as $\frac{-y \log(\hat{y})}{-(1 - y) \log(1 - \hat{y})}$.
- The gradient of the sigmoid function with respect to z is given as $\frac{\partial \hat{y}}{\partial z} = \sigma'(z) = \sigma(z)(1 - \sigma(z))$.

- By chain rule:

$$\frac{\partial l}{\partial w_{11}} = \left(\frac{1 - y}{1 - \hat{y}} - \frac{y}{\hat{y}} \right) \hat{y}(1 - \hat{y})x_1$$

Computing Gradients



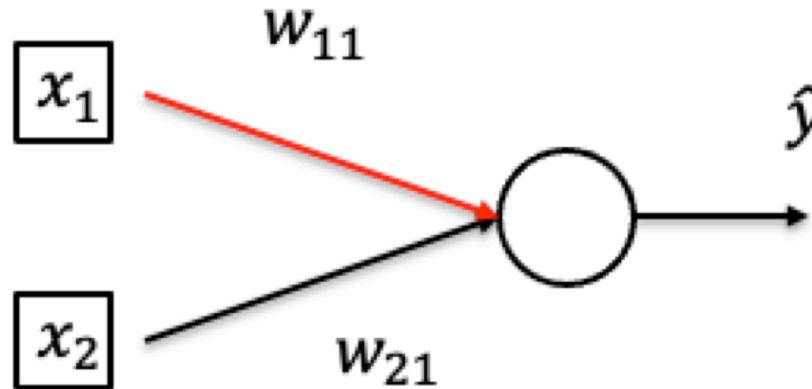
$$\begin{array}{c} w_{11}x_1 \\ w_{21}x_2 \end{array} \rightarrow \text{+} \rightarrow z \xrightarrow{\text{sigmoid function}} \hat{y} \xrightarrow{-y \log(\hat{y}) - (1 - y) \log(1 - \hat{y})} \ell(\mathbf{x}, y)$$

$$\frac{\partial \hat{y}}{\partial z} = \sigma'(z) = \sigma(z)(1 - \sigma(z))$$

- By chain rule:

$$\frac{\partial l}{\partial w_{11}} = (\hat{y} - y)x_1$$

Computing Gradients



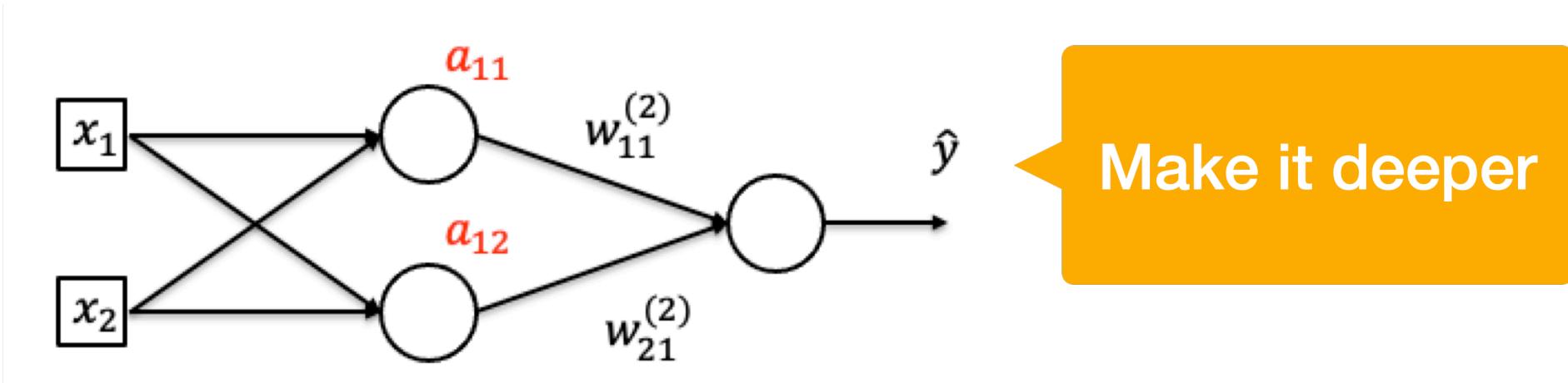
A computational graph illustrating the forward pass and gradients. On the left, inputs $w_{11}x_1$ and $w_{21}x_2$ are summed at a plus node to produce z . This z is passed through a "sigmoid function" to produce \hat{y} . The loss function $\ell(\mathbf{x}, y)$ is then calculated as $-y \log(\hat{y}) - (1 - y) \log(1 - \hat{y})$. Below the graph, the derivative of the sigmoid function is given as $\frac{\partial \hat{y}}{\partial z} = \sigma'(z) = \sigma(z)(1 - \sigma(z))$.

$$\begin{array}{c} w_{11}x_1 \\ w_{21}x_2 \end{array} \rightarrow \text{+} \rightarrow z \rightarrow \text{sigmoid function} \rightarrow \hat{y} \rightarrow \ell(\mathbf{x}, y)$$
$$\frac{\partial \hat{y}}{\partial z} = \sigma'(z) = \sigma(z)(1 - \sigma(z))$$

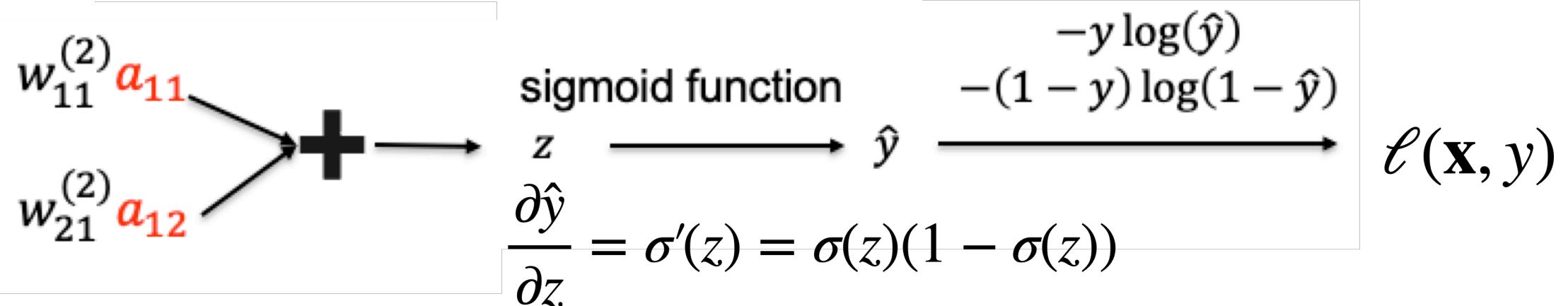
- By chain rule:

$$\frac{\partial l}{\partial x_1} = \frac{\partial l}{\partial \hat{y}} \frac{\partial \hat{y}}{\partial z} w_{11} = (\hat{y} - y)w_{11}$$

Computing Gradients: More Layers



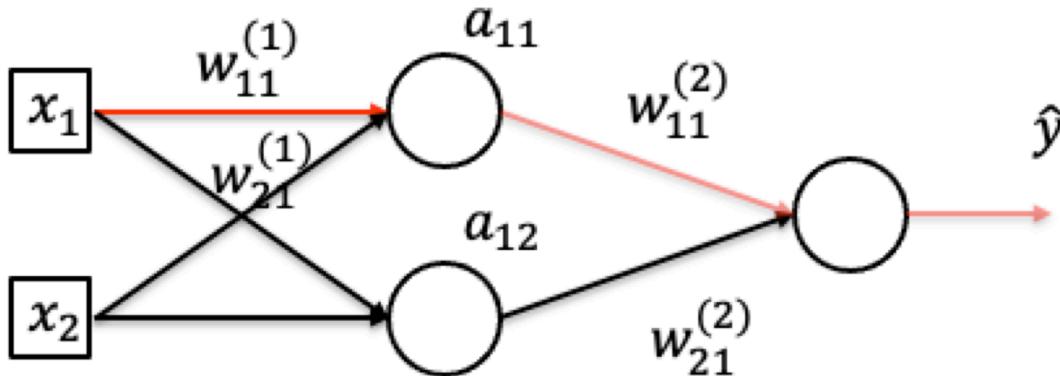
Make it deeper



- By chain rule:

$$\frac{\partial l}{\partial a_{11}} = (\hat{y} - y)w_{11}^{(2)}, \quad \frac{\partial l}{\partial a_{12}} = (\hat{y} - y)w_{21}^{(2)}$$

Computing Gradients: More Layers

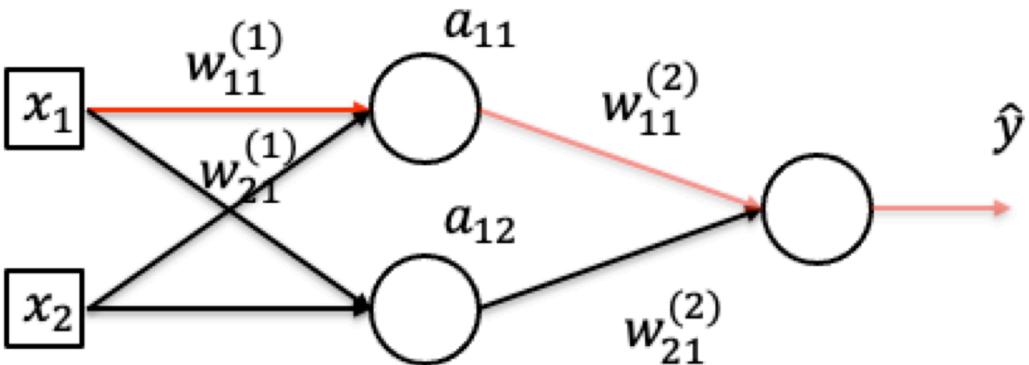


$$\begin{aligned} & w_{11}^{(1)} x_1 \quad \quad \quad w_{21}^{(1)} x_2 \quad \quad \quad + \quad \quad \quad z_{11} \quad \xrightarrow{\sigma(z_{11})} \quad a_{11} \quad \xrightarrow{} \quad l(x, y) \\ & \frac{\partial a_{11}}{\partial z_{11}} = \sigma'(z_{11}) \quad \quad \quad \frac{\partial l}{\partial a_{11}} = (\hat{y} - y) w_{11}^{(2)} \end{aligned}$$

- By chain rule:

$$\frac{\partial l}{\partial w_{11}} = \frac{\partial l}{\partial a_{11}} \frac{\partial a_{11}}{\partial w_{11}^{(1)}} = (\hat{y} - y) w_{11}^{(2)} \frac{\partial a_{11}}{\partial w_{11}^{(1)}}$$

Computing Gradients: More Layers

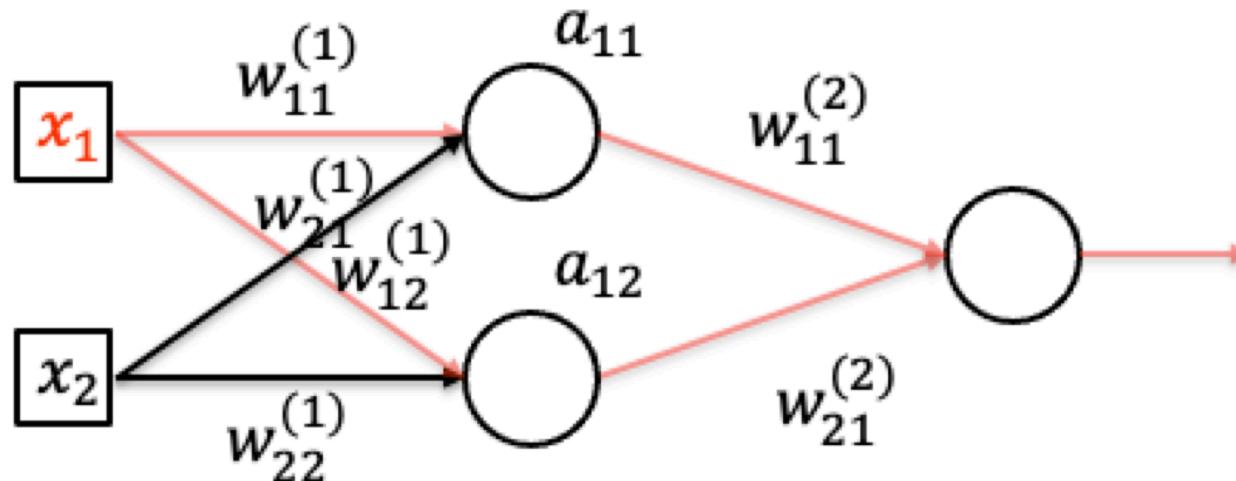


A computational graph illustrating the backpropagation process. It starts with the loss function $l(\mathbf{x}, y)$ on the right. A horizontal arrow points to the right from $l(\mathbf{x}, y)$, labeled with the gradient $\frac{\partial l}{\partial a_{11}}$. Below this arrow is the formula $\frac{\partial l}{\partial a_{11}} = (\hat{y} - y)w_{11}^{(2)}$. From the right side of the a_{11} node, a horizontal arrow points to the right, labeled with the gradient $\frac{\partial a_{11}}{\partial z_{11}}$. Below this arrow is the formula $\frac{\partial a_{11}}{\partial z_{11}} = \sigma'(z_{11})$. From the right side of the z_{11} node, a horizontal arrow points to the right, labeled with the gradient $\sigma(z_{11})$. Below this arrow is the formula $\sigma(z_{11}) = a_{11}$. From the right side of the a_{11} node, a diagonal arrow points down and to the left, labeled with the gradient $w_{11}^{(1)}$. From the right side of the a_{12} node, a diagonal arrow points down and to the left, labeled with the gradient $w_{21}^{(1)}$. These two arrows converge at a black addition symbol ($+$), representing the sum of the weighted inputs. The inputs to the addition symbol are $w_{11}^{(1)}x_1$ and $w_{21}^{(1)}x_2$.

- By chain rule:

$$\frac{\partial l}{\partial w_{11}} = \frac{\partial l}{\partial a_{11}} \frac{\partial a_{11}}{\partial w_{11}^{(1)}} = (\hat{y} - y)w_{11}^{(2)}a_{11}(1 - a_{11})x_1$$

Computing Gradients: More Layers



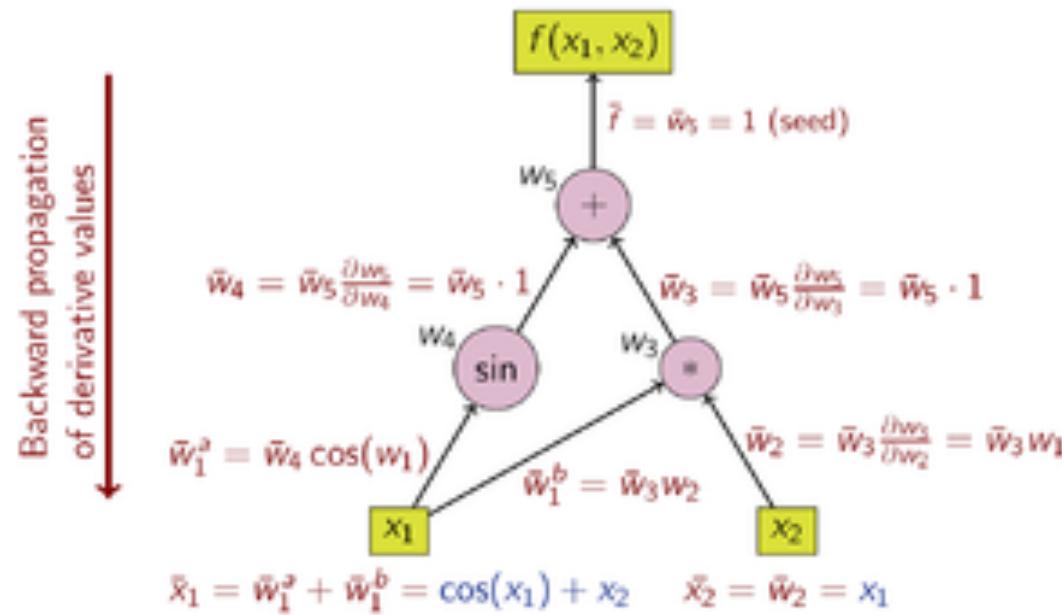
$$\begin{aligned} & w_{11}^{(1)}x_1 \\ & w_{21}^{(1)}x_2 \end{aligned} \rightarrow \text{+} \rightarrow z_{11} \xrightarrow{\sigma(z_{11})} a_{11} \xrightarrow{\frac{\partial l}{\partial a_{11}} = \sigma'(z_{11})} \frac{\partial l}{\partial a_{11}} = (\hat{y} - y)w_{11}^{(2)}$$

- By chain rule:

$$\frac{\partial l}{\partial x_1} = \frac{\partial l}{\partial a_{11}} \frac{\partial a_{11}}{\partial x_1} + \frac{\partial l}{\partial a_{12}} \frac{\partial a_{12}}{\partial x_1}$$

Backpropagation

- Now we can compute derivatives for particular neurons, but we want to automate this process
- Set up a computation graph and run on the graph
- Go backwards from top to bottom, recursively computing gradients





Break & Quiz

Q2-1: Are these statements true or false?

- (A) Backpropagation is based on the chain rule.
- (B) Backpropagation contains only forward passes.

- 1. True, True
- 2. True, False
- 3. False, True
- 4. False, False

Q2-1: Are these statements true or false?

- (A) Backpropagation is based on the chain rule.
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- 4. False, False



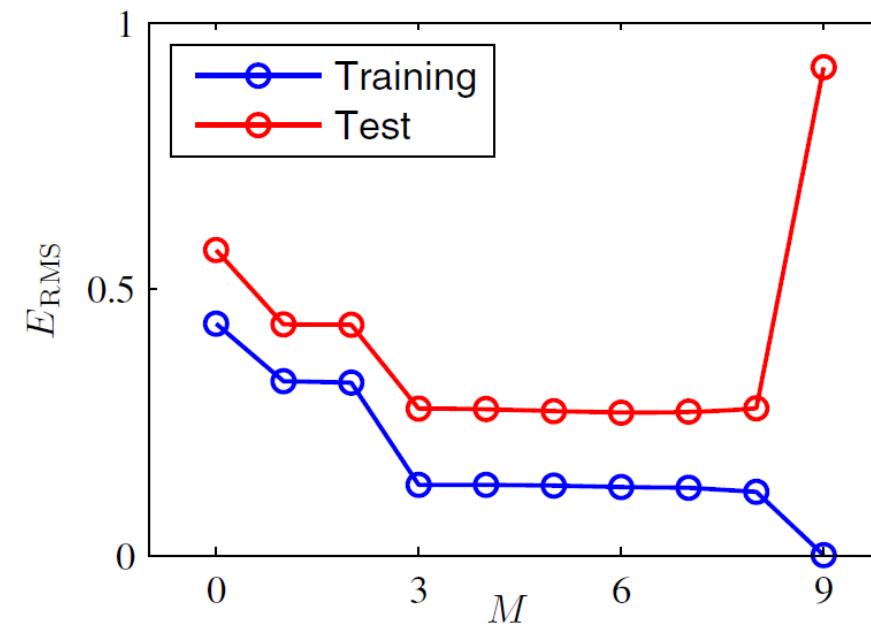
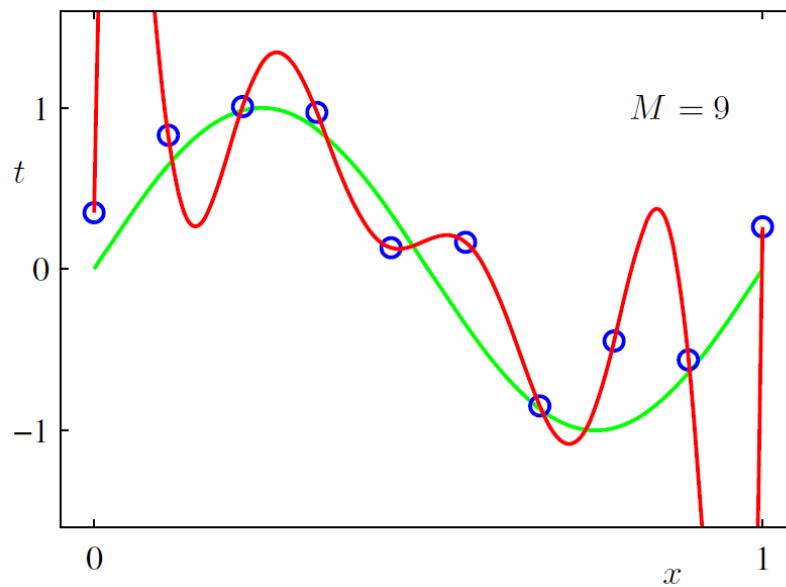
- (A) We use chain rule to calculate the partial derivatives of composite functions like neural network.
- (B) It contains both forward and backward passes.

Outline

- **Neural Networks**
 - Introduction, Setup, Components, Activations
- **Training Neural Networks**
 - SGD, Computing Gradients, Backpropagation
- **Regularization**
 - Views, Data Augmentation, Other approaches

Review: Overfitting

- What is it? When empirical loss and expected loss are different
- Possible solutions:
 - Larger data set
 - Throwing away useless hypotheses also helps (**regularization**)



Review: Regularization

- In general: any method to **prevent overfitting**
- One approach: modify the optimization objective
- Different “views”
 - Hard constraint,
 - Soft constraint,
 - Bayesian view

Regularization: Hard Constraint View

- Training objective / parametrized version

$$\min_f \hat{L}(f) = \frac{1}{n} \sum_{i=1}^n l(f, x_i, y_i)$$

subject to: $f \in \mathcal{H}$

$$\min_\theta \hat{L}(\theta) = \frac{1}{n} \sum_{i=1}^n l(\theta, x_i, y_i)$$

subject to: $\theta \in \Omega$

- Constrain beyond its natural choice

$$\min_\theta \hat{L}(\theta) = \frac{1}{n} \sum_{i=1}^n l(\theta, x_i, y_i)$$

subject to: $R(\theta) \leq r$

$$\min_\theta \hat{L}(\theta) = \frac{1}{n} \sum_{i=1}^n l(\theta, x_i, y_i)$$

subject to: $\|\theta\|_2^2 \leq r^2$

L2 Regularization

Regularization: Soft Constraint View

- Equivalent to, for some parameter $\lambda \uparrow * > 0$

$$\min_{\theta} \hat{L}_R(\theta) = \frac{1}{n} \sum_{i=1}^n l(\theta, x_i, y_i) + \lambda^* R(\theta)$$

- For L2,

$$\min_{\theta} \hat{L}_R(\theta) = \frac{1}{n} \sum_{i=1}^n l(\theta, x_i, y_i) + \lambda^* \|\theta\|_2^2$$

- Comes from **Lagrangian duality**

Regularization: Bayesian Prior View

- Recall our MAP version of training. Bayes law:

$$p(\theta | \{x_i, y_i\}) = \frac{p(\theta)p(\{x_i, y_i\}|\theta)}{p(\{x_i, y_i\})}$$

- MAP:

$$\max_{\theta} \log p(\theta | \{x_i, y_i\}) = \min_{\theta} \underbrace{-\log p(\theta)}_{\text{Regularization}} - \underbrace{\log p(\{x_i, y_i\} | \theta)}_{\text{MLE loss}}$$

Choice of View?

- Typical choice for optimization: soft-constraint

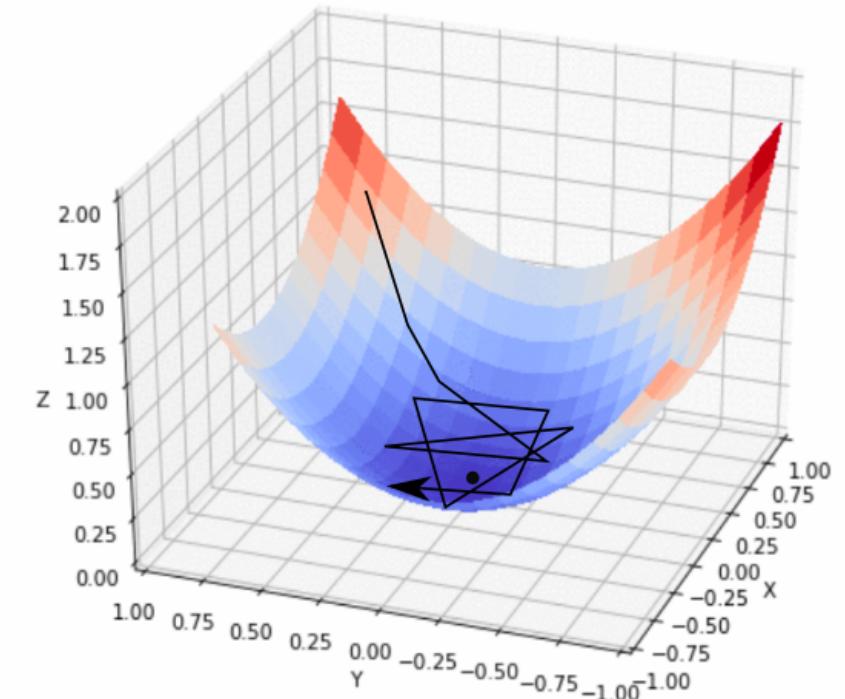
$$\min_{\theta} \hat{L}_R(\theta) = \hat{L}(\theta) + \lambda R(\theta)$$

- Hard constraint / Bayesian view: conceptual / for derivation
- Hard-constraint preferred if
 - Know the explicit bound
- Bayesian view preferred if
 - Domain knowledge easy to represent as a prior

Examples: L2 Regularization

$$\min_{\theta} \hat{L}_R(\theta) = \hat{L}(\theta) + \frac{\lambda}{2} \|\theta\|_2^2$$

- Questions: what are the
 - Effects on (stochastic) gradient descent?
 - Effects on the optimal solution?



L2 Regularization: Effect on GD

- Gradient of regularized objective

$$\nabla \hat{L}_R(\theta) = \nabla \hat{L}(\theta) + \lambda \theta$$

- Gradient descent update

$$\theta \leftarrow \theta - \eta \nabla \hat{L}_R(\theta) = \theta - \eta \nabla \hat{L}(\theta) - \eta \lambda \theta$$

$$= (1 - \eta \lambda) \theta - \eta \nabla \hat{L}(\theta)$$

- In words, **weight decay**

L2 Regularization: Effect on Optimal Solution

- Consider a quadratic approximation around

$$\hat{L}(\theta) \approx \hat{L}(\theta^*) + (\theta - \theta^*)^T \nabla \hat{L}(\theta^*) + \frac{1}{2} (\theta - \theta^*)^T H (\theta - \theta^*)$$

- Since θ^* is optimal,

$$\hat{L}(\theta) \approx \hat{L}(\theta^*) + \frac{1}{2} (\theta - \theta^*)^T H (\theta - \theta^*)$$

$$\nabla \hat{L}(\theta) \approx H(\theta - \theta^*)$$

L2 Regularization: Effect on Optimal Solution

- Gradient of regularized objective: $\nabla \hat{L}_R(\theta) \approx H(\theta - \theta^*) + \lambda\theta$
- On the optimal θ_R^* : $0 = \nabla \hat{L}_R(\theta_R^*) \approx H(\theta_R^* - \theta^*) + \lambda\theta_R^*$
$$\theta_R^* \approx (H + \lambda I)^{-1} H \theta^*$$
- H has eigendecomps. $H = Q\Lambda Q^T$, assume $(\Lambda + \lambda I)^{-1}$ exists:
$$\theta_R^* \approx (H + \lambda I)^{-1} H \theta^* = Q(\Lambda + \lambda I)^{-1} \Lambda Q^T \theta^*$$

Effect: **rescale along eigenvectors of H**



Thanks Everyone!

Some of the slides in these lectures have been adapted/borrowed from materials developed by Mark Craven, David Page, Jude Shavlik, Tom Mitchell, Nina Balcan, Elad Hazan, Tom Dietterich, Pedro Domingos, Jerry Zhu, Yingyu Liang, Volodymyr Kuleshov, Sharon Li