



CS 760: Machine Learning **ML Overview**

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Announcements

- **Enrollment:**

- Some of you should have been able to enroll last week.
- Undergraduates: email me (if you haven't in the last 1-2 weeks)

- **Recordings**

- Not set up yet. Will try and resolve this by next week.

Announcements

- **Background knowledge:**
 - We will assume knowledge of calculus, linear algebra, prob/stat etc.
 - If you consider yourself to be mathematically inclined, you should be fine.
 - Some programming experience is necessary.
 - We will use Python, Numpy, and relevant libraries but you don't need specific experience in any of them.
- **Homework 1**
 - Due on Wednesday at 10

Outline

- **Review from last time**

- Supervised vs. unsupervised learning

- **Supervised learning concepts**

- Features, models, training, other terminology

- **Unsupervised learning concepts**

- Clustering, anomaly detection, dimensionality reduction

Outline

- **Review from last time**

- Supervised vs. unsupervised learning

- **Supervised learning concepts**

- Features, models, training, other terminology

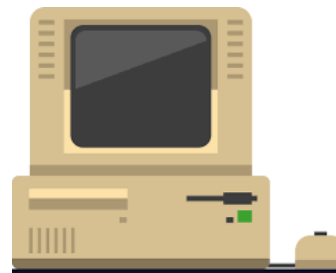
- **Unsupervised learning concepts**

- Clustering, anomaly detection, dimensionality reduction

Review: ML Overview: Definition

What is machine learning?

“A computer program is said to learn from experience **E** with respect to some class of tasks **T** and performance measure **P**, if its performance at tasks in **T** as measured by **P**, improves with experience **E**.” *Machine Learning*, Tom Mitchell, 1997



learning



ML Overview: Flavors

Supervised Learning

- Learning from examples, as above
- **Workflow:**
 - Collect a set of examples {data, labels}: **training set**
 - “**Train**” a model to match these examples
 - “**Test**” it on new data

• Image classification:



indoor



outdoor



ML Overview: Flavors

Supervised Learning

- **Example: Image classification**
- Recall **T**ask/**P**erformance measure/**E**xperience definition
 - **T**ask: distinguish **indoor** vs **outdoor**
 - **P**erformance measure: probability of misclassifying
 - **E**xperience: labeled examples



indoor



outdoor

ML Overview: Flavors

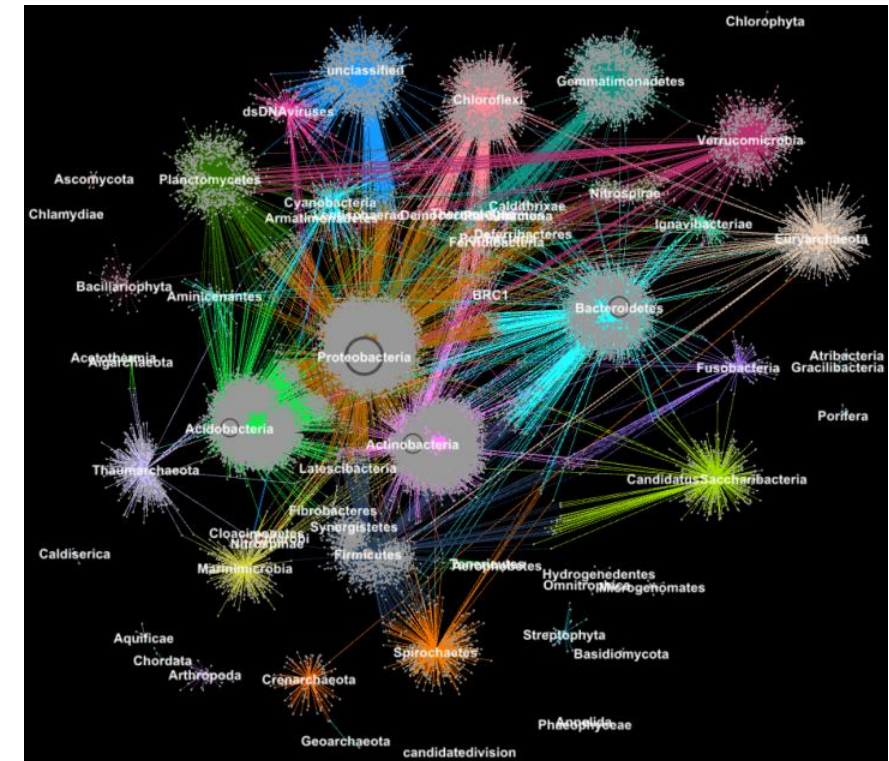
Unsupervised Learning

- Data, but no labels. No input/output.
- Goal: get “something”: structure, hidden information, more

- **Workflow:**

- Collect a set {data}
- Perform some algorithm on it

- **Clustering:** reveal hidden structure

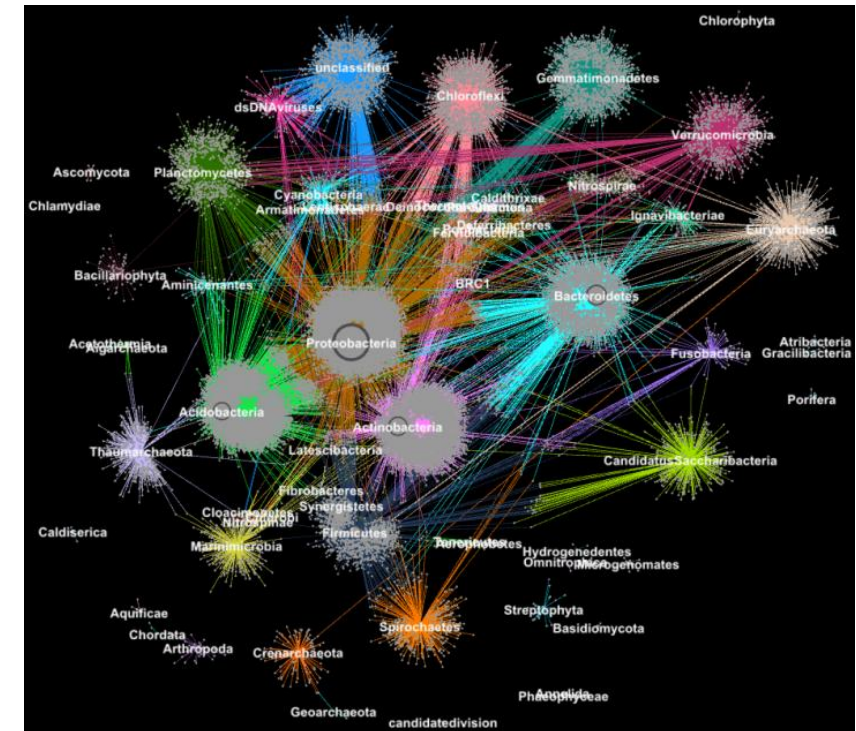


ML Overview: Flavors

Unsupervised Learning

- **Example: Clustering**

- **Task:** produce distinct clusters for a set of data
- **Performance measure:** closeness to underlying structure
- **Experience:** available datapoints



ML Overview: Flavors

Reinforcement Learning

- Agent interacting with the world; gets rewards for actions
- Goal: learn to perform some activity
- **Workflow:**
 - Create an environment, reward, agent
 - **Train:** modify policy to maximize rewards
 - **Deploy** in new environment
- **Controlling aircraft:** learn to fly



ML Overview: Flavors

Reinforcement Learning

- **Example: Controlling aircraft**

- **Task:** keep the aircraft in the air, steer towards a desired goal
- **Performance measure:** reward for reaching goal quickly
- **Experience:** data (state/action/reward) from previous flights





Break & Quiz

Q1-1: Which of the following is generally NOT a supervised learning task?

1. Binary classification
2. Email spam detection
3. Handwriting recognition
4. Eigenvalue calculation

Outline

- Review from last time

- Supervised vs. unsupervised learning

- **Supervised learning concepts**

- Features, models, training, other terminology

- Unsupervised learning concepts

- Clustering, anomaly detection, dimensionality reduction

Supervised Learning

- Can I eat this?
- Safe or poisonous?
 - **Never seen it before**
- How to decide?



Supervised Learning: Training Instances

- I know about other mushrooms:

safe



poisonous



- Training set of **examples/instances/labeled data**

Supervised Learning: Formal Setup

Problem setting

- Set of possible instances

 \mathcal{X}

- Unknown *target function*

 $f : \mathcal{X} \rightarrow \mathcal{Y}$

- Set of *models* (a.k.a. *hypotheses*):

 $\mathcal{H} = \{h | h : \mathcal{X} \rightarrow \mathcal{Y}\}$

Get

- Training set of instances for unknown target function,

where $y^{(i)} \approx f(x^{(i)})$

 $(x^{(1)}, y^{(1)}), (x^{(2)}, y^{(2)}), \dots, (x^{(n)}, y^{(n)})$ 

safe



poisonous



safe

Supervised Learning: Formal Setup

Problem setting

- Set of possible instances
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- Set of *models* (a.k.a. *hypotheses*)

 \mathcal{X} $f : \mathcal{X} \rightarrow \mathcal{Y}$ $\mathcal{H} = \{h \mid h : \mathcal{X} \rightarrow \mathcal{Y}\}$

Get

- Training set of instances for unknown target function f ,

$$(x^{(1)}, y^{(1)}), (x^{(2)}, y^{(2)}), \dots, (x^{(n)}, y^{(n)})$$

Goal: model h that best approximates f

Supervised Learning: Objects

Three types of sets

- Input space, output space, hypothesis class

$$\mathcal{X}, \mathcal{Y}, \mathcal{H}$$

• Examples:

- Input space: feature vectors

$$\mathcal{X} \subseteq \mathbb{R}^d$$

- Output space:

- Binary classification

$$\mathcal{Y} = \{-1, +1\}$$

- Continuous

$$\mathcal{Y} \subseteq \mathbb{R}$$



safe poisonous

13.23°

Input Space: Feature Vectors

- Need a way to represent instance information:

$$\mathbf{x}^{(1)} = \langle \text{bell, fibrous, gray, false, foul, ...} \rangle$$

cap-shape *cap-surface* *cap-color* *bruises* *odor*



safe

- For each instance, store features as a vector.
 - What kinds of features can we have?

Input Space: Feature Types

- *nominal* (including Boolean)

- no ordering among values (e.g. *color* \in {*red*, *blue*, *green*} (vs. *color* = 1000 Hertz))

- *ordinal*

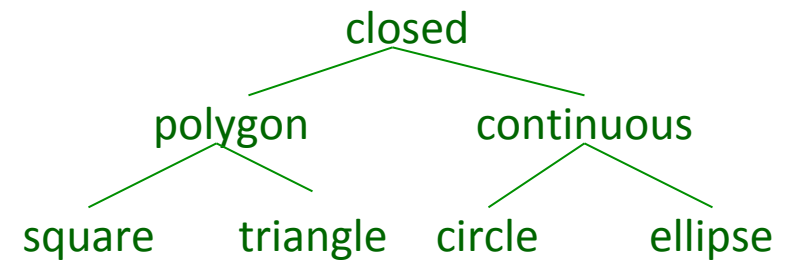
- values of the feature are totally ordered (e.g. *size* \in {*small*, *medium*, *large*})

- *numeric* (continuous)

height \in [0, 100] inches

- *hierarchical*

- possible values are partially *ordered* in a hierarchy, e.g. *shape*



Input Space: Features Example



sunken is one possible value
of the *cap-shape* feature

Mushroom features (UCI Repository)

cap-shape: bell=b,conical=c,convex=x,flat=f, knobbed=k,sunken=s

cap-surface: fibrous=f,grooves=g,scaly=y,smooth=s

cap-color: brown=n,buff=b,cinnamon=c,gray=g,green=r, pink=p,purple=u,red=e,white=w,yellow=y

bruises?: bruises=t,no=f

odor: almond=a,anise=l,creosote=c,fishy=y,foul=f, musty=m,none=n,pungent=p,spicy=s

gill-attachment: attached=a,descending=d,free=f,notched=n

gill-spacing: close=c,crowded=w,distant=d

gill-size: broad=b,narrow=n

gill-color: black=k,brown=n,buff=b,chocolate=h,gray=g, green=r,orange=o,pink=p,purple=u,red=e, white=w,yellow=y

stalk-shape: enlarging=e,tapering=t

stalk-root: bulbous=b,club=c,cup=u,equal=e, rhizomorphs=z,rooted=r,missing=?

stalk-surface-above-ring: fibrous=f,scaly=y,silky=k,smooth=s

stalk-surface-below-ring: fibrous=f,scaly=y,silky=k,smooth=s

stalk-color-above-ring: brown=n,buff=b,cinnamon=c,gray=g,orange=o, pink=p,red=e,white=w,yellow=y

stalk-color-below-ring: brown=n,buff=b,cinnamon=c,gray=g,orange=o, pink=p,red=e,white=w,yellow=y

veil-type: partial=p,universal=u

veil-color: brown=n,orange=o,white=w,yellow=y

ring-number: none=n,one=o,two=t

ring-type: cobwebby=c,evanescent=e,flaring=f,large=l, none=n,pendant=p,sheathing=s,zone=z

spore-print-color: black=k,brown=n,buff=b,chocolate=h,green=r, orange=o,purple=u,white=w,yellow=y

population: abundant=a,clustered=c,numerous=n, scattered=s,several=v,solitary=y

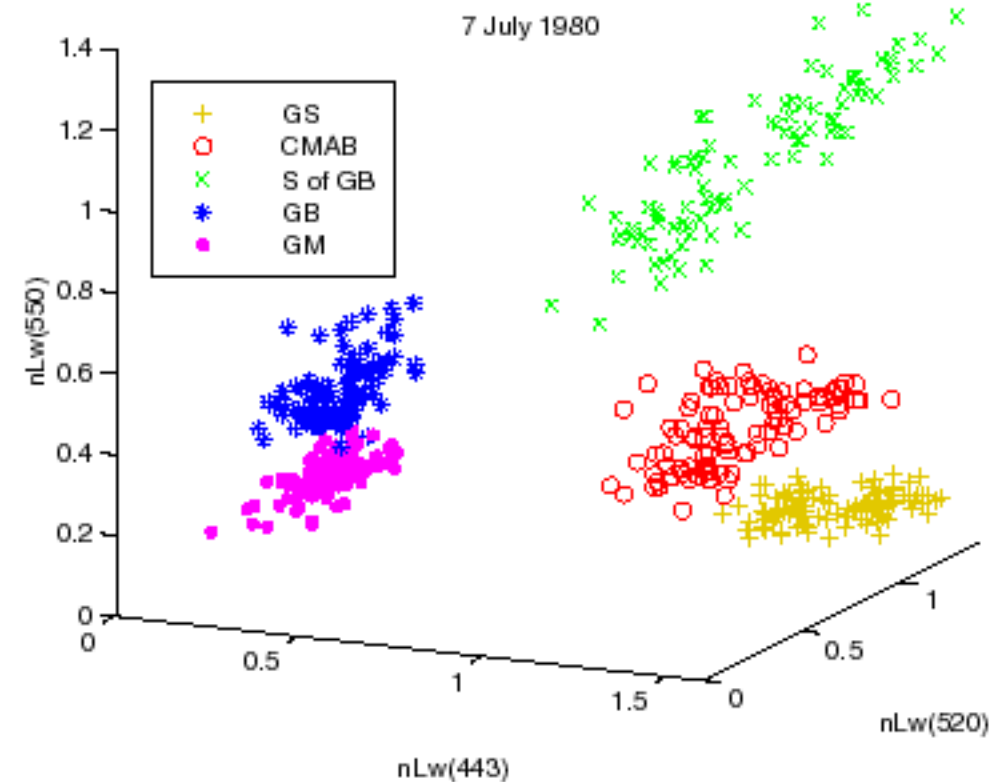
habitat: grasses=g,leaves=l,meadows=m,paths=p, urban=u,waste=w,woods=d

Input Space: Feature Spaces

- *If all features are numeric, we can think of each instance as a point in a d -dimensional Euclidean feature space where d is the number of features*

- **Example:** optical properties of oceans in three spectral bands

[Traykovski and Sosik, *Ocean Optics XIV Conference Proceedings*, 1998]



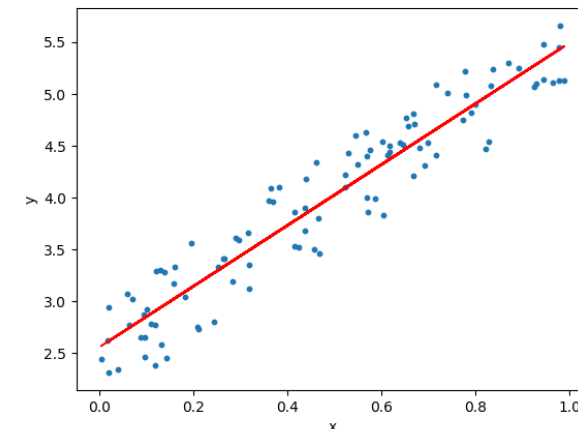
Output space: Classification vs. Regression

Choices of \mathcal{Y} have special names:

- Discrete: “**classification**”. The elements of \mathcal{Y} are **classes**
 - Note: does not have to be binary



- Continuous: “**regression**”
 - Example: linear regression
- There are other types...

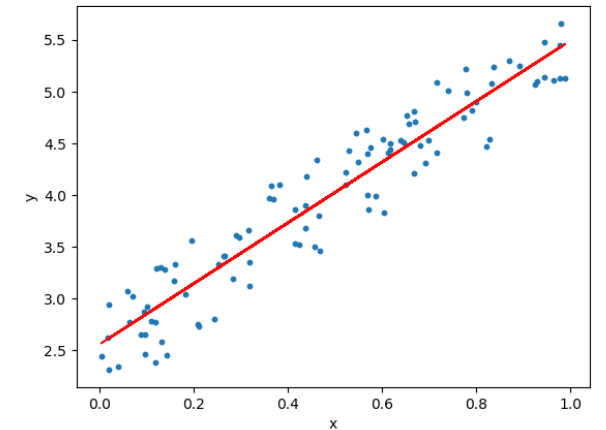


Hypothesis class

We talked about \mathcal{X}, \mathcal{Y} what about \mathcal{H} ?

- Recall: hypothesis class / model space.
 - Theoretically, could be all maps from \mathcal{X} to \mathcal{Y}
 - Does not work! We'll see why later.
- Pick specific class of models. E.g. linear models:

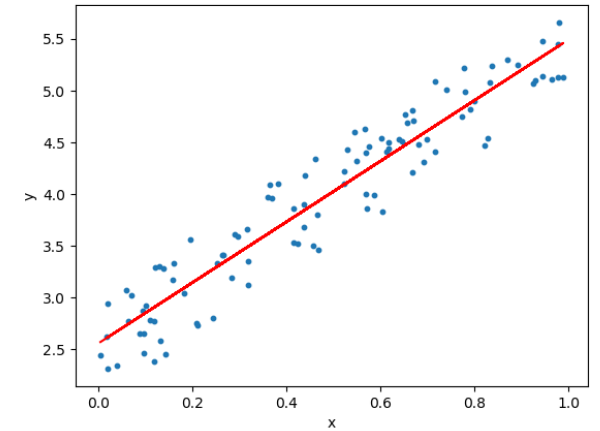
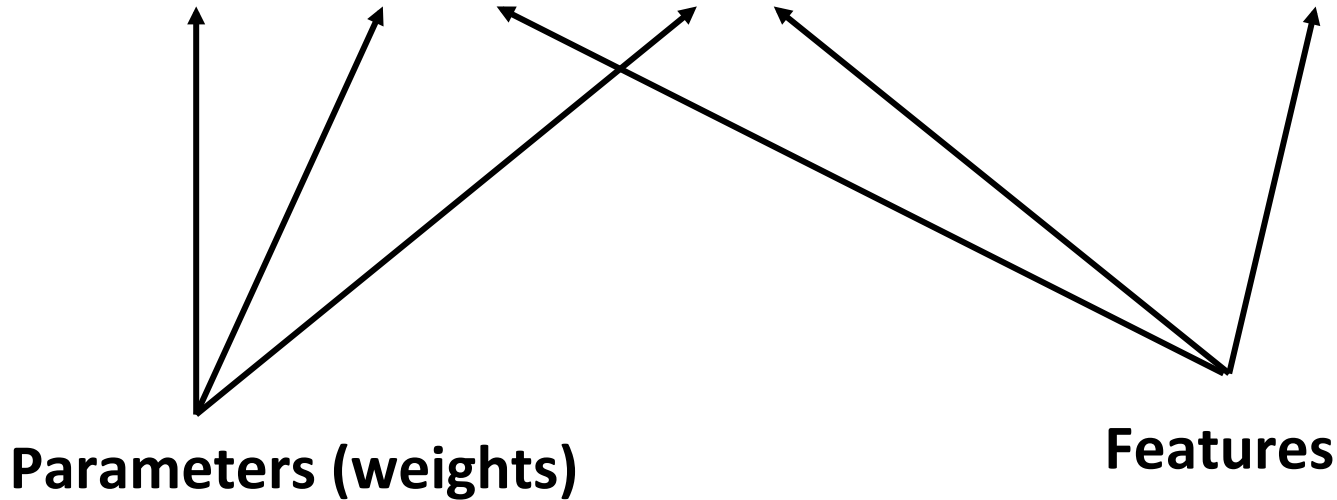
$$h_{\theta}(x) = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \dots + \theta_d x_d$$



Hypothesis class: Linear Functions

- **Example** class of models: linear models

$$h_{\theta}(x) = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \dots + \theta_d x_d$$



- How many linear functions are there?
 - Can any function be fit by a linear model?

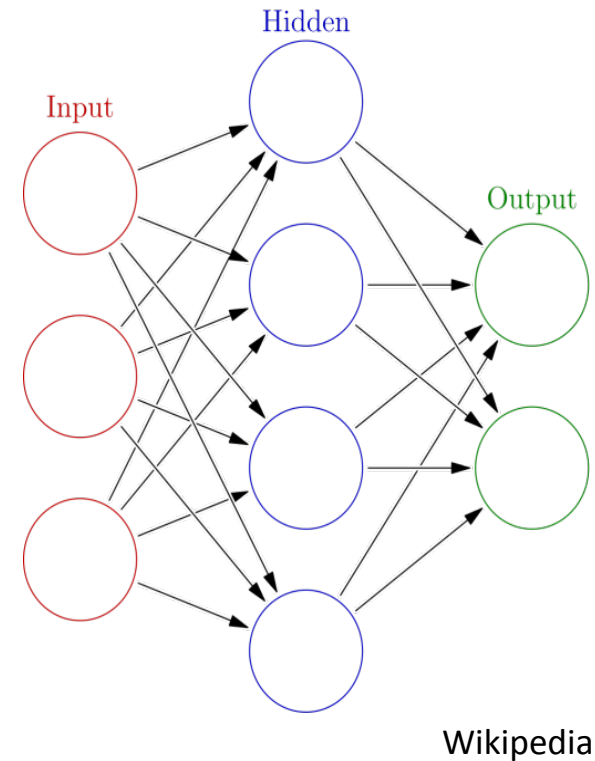
Hypothesis class: Other Examples

Example classes of models: neural networks

$$f^{(k)}(x) = \sigma(W_k^T f^{(k-1)}(x))$$

Feedforward network

- Each layer:
 - linear transformation
 - Non-linearity
- What are the parameters here?



Back to Formal Setup

Problem setting

- Set of possible instances
- Unknown *target function*
- Set of *models* (a.k.a. *hypotheses*)

 \mathcal{X} $f : \mathcal{X} \rightarrow \mathcal{Y}$ $\mathcal{H} = \{h \mid h : \mathcal{X} \rightarrow \mathcal{Y}\}$ 

Get

- Training set of instances for unknown target function f ,

 $(x^{(1)}, y^{(1)}), (x^{(2)}, y^{(2)}), \dots, (x^{(n)}, y^{(n)})$ 

Goal: model h that best approximates f

Supervised Learning: Training

Goal: model h that best approximates f

- One way: empirical risk minimization (ERM)

$$\hat{f} = \arg \min_{h \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^n \ell(h(x^{(i)}), y^{(i)})$$

Hypothesis Class

Loss function: how far is the prediction from the label)?

Model prediction

Batch vs. Online Learning

- **Batch learning:** get all your instances at once

$$(x^{(1)}, y^{(1)}), (x^{(2)}, y^{(2)}), \dots, (x^{(n)}, y^{(n)})$$

- **Online learning:** get them sequentially
 - Train a model on initial group, then update

$$\{(x^{(1)}, y^{(1)}), \dots, (x^{(m)}, y^{(m)})\} \quad \{(x^{(m+1)}, y^{(m+1)})\}$$

Supervised Learning: Predicting

Now that we have our learned model, we can use it for predictions.



$x = \langle \text{bell, fibrous, brown, false, foul, ...} \rangle$

```
odor = a: e (400.0)
odor = c: p (192.0)
odor = f: p (2160.0)
odor = l: e (400.0)
odor = m: p (36.0)
odor = n
  spore-print-color = b: e (48.0)
  spore-print-color = h: e (48.0)
  spore-print-color = k: e (1296.0)
  spore-print-color = n: e (1344.0)
  spore-print-color = o: e (48.0)
  spore-print-color = r: p (72.0)
  spore-print-color = u: e (0.0)
  spore-print-color = w
    gill-size = b: e (528.0)
    gill-size = n
      gill-spacing = c: p (32.0)
      gill-spacing = d: e (0.0)
      gill-spacing = w
        population = a: e (0.0)
        population = c: p (16.0)
        population = n: e (0.0)
        population = s: e (0.0)
        population = v: e (48.0)
        population = y: e (0.0)
    spore-print-color = y: e (48.0)
  odor = p: p (256.0)
  odor = s: p (576.0)
  odor = y: p (576.0)
```

safe or poisonous

Recall supervised learning workflow

- Collect a set of examples {data, labels}: **training set**
- **“Train”** a model to match these examples
 - E.g. Choose a hypothesis class and perform ERM
- **“Test”** it on new data



Recall supervised learning workflow

- Collect a set of examples {data, labels}: **training set**



- **“Train”** a model to match these examples



- E.g. Choose a **hypothesis class** and perform **ERM**

$$\hat{f} = \arg \min_{h \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^n \ell(h(x^{(i)}), y^{(i)})$$

Model prediction

Hypothesis Class

Loss function

- **“Test”** it on new data



From linear to polynomial regression

Another class of models: polynomials:

$$h_{\theta}(x) = \theta_d x^d + \theta_{d-1} x^{d-1} + \dots + \theta_1 x + \theta_0$$

- We can get a perfect fit by setting d to be very large.
 - E.g. In 1D, set $d = n-1$
- So, are we done?
 - How sensitive to noise?
 - How will they **extrapolate**?

Generalization

Fitting data isn't the only task, we want to **generalize**

- Apply learned model to unseen data:

- For $(x, y) \sim \mathcal{D}$,

$$\mathbb{E}_{\mathcal{D}}[\ell(\hat{f}(x), y)]$$

- Can study theoretically or empirically
 - For theory: need assumptions, ie, training instances are iid
 - Not always the case!
 - Sequential data



Break & Quiz

Q2-1: Which of the following is a NOMINAL feature as introduced in the lecture?

1. Cost $\in [0, 100]$
2. Awarded $\in \{True, False\}$
3. Steak $\in \{Rare, Medium Rare, Medium, Medium Well, Well Done\}$
4. Attitude $\in \{strongly disagree, disagree, neutral, agree, strongly agree\}$

Q2-2: What is the dimension of the following feature space?

The CIFAR-10 dataset contains 60,000 32x32 **color** images in 10 different classes.

(convert each data to a vector)

1. 10
2. 60,000
3. 3072
4. 1024

Q2-3: Are these statements true or false?

(A) Instances from time series are independent and identically distributed.

(B) The primary objective of supervised learning is to find a model that achieves the highest accuracy on the training data.

1. True, True
2. True, False
3. False, True
4. False, False

Outline

- **Review from last time**

- Supervised vs. unsupervised learning

- **Supervised learning concepts**

- Features, models, training, other terminology

- **Unsupervised learning concepts**

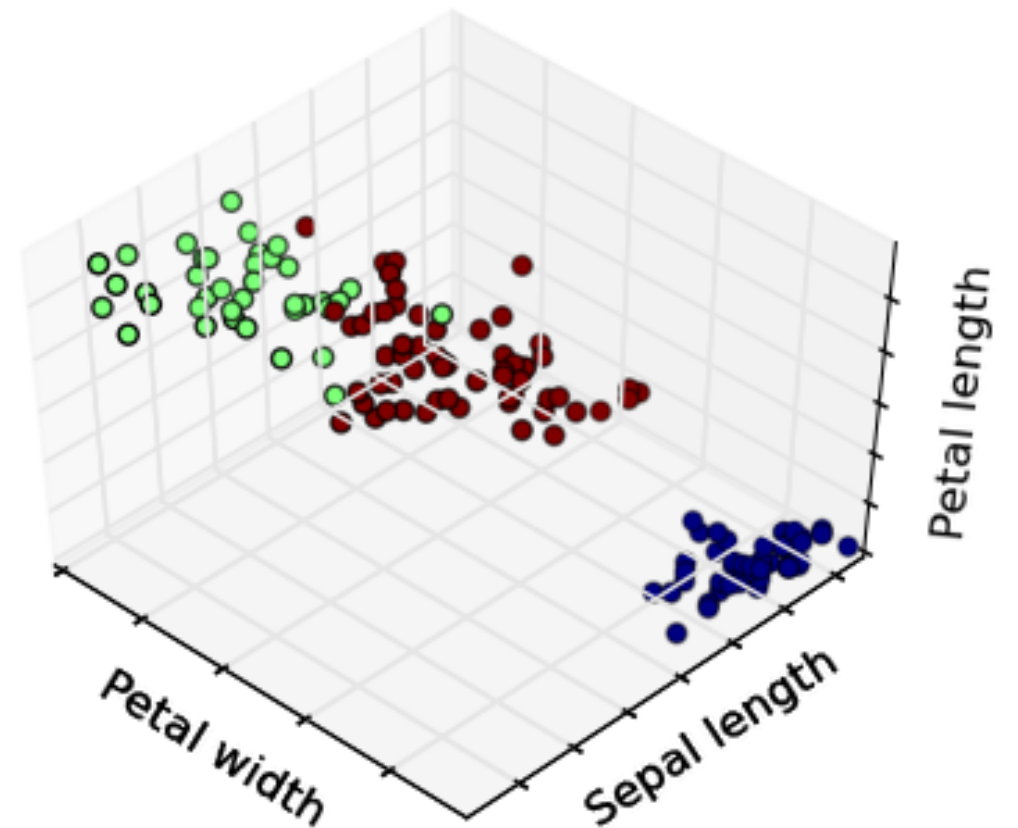
- Clustering, anomaly detection, dimensionality reduction

Unsupervised Learning: Setup

- Given instances $\{x^{(1)}, x^{(2)}, \dots, x^{(n)}\}$
- **Goal:** discover interesting regularities/structures/patterns that characterize the instances. For example:
 - clustering
 - anomaly detection
 - dimensionality reduction

Clustering: Setup

- Given instances $\{x^{(1)}, x^{(2)}, \dots, x^{(n)}\}$
- **Goal:** model h divides the training set into clusters with
 - intra-cluster similarity
 - inter-cluster dissimilarity
- Clustering *irises*:

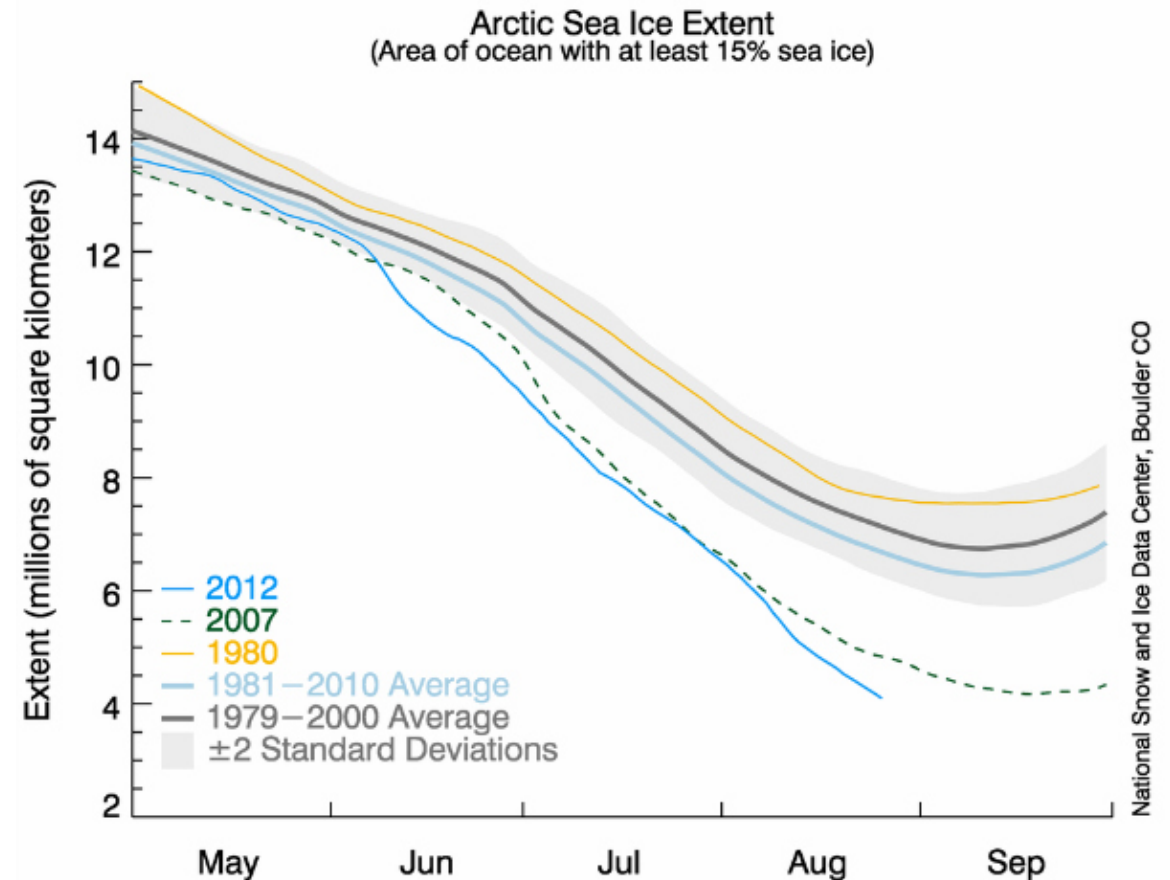


Anomaly Detection: Setup

- Given instances $\{x^{(1)}, x^{(2)}, \dots, x^{(n)}\}$
- **Goal:** model h that represents “normal” x
 - Can apply to new data to find anomalies

Let's say our model is represented by:
1979-2000 average, ± 2 stddev

Does the data for 2012 look anomalous?



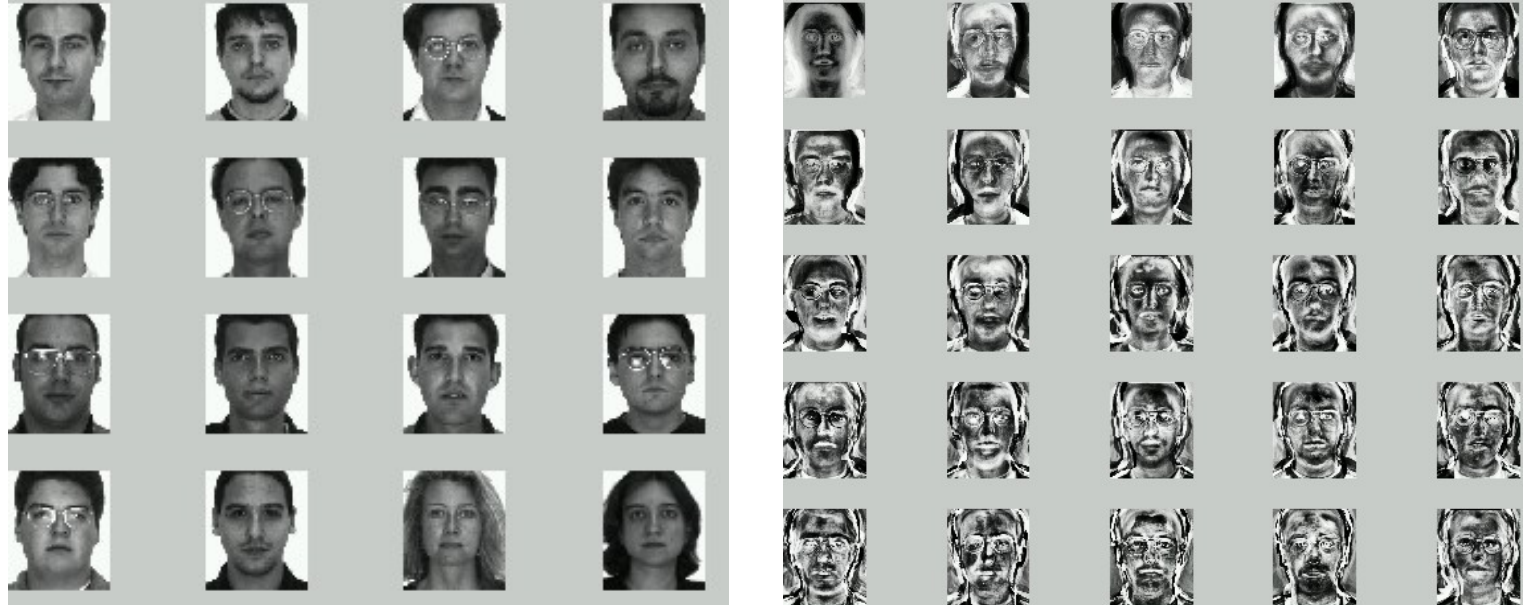
Dimensionality Reduction: Setup

• Given instances $\{x^{(1)}, x^{(2)}, \dots, x^{(n)}\}$

• **Goal:** model h that represents x with

- lower-dim. feature vectors
- preserving information

• Example: Eigenfaces



Dimensionality Reduction: Setup

Example: Eigenfaces

$$\text{Image of a man} = \alpha_1^{(1)} \times \text{Eigenface 1} + \alpha_2^{(1)} \times \text{Eigenface 2} + \dots + \alpha_{20}^{(1)} \times \text{Eigenface 20}$$

$$x^{(1)} = \langle \alpha_1^{(1)}, \alpha_2^{(1)}, \dots, \alpha_{20}^{(1)} \rangle$$

$$\text{Image of a woman} = \alpha_1^{(2)} \times \text{Eigenface 1} + \alpha_2^{(2)} \times \text{Eigenface 2} + \dots + \alpha_{20}^{(2)} \times \text{Eigenface 20}$$

$$x^{(2)} = \langle \alpha_1^{(2)}, \alpha_2^{(2)}, \dots, \alpha_{20}^{(2)} \rangle$$

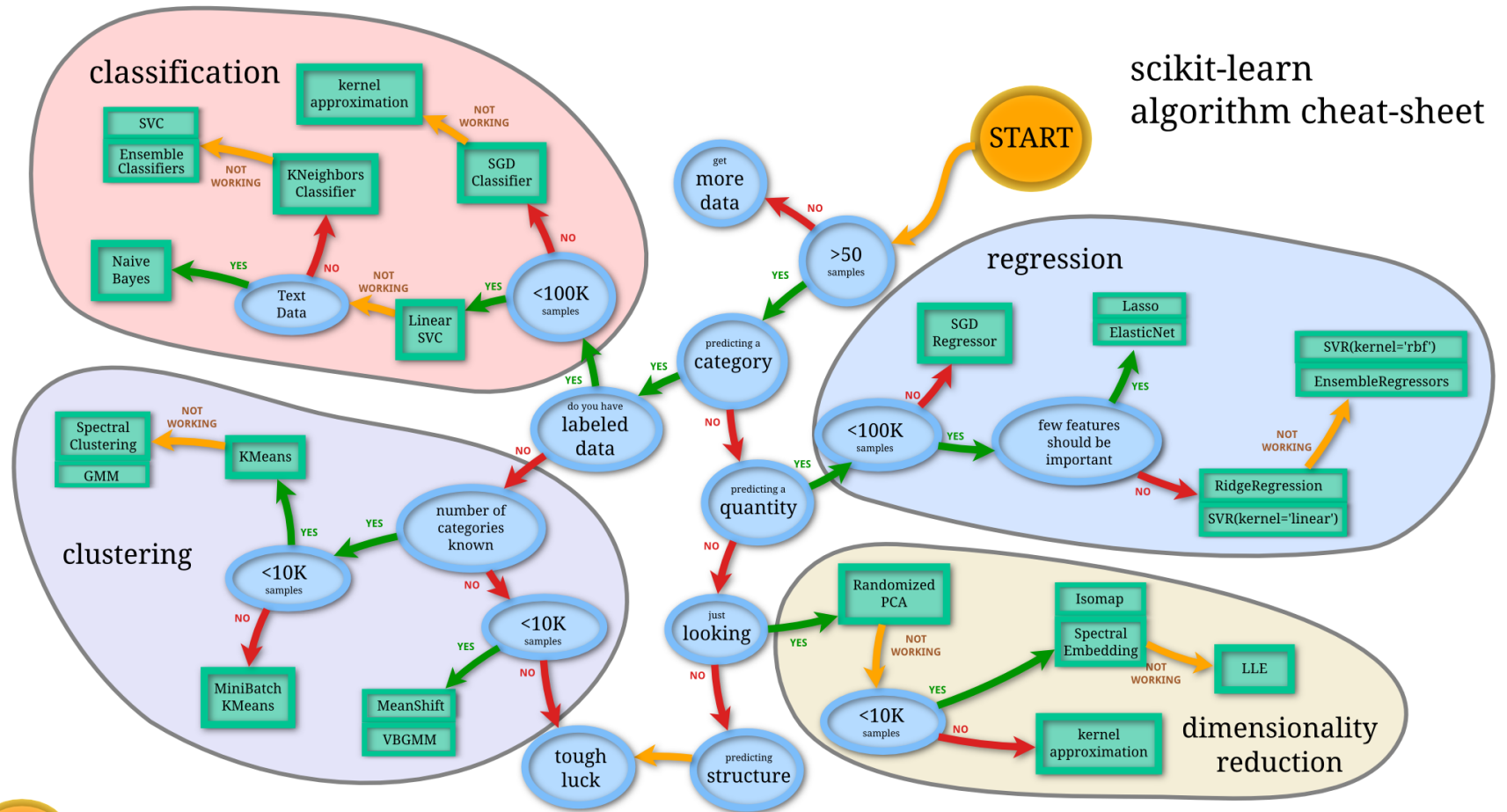
What dimension are we using now?

Q3-1: Which generally is NOT an unsupervised learning task?

1. Principal component analysis
2. Fraud detection
3. CIFAR-10 image classification
4. Community detection

Model Zoo

Lots of models!





Thanks Everyone!

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