

CS 760: Machine Learning Graphical Models

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Announcements

- •Lecture recordings for last 4 lectures out
 - (Small issue with last recording, use slides from the webpage to follow along)

• HW 5 due next Monday.

Outline

Probability Review

•Basics, joint probability, conditional probabilities, etc

Bayesian Networks

• Definition, examples, inference, learning

Undirected Graphical Models

• Definitions, MRFs, exponential families

Structure learning

•Chow-Liu Algorithm

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Basics: Joint Distributions

•Joint distribution of 2 random variables X and Y

$$P(X = a, Y = b)$$

•Or more variables.

$$P(X_1 = x_1, X_2 = x_2, \dots, X_k = x_k)$$

Basics: Marginal Probability

•Given a joint distribution

$$P(X = a, Y = b)$$

•Compute the distribution of just one variable:

$$P(X = a) = \sum_{b} P(X = a, Y = b)$$

•This is the "marginal" distribution.

Basics: Marginal Probability

$$P(X = a) = \sum_{b} P(X = a, Y = b)$$



$$[P(hot), P(cold)] = [\frac{195}{365}, \frac{170}{365}]$$





Independence

•Independence for a set of events A_1, \ldots, A_k

 $P(A_{i_1}A_{i_2}\cdots A_{i_j}) = P(A_{i_1})P(A_{i_2})\cdots P(A_{i_j})$ for all the i₁,...,i_j combinations

•Why useful? Dramatically reduces the complexity
•Collapses joint into **product** of marginals
•Note sometimes we have only pair-wise, etc

independence

Uncorrelatedness

•For random variables, uncorrelated means

E[XY] = E[X]E[Y]

Note: weaker than independence.

- Independence implies uncorrelated (easy to see)
- If X,Y independent, functions are not correlated:

E[f(X)f(Y)] = E[f(X)]E[f(Y)]

Conditional Probability

•When we know something,

$$P(X = a | Y = b) = \frac{P(X = a, Y = b)}{P(Y = b)}$$

Conditional independence



Credit: Devin Soni

$$P(X, Y|Z) = P(X|Z)P(Y|Z)$$

Chain Rule

Apply repeatedly,

$$P(A_1, A_2, \ldots, A_n)$$

 $= P(A_1)P(A_2|A_1)P(A_3|A_2, A_1)\dots P(A_n|A_{n-1}, \dots, A_1)$

- •Note: still big!
 - If some **conditional independence**, can factor!
 - •Leads to probabilistic graphical models (this lecture)

Law of Total Probability

•Partition the sample space into disjoint $B_1, ..., B_k$ •Then,

 $P(A) = \sum P(A|B_i)P(B_i)$ i

Bayesian Inference

•Bayes rule:

$$P(H|E_1, E_2, \dots, E_n) = \frac{P(E_1, \dots, E_n|H)P(H)}{P(E_1, E_2, \dots, E_n)}$$

•Under conditional independence

$$P(H|E_1, E_2, \dots, E_n) = \frac{P(E_1|H)P(E_2|H)\cdots, P(E_n|H)P(H)}{P(E_1, E_2, \dots, E_n)}$$

Random Vectors & Covariance

•Recall variance:

$$\mathbb{E}[(X - E[X])^2]$$

•For a random vector

• Note: size d x d. All variables are centered

$$\Sigma = \begin{bmatrix} \mathbb{E}[(X_1 - \mathbb{E}[X_1])^2] & \dots & [(X_1 - \mathbb{E}[X_1])((X_n - \mathbb{E}[X_n])] \\ \vdots & \vdots & \vdots \\ [(X_n - \mathbb{E}[X_n])((X_1 - \mathbb{E}[X_1])] & \dots & \mathbb{E}[(X_n - \mathbb{E}[X_n])^2] \end{bmatrix}$$
Covariance
Diagonals: Variance



50% of emails are spam. Software has been applied to filter spam. A certain brand of software claims that it can detect 99% of spam emails, and the probability for a false positive (a non-spam email detected as spam) is 5%. Now if an email is detected as spam, then what is the probability that it is in fact a nonspam email?

- A. 5/104
- B. 95/100
- C. 1/100

D. 1/2

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•Consider the following 5 binary random variables:

- *B* = a burglary occurs at the house
- *E* = an earthquake occurs at the house
- A = the alarm goes off
- J = John calls to report the alarm
- *M* = Mary calls to report the alarm

•Suppose the Burglary or Earthquake can trigger Alarm, and Alarm can trigger John's call or Mary's call

•Now we want to answer queries like what is $P(B \mid M, J)$?













Bayesian Networks: Definition

- A BN consists of a **Directed Acyclic Graph (DAG**) and a set of **conditional probability distribution**s (CPD)
- The DAG:
 - each node denotes a random variable
 - each edge from X to Y typically represents a causal link from X to Y
 - formally: each variable X is independent of its non-descendants given its parents
 - Each CPD: represents P(X | Parents(X))

$$p(x_1, \dots, x_d) = \prod_{v \in V} p(x_v | x_{\operatorname{pa}(v)})$$



Bayesian Networks: Parameter Counting

- Parameter reduction: standard representation of the joint distribution for Alarm example has 2⁵-1 = 31 parameters
- the BN representation of this distribution has 10 parameters



Inference in Bayesian Networks

- **Given**: values for some variables in the network (*evidence*), and a set of *query* variables
- **Do**: compute the posterior distribution over the query variables
- Variables that are neither evidence variables nor query variables are *hidden* variables
- •The BN representation is flexible enough that any set can be the evidence variables and any set can be the query variables

Inference by Enumeration

- •Let *a* denote A=true, and $\neg a$ denote A=false
- •Suppose we're given the query: $P(b \mid j, m)$

"probability the house is being burglarized given that John and Mary both called"

• From the graph structure we can first compute:



Inference by Enumeration



Inference by Enumeration

•Next do equivalent calculation for $P(\neg b, j, m)$ and determine $P(b \mid j, m)$

$$P(b \mid j, m) = \frac{P(b, j, m)}{P(j, m)} = \frac{P(b, j, m)}{P(b, j, m) + P(\neg b, j, m)}$$

So: exact method, but can be intractably hard.

- Efficient for small BNs
- •Approximate inference sometimes available

Learning Bayes Nets

• Problem 1 (parameter learning): given a set of training instances, the graph structure of a BN



•Goal: infer the parameters of the CPDs

Learning Bayes Nets

• Problem 2 (structure learning): given a set of training instances



•Goal: infer the graph structure (and then possibly also the parameters of the CPDs)

Parameter Learning: MLE

- •Goal: infer the parameters of the CPDs
- •As usual, can use MLE

$$L(\theta: D, G) = P(D \mid G, \theta) = \prod_{d \in D} P(x_1^{(d)}, x_2^{(d)}, ..., x_n^{(d)})$$

$$= \prod_{d \in D} \prod_i P(x_i^{(d)} \mid Parents(x_i^{(d)}))$$

$$= \prod_i \left(\prod_{d \in D} P(x_i^{(d)} \mid Parents(x_i^{(d)})) \right)$$

independent parameter learning
problem for each CPD

Parameter Learning: MLE Example

- •Goal: infer the parameters of the CPDs
- •Consider estimating the CPD parameters for B and J in the alarm network given the following data set



В	E	A	J	М
f	f	f	t	f
f	t	f	f	f
f	f	f	t	t
t	f	f	f	t
f	f	t	t	f
f	f	t	f	t
f	f	t	t	t
f	f	t	t	t

 $P(b) = \frac{1}{8} = 0.125$ $P(\neg b) = \frac{7}{8} = 0.875$ $P(j \mid a) = \frac{3}{4} = 0.75$ $P(\neg j \mid a) = \frac{1}{4} = 0.25$ $P(j \mid \neg a) = \frac{2}{4} = 0.5$ $P(\neg j \mid \neg a) = \frac{2}{4} = 0.5$

Parameter Learning: MLE Example

- •Goal: infer the parameters of the CPDs
- •Consider estimating the CPD parameters for B and J in the alarm network given the following data set





$$P(b) = \frac{0}{8} = 0$$
$$P(\neg b) = \frac{8}{8} = 1$$

do we really want to set this to 0?

Parameter Learning: Laplace Smoothing

- Instead of estimating parameters strictly from the data, we could start with some prior belief for each
- •For example, we could use *Laplace estimates*



where n_v represents the number of occurrences of value v•Recall: we did this for Naïve Bayes



Q2-1: Consider a case with 8 binary random variables, how many parameters does a BN with the following graph structure have?

- 1. 12
- 2. 14
- 3. 16
- 4. 26



Q2-1: Consider a case with 8 binary random variables, how many parameters does a BN with the following graph structure have?





So we have 16 parameters in total.

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Undirected Graphical Models

- •Still want to encode conditional independence, but not in an causal way (ie, no parents, direction)
 - Why? Allows for modeling other distributions that Bayes nets can't, allows for other algorithms
- •Graph directly encodes a type of conditional independence. If nodes i, j are not neighbors,

$$X_i \perp X_j | X_{V \setminus \{i,j\}}|$$

Markov Random Fields

- •A particularly popular kind of undirected model. As above, can describe in terms of:
 - 1. Conditional independence:

$$X_i \perp X_j | X_{V \setminus \{i,j\}}$$

- •2. Factorization. (Clique: maximal fully-connected subgraphs)
 - Bayes nets: factorize over CPTs with **parents**; MRFs: factorize over **cliques**

$$P(X) = \frac{1}{Z} \prod_{C \in \text{cliques}(G)} \phi_C(X_C)$$
Partition function Potential functions

Ising Models

- Ising models: a particular kind of MRF usually written in exponential form
 - Popular in statistical physics
 - Idea: pairwise interactions (biggest cliques of size 2)

$$P(x_1, \dots, x_d) = \frac{1}{Z} \exp(\sum_{(i,j)\in E} \theta_{ij} x_i x_j)$$

- •Challenges:
 - Compute partition function
 - Perform inference/marginalization

Khudier and Fawaz

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Structure Learning

- •Generally a hard problem, many approaches.
 - Exponentially (or worse) many structures in # variables
 - Can either use heuristics or restrict to some tractable subset of networks. Ex: trees
- •Chow-Liu Algorithm
 - Learns a BN with a <u>tree structure</u> that maximizes the likelihood of the training data
 - 1. Compute weight $I(X_i, X_j)$ of each possible edge (X_i, X_j)
 - 2. Find maximum weight spanning tree (MST)

Chow-Liu: Computing weights

• Use mutual information to calculate edge weights

$$I(X,Y) = \sum_{x \in \text{values}(X)} \sum_{y \in \text{values}(Y)} P(x,y) \log_2 \frac{P(x,y)}{P(x)P(y)}$$

•The probabilities are calculated empirically using data

Chow-Liu: Finding MST

- Many algorithms for calculating MST (e.g Kruskal's, Prim's)
- •Kruskal's algorithm

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given: graph with vertices V and edges E
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\begin{split} E_{new} &\leftarrow \{ \ \} \\ \text{for each } (u, v) \text{ in } E \text{ ordered by weight (from high to low)} \\ \{ \\ \text{remove } (u, v) \text{ from } E \\ \text{if adding } (u, v) \text{ to } E_{new} \text{ does not create a cycle} \\ \text{add } (u, v) \text{ to } E_{new} \\ \} \\ \text{return } V \text{ and } E_{new} \text{ which represent an MST} \end{split}
```

Chow-Liu: Example

- First, calculate empirical mutual information for each pair and calculate edge weights.
 - Graph is usually fully connected (using a non-complete graph for clarity)



Chow-Liu: Example (cont'd)









ii.



Chow-Liu: Example (cont'd)





Chow-Liu Algorithm

- 1. Finding tree structures is a 'second order' approximation
 - First order: product of marginals $P(X_1, \ldots, X_n) = \prod_{i=1}^n P(X_i)$
 - Second order: allow conditioning on one variable $P(X_1, \ldots, X_n) = P(X_1) \prod_{i=1}^n P(X_i | X_{i-1})$
- 2. To assign directions in a Bayes' network, pick a root and making everything directed from root (may require domain expertise)





Thanks Everyone!

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