

MECHANISM DESIGN FOR COLLABORATIVE NORMAL MEAN ESTIMATION

STANFORD RAIN SEMINAR, APRIL 15, 2024

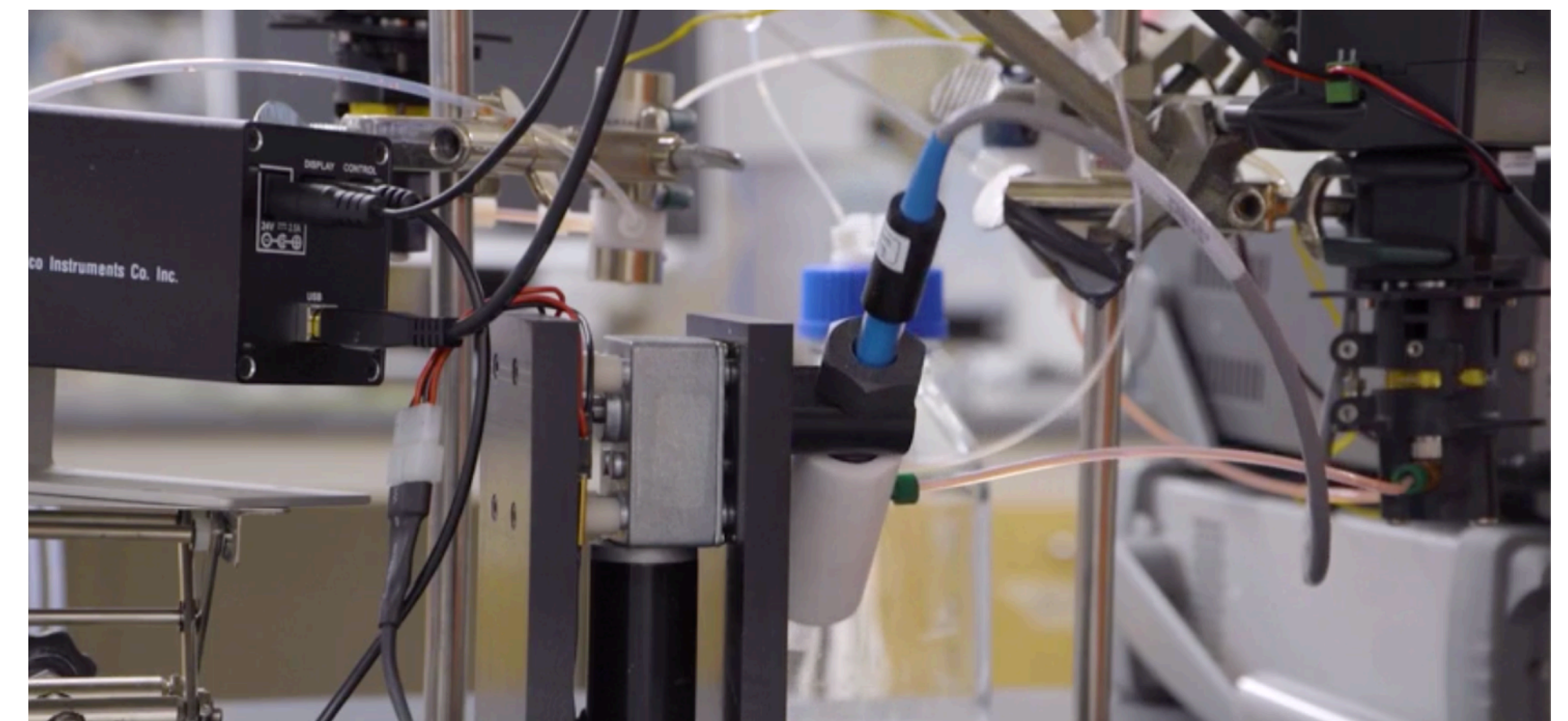
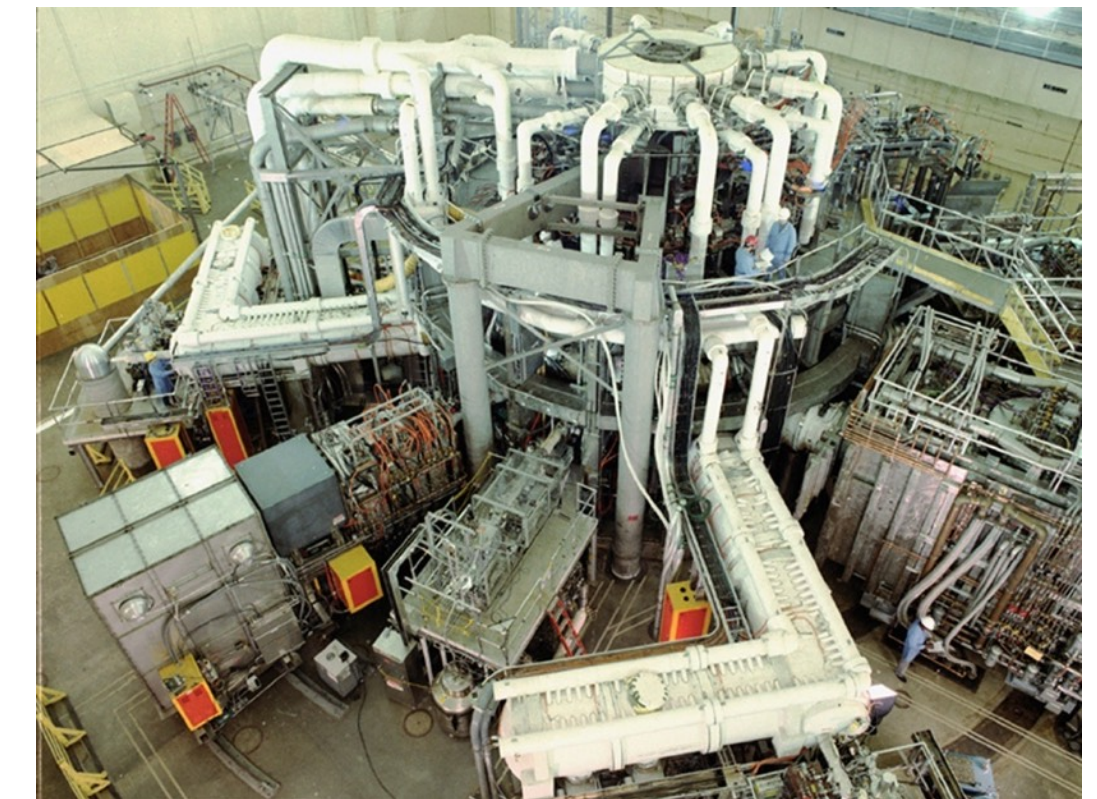
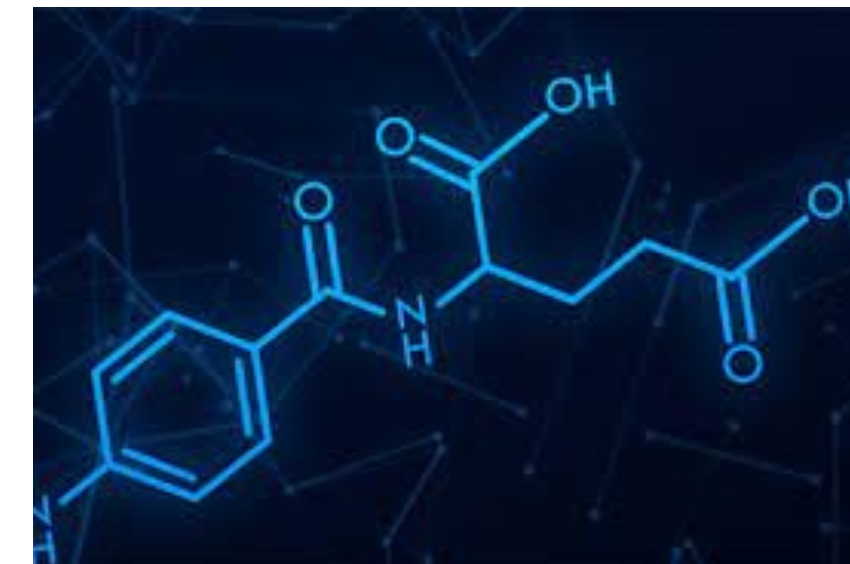
KIRTHEVASAN KANDASAMY

UNIVERSITY OF WISCONSIN-MADISON

BASED ON JOINT WORK WITH: YIDING CHEN, ALEX CLINTON, AND JERRY ZHU

MACHINE LEARNING IS UBIQUITOUS

- ▶ Consumer facing businesses
- ▶ Industrial processes
- ▶ Scientific research
- ▶ Transport/logistics



- ▶ Data is the *new oil*.
- ▶ Data is the *new gold*.

The Economist, NY Times, Forbes, Wired, Deloitte, EY, Boston Consulting Group, and several more ...

- ▶ Data is the *new oil*.
- ▶ Data is the *new gold*.

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- ▶ But data is different to other types of resources
 - ▶ Data is **costly** to produce, but **free** to replicate.

Everyone collects data, everyone shares their data with others.

- Cost incurred by one organization to produce data can benefit others.
- Better for the organizations, better for society at large.



Small organizations with little data:

A B C D E F

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A B C D E F

Large organization with lots of data:

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By sharing data with each other, small organizations can compete with larger organizations.

Ethical/Legal

Privacy

Ownership of data

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Security

Data breaches

Adversarial attacks

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Inter-operability
Communication costs

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Free-riding
Competition
Data monetization
Data valuation

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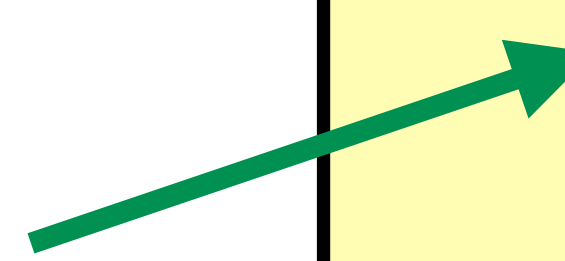
Inter-operability
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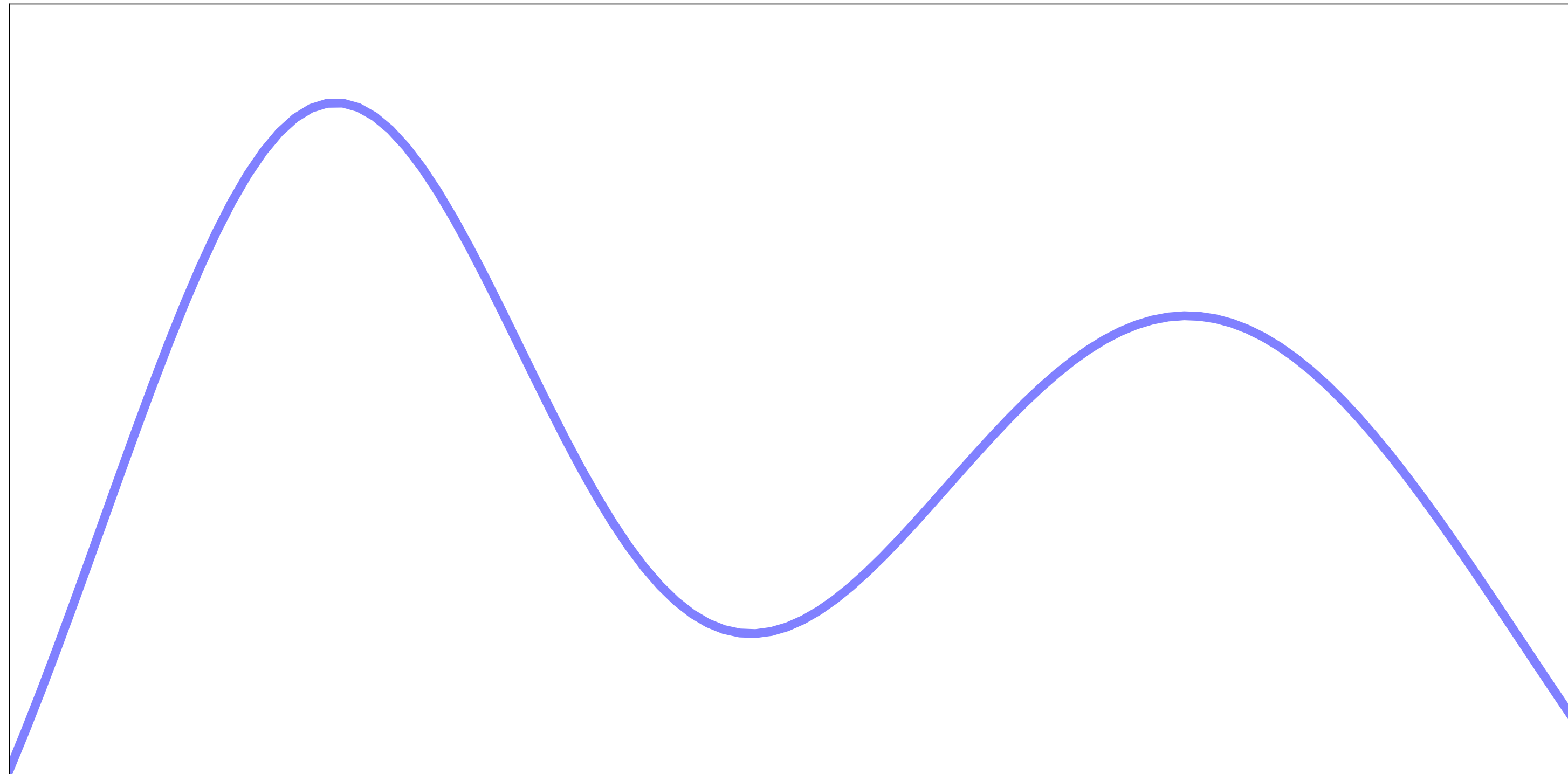
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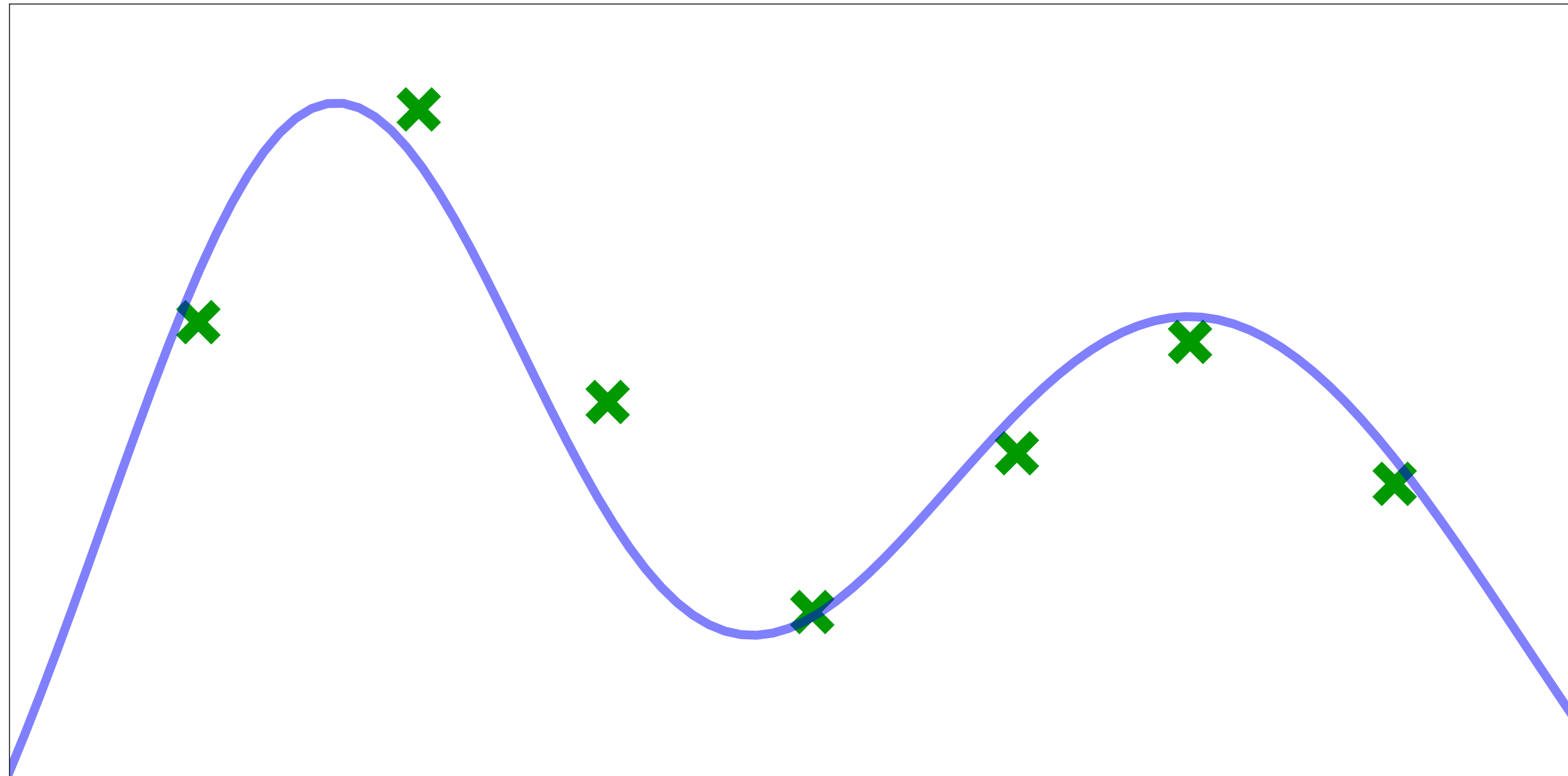
This talk



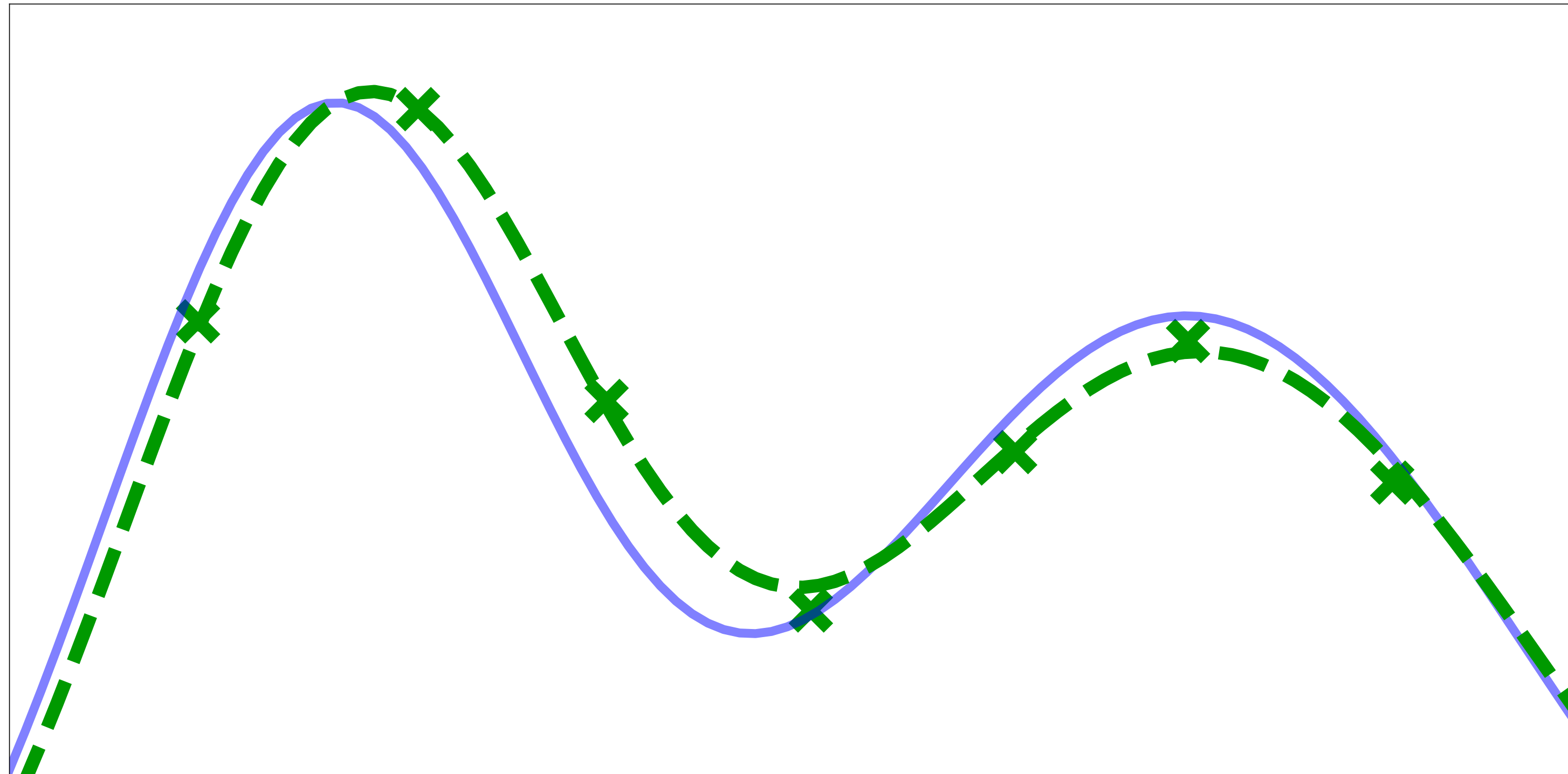
agent's penalty = estimation error + cost of data collection



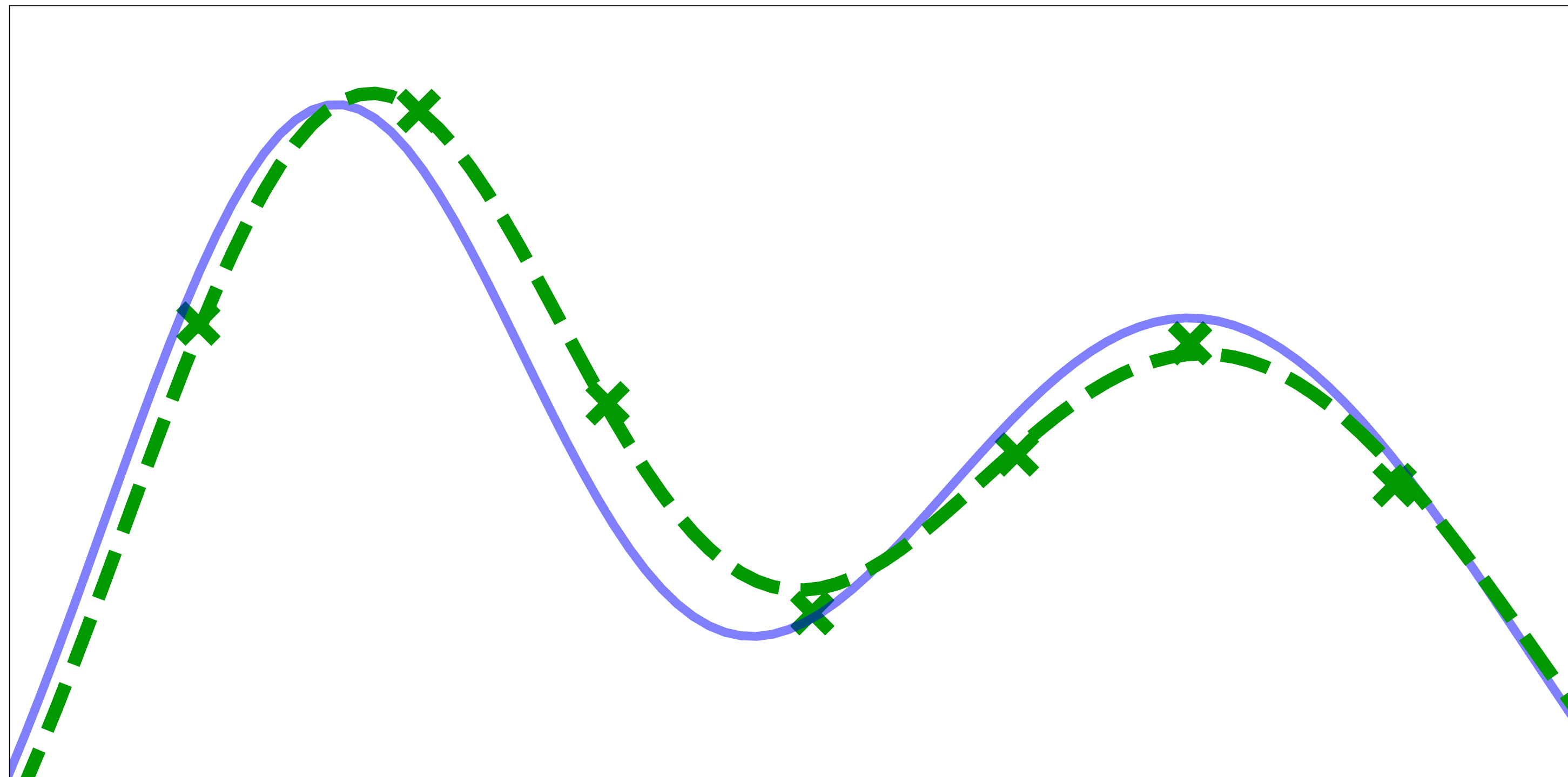
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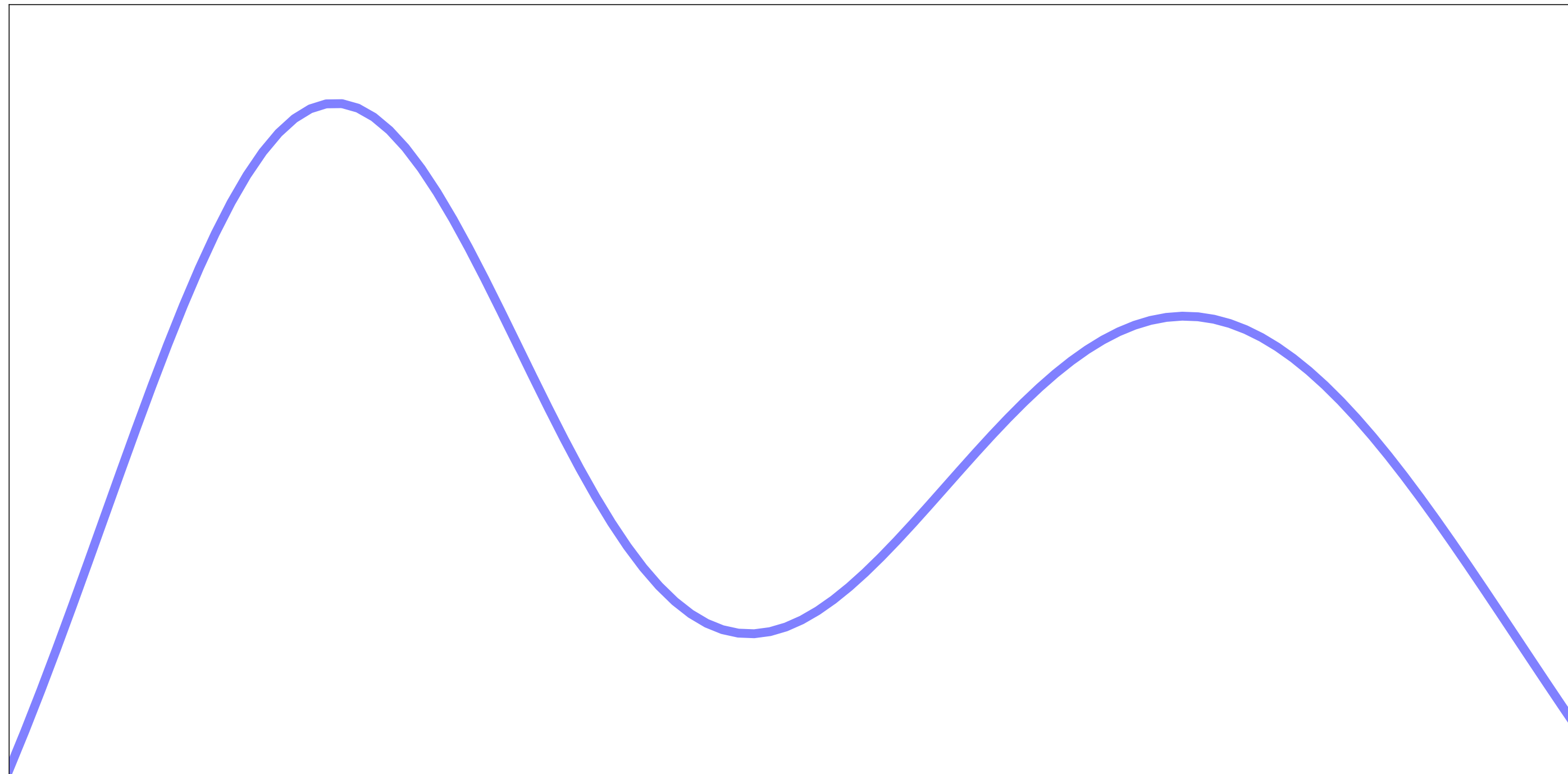
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When **working on her own**, an agent will collect enough data until the cost offsets the (diminishing) increase in value from data.

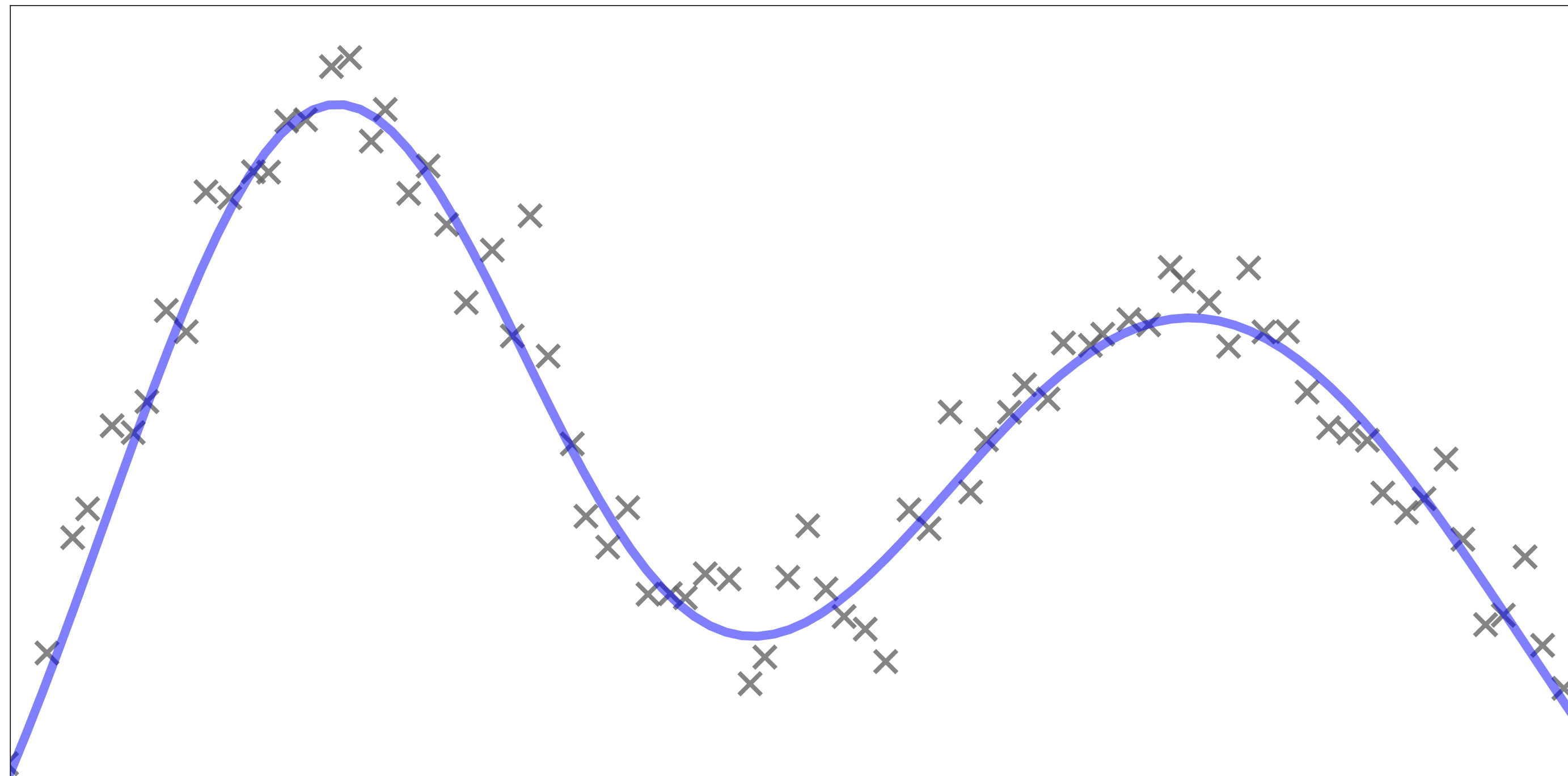
Multiple agents share data via a *naive* pool-and-share protocol:

- ▶ Everyone collects data, everyone gets a copy of the others' data.



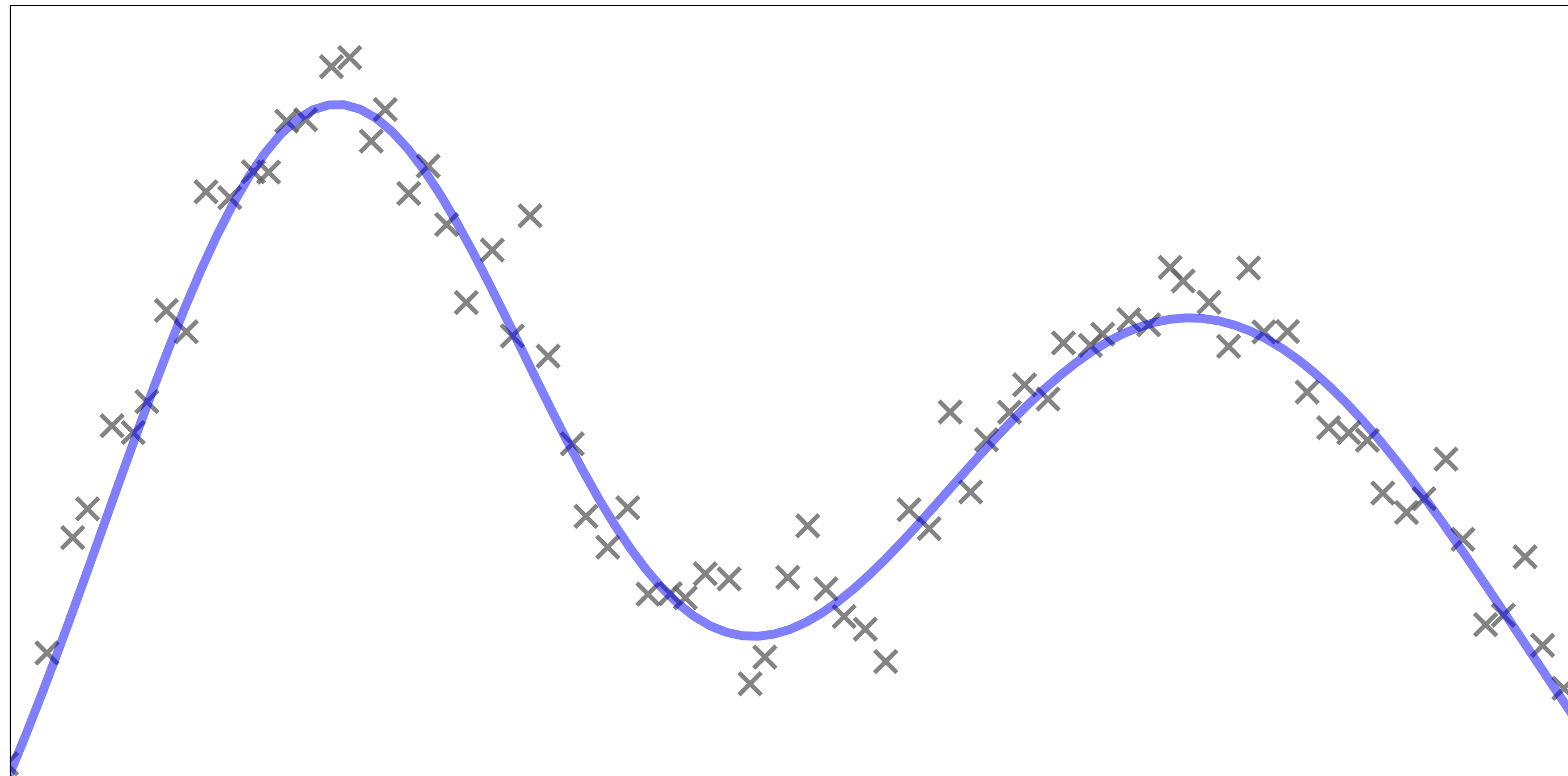
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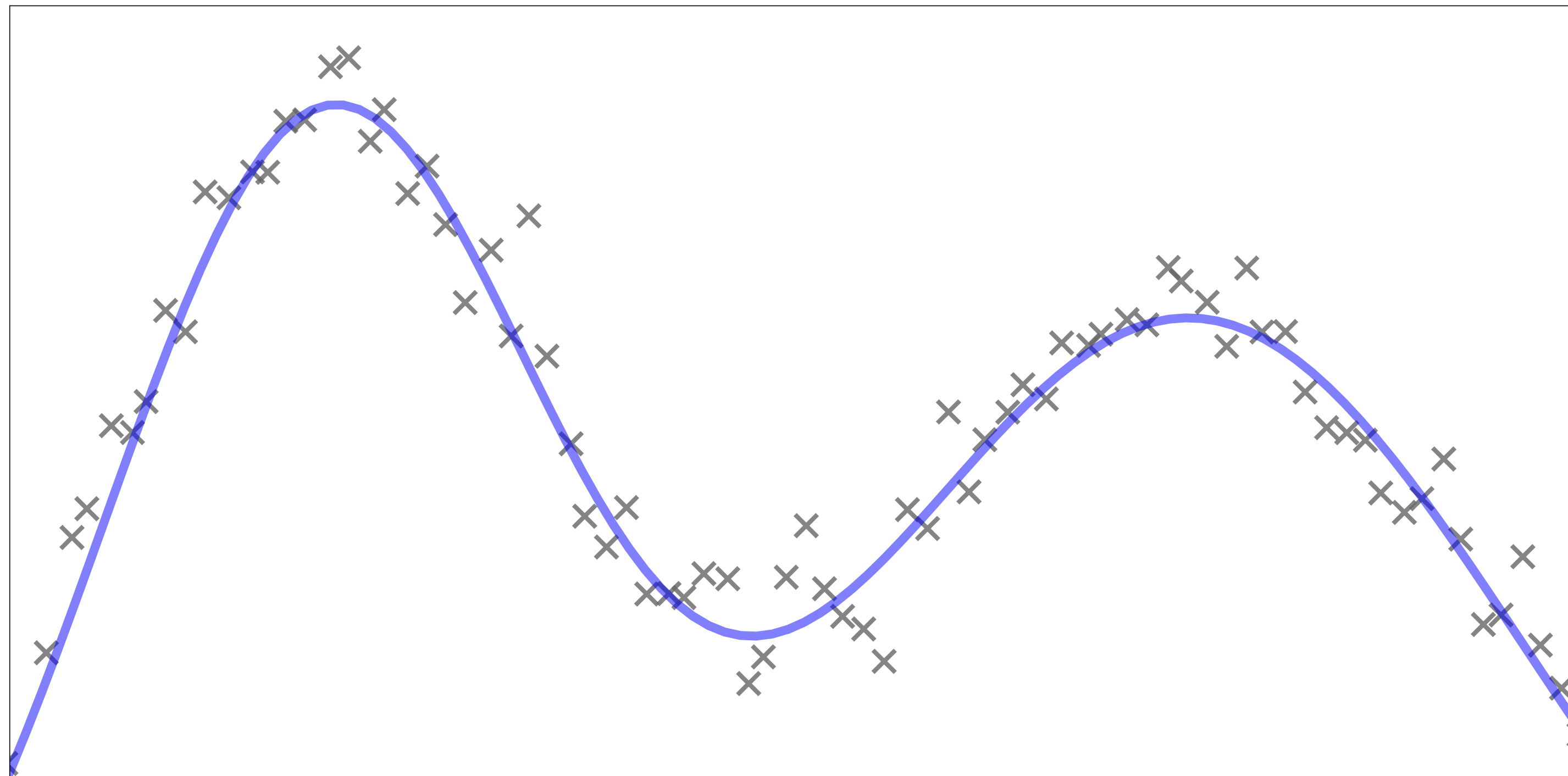
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If others are already contributing large amounts of data, an agent has no incentive to collect/contribute data of her own.

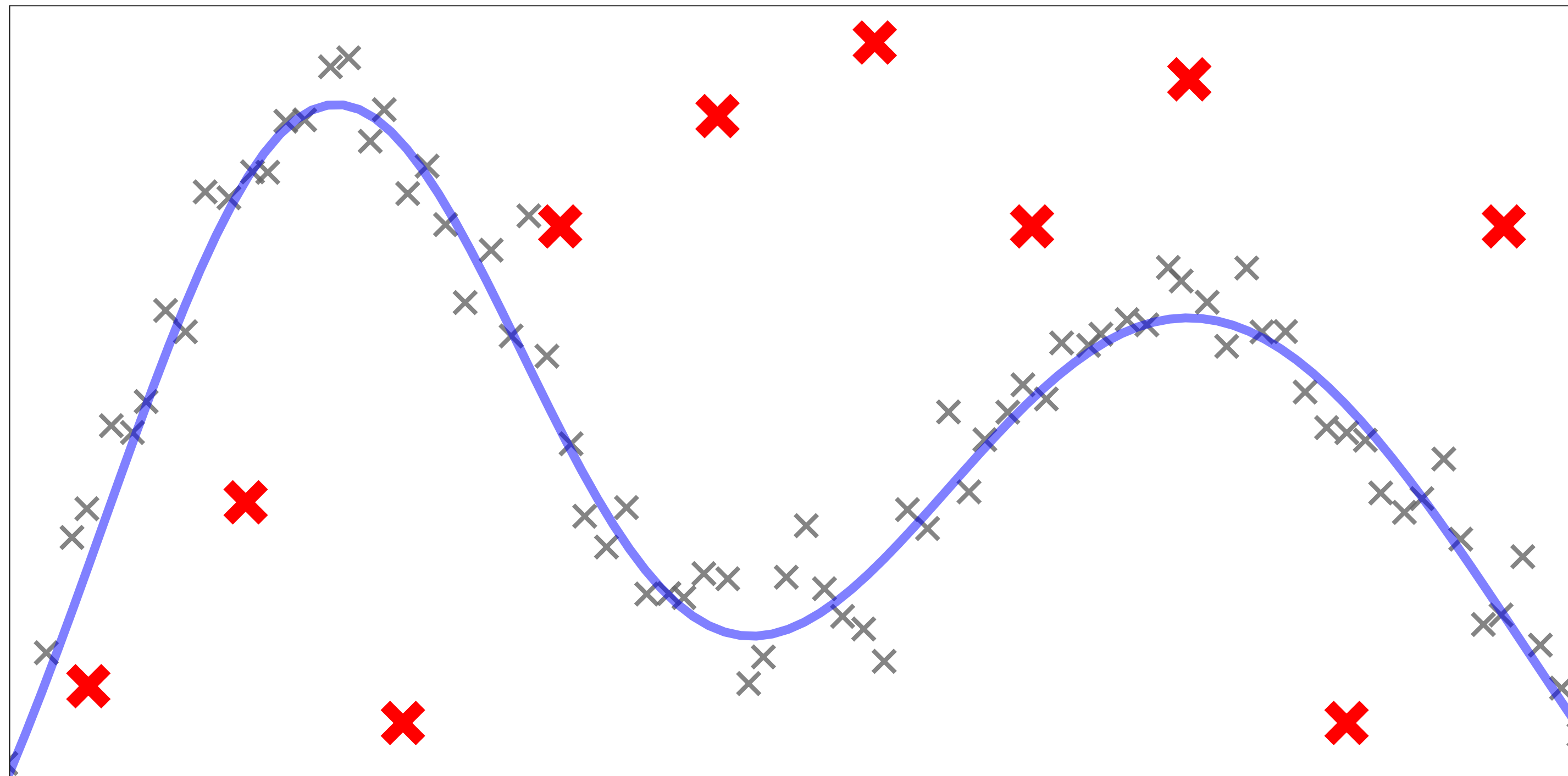
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Pool-and-share but only if the agent contributes sufficient data



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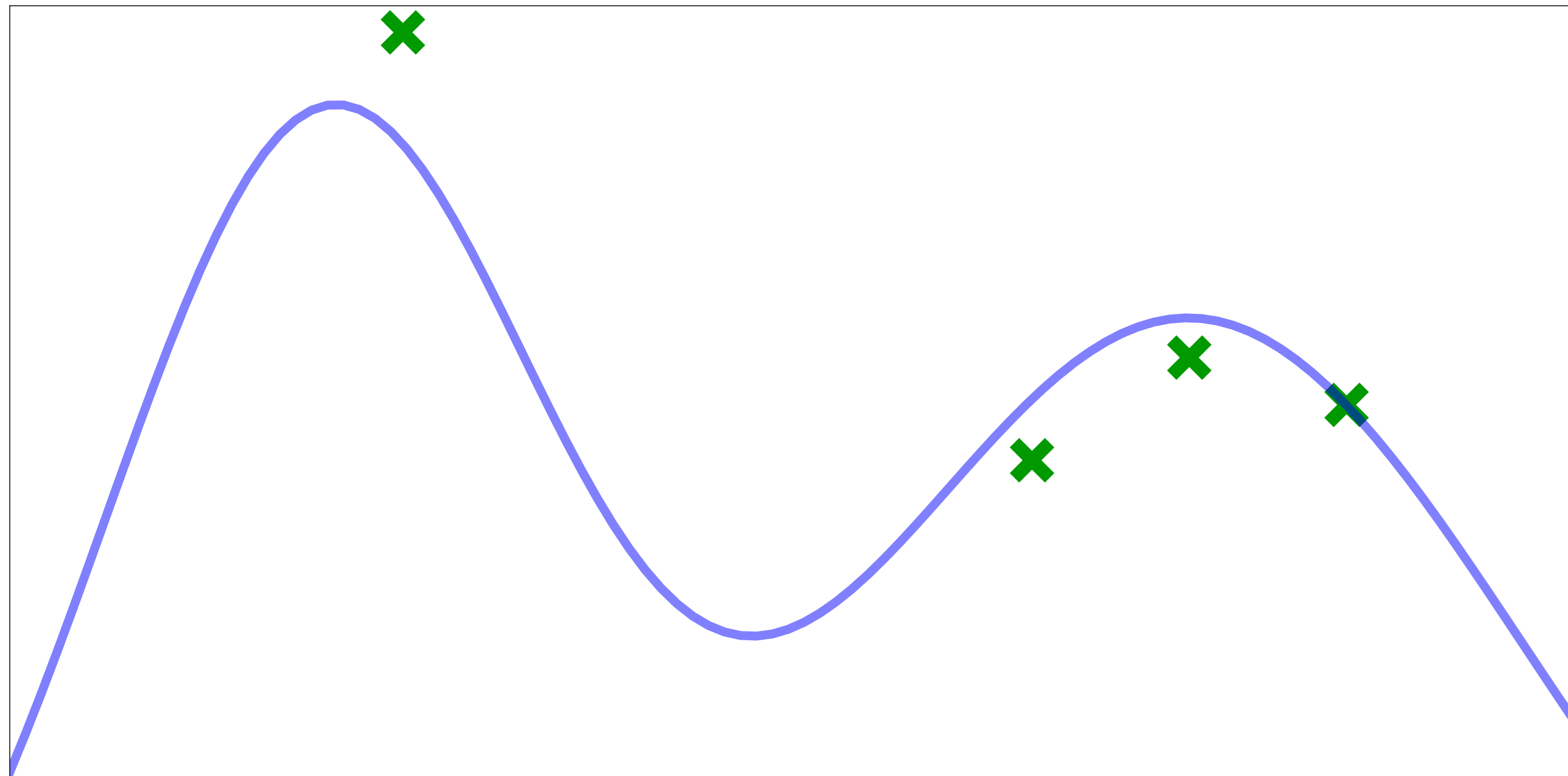
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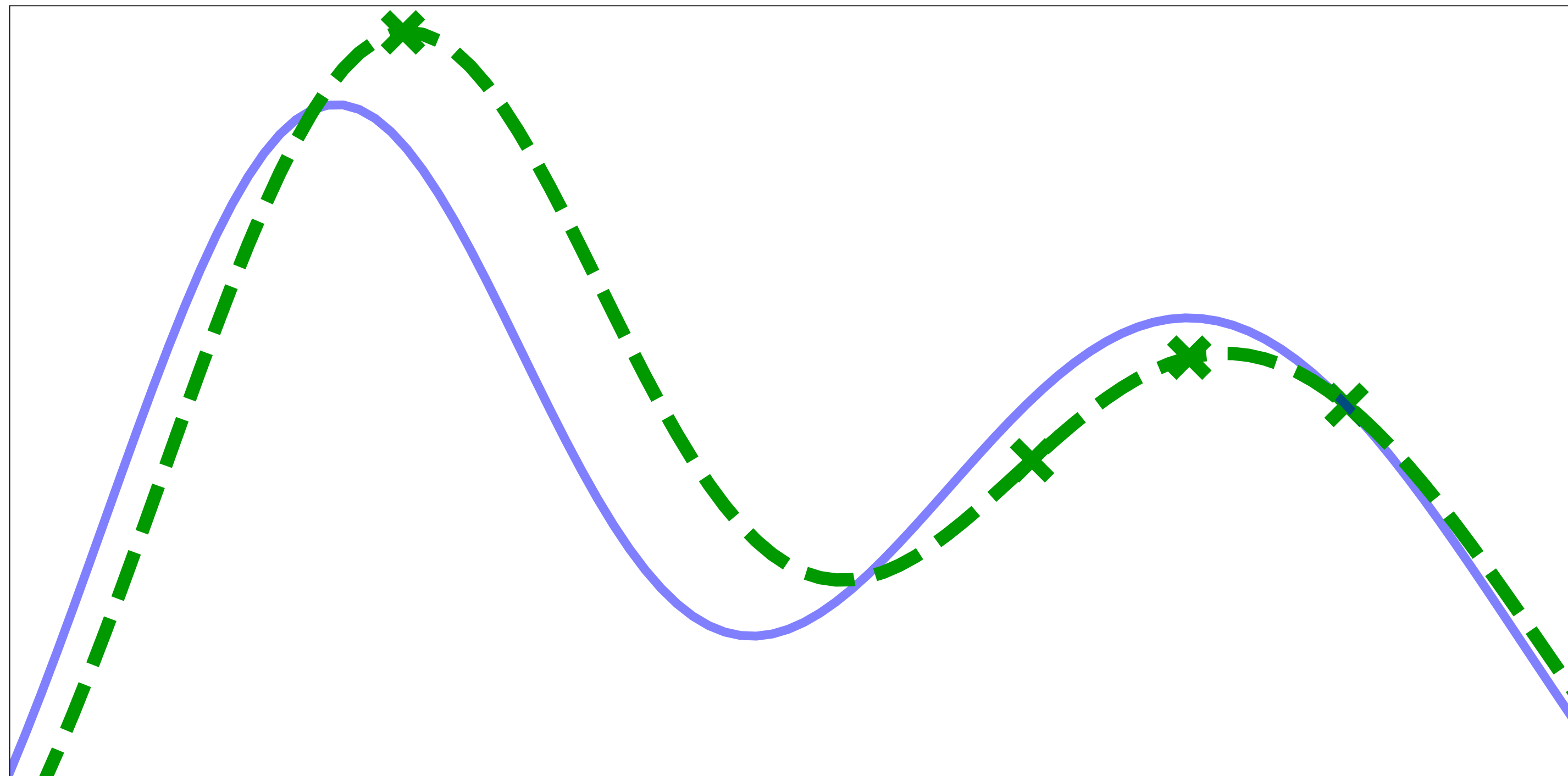
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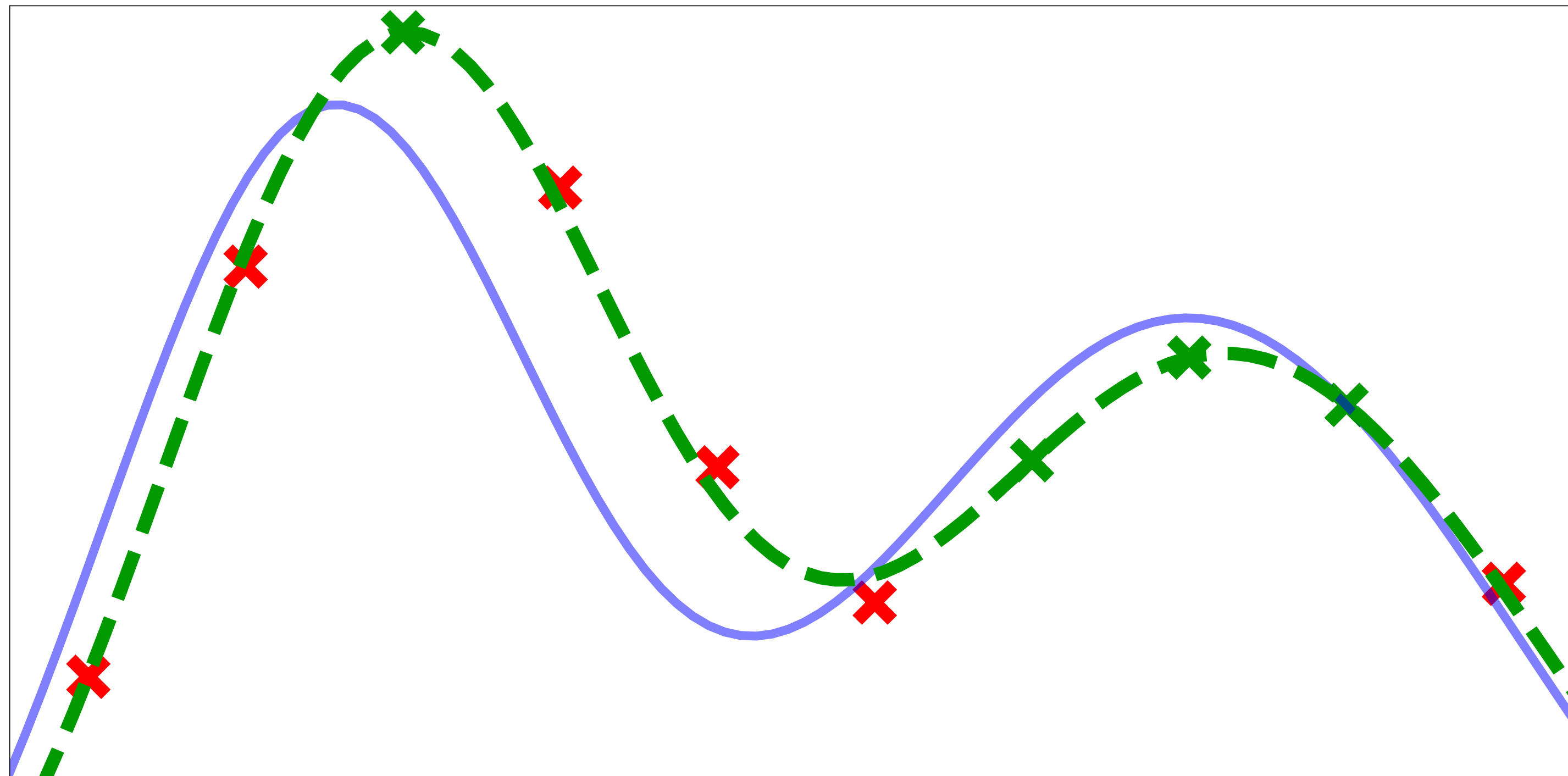
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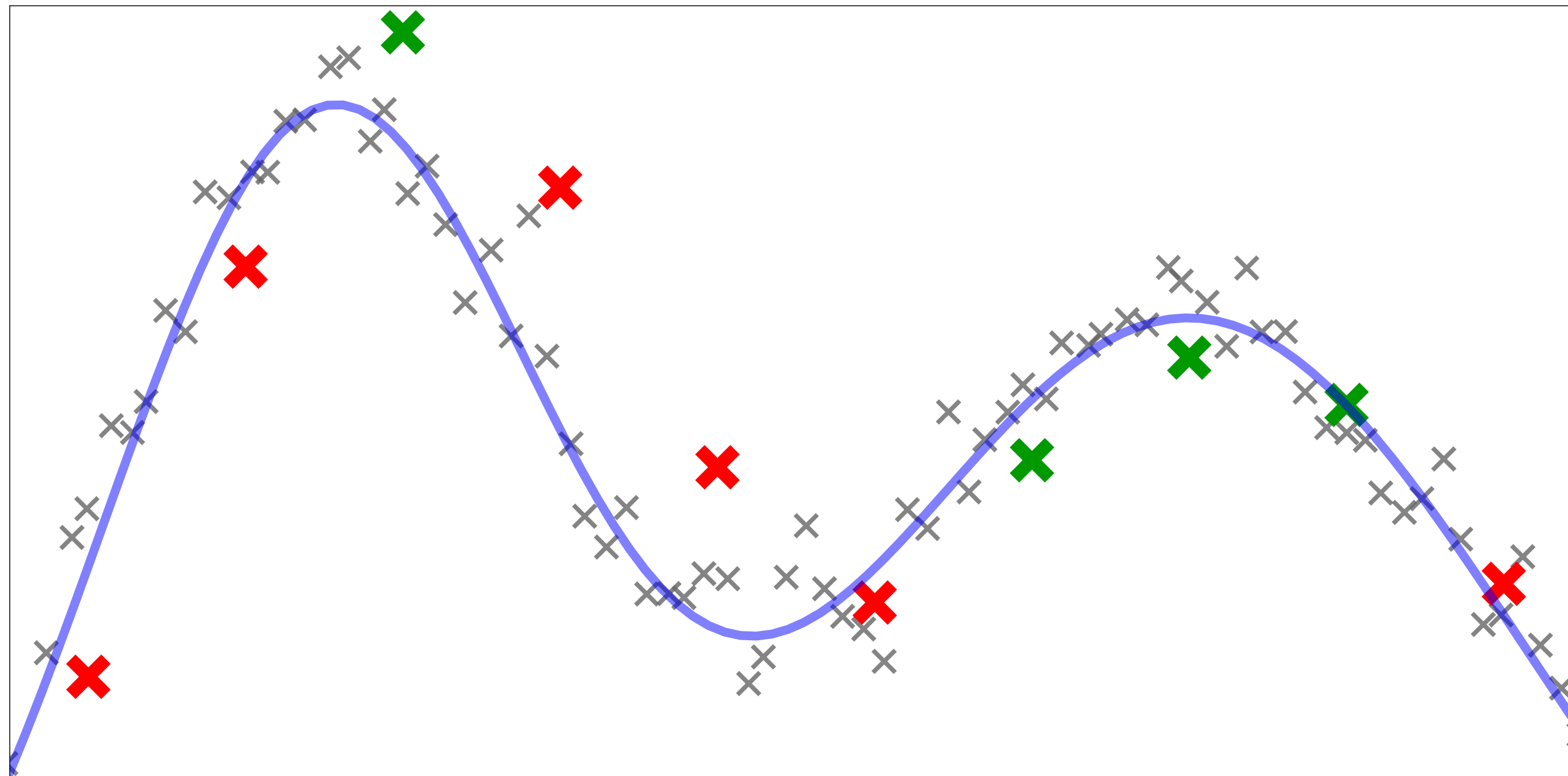
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BUT THERE IS A DEMAND FOR DATA SHARING IN THE REAL WORLD

Data sharing platforms/consortia

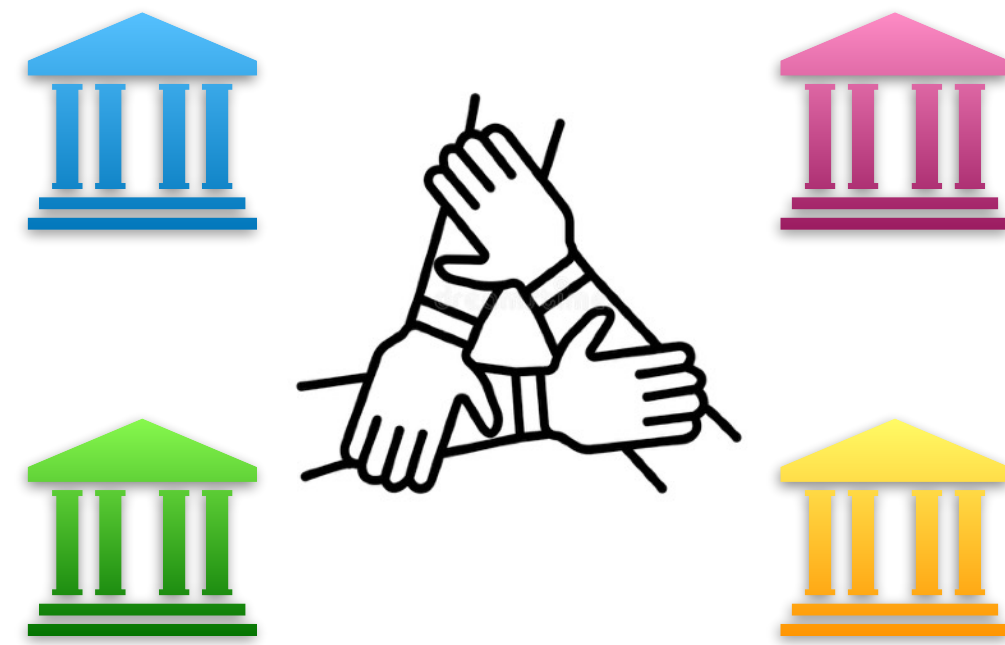


An open standard for secure data sharing

Marketplaces for data and ML models

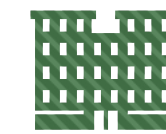


Mechanisms for data sharing and federated learning



Data marketplaces

Contributors



Marketplace

Consumers



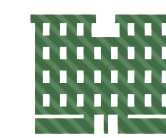
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Goal: Incentivize agents to collect as much data and share it honestly.

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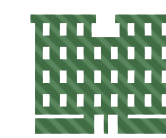


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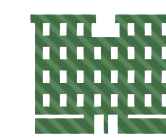


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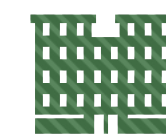


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Goal: Incentivize contributors to honestly contribute lots of data. Fairly reward them for effort via payments from consumers.

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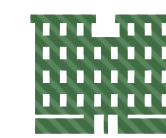


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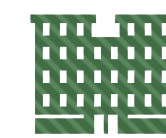


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- A mediator checks for the quality of the data from contributors.
- Higher quality data \implies higher revenue for data contributors.

Mechanisms for data sharing and federated learning

Sim, Zhang, Chan, Low 2020

Xu, Lyu, Ma et al 2021

Blum, Haghtalab, Phillips, Shao 2021

Karimireddy, Guo, Jordan 2022

Fraboni, Vidal, Lorenzi 2021

Lin, Du, Liu 2019

Ding, Fang, Huang 2020

Liu, Tian, Chen et al 2022

Data marketplaces

Cai, Daskalakis, Papadimitriou 2015

Agarwal, Dahleh, Sarkar, 2019

Agarwal, Dahleh, Horel, Rui, 2020

Jia, Dao, Wang et al, 2019

Wang, Rausch, Zhang et al 2020

Key difference:

- ▶ All these works assume agents will always truthfully submit the data they have, i.e without fabrication/alteration.

1. Mechanism design for collaborative normal mean estimation

(Chen, Zhu, Kandasamy, NeurIPS 2023)

- ▶ **Intuitions, overview of results**
- ▶ **Problem formalism**
- ▶ **Mechanism and theoretical analysis**

2. Extensions

(Clinton, Chen, Zhu, Kandasamy, Ongoing work)

- ▶ **Multiple distributions with asymmetric data collection capabilities**
- ▶ **Collaborative supervised learning and experiment design**

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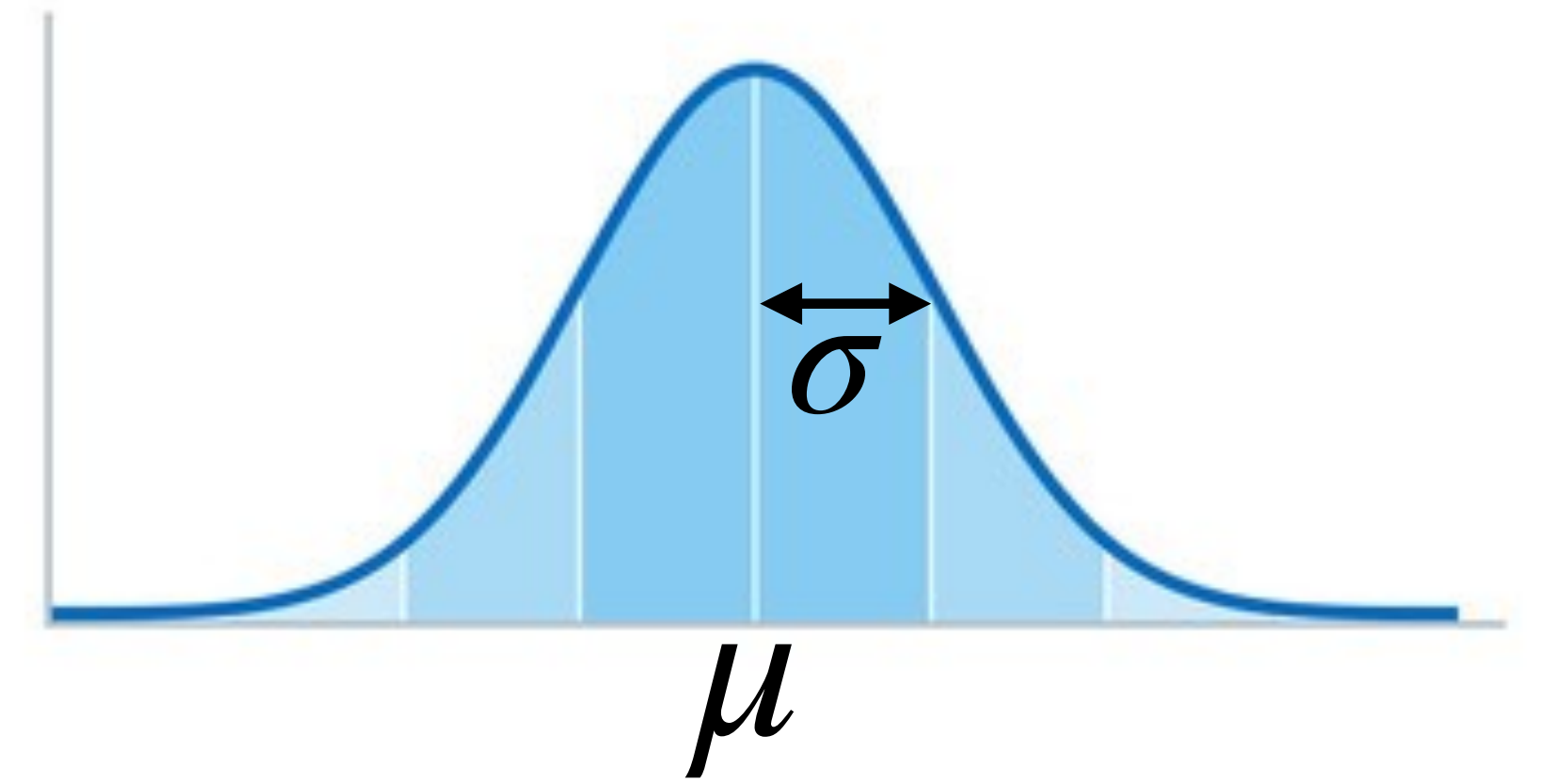
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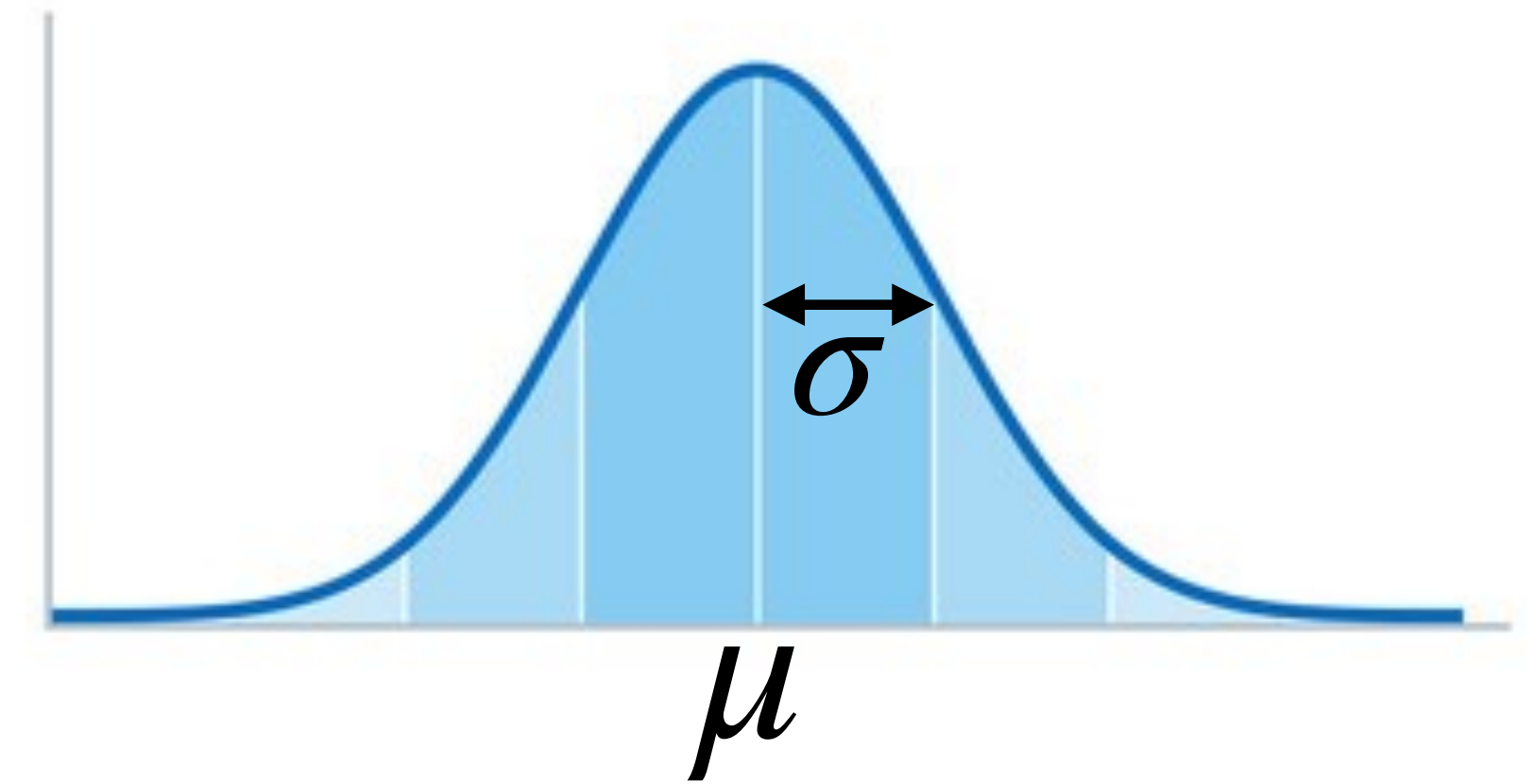
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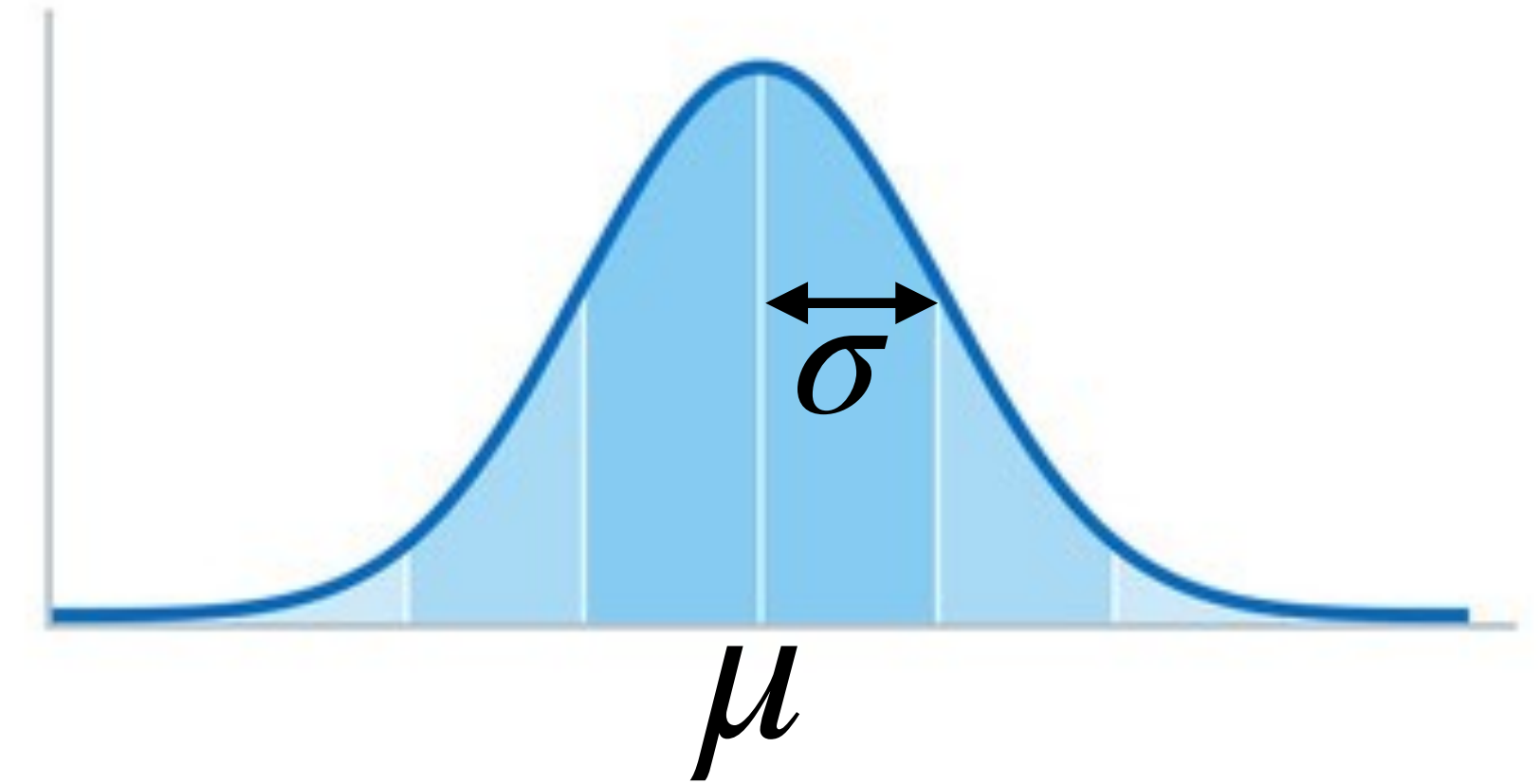
- ▶ Multiple distributions with asymmetric data collection capabilities
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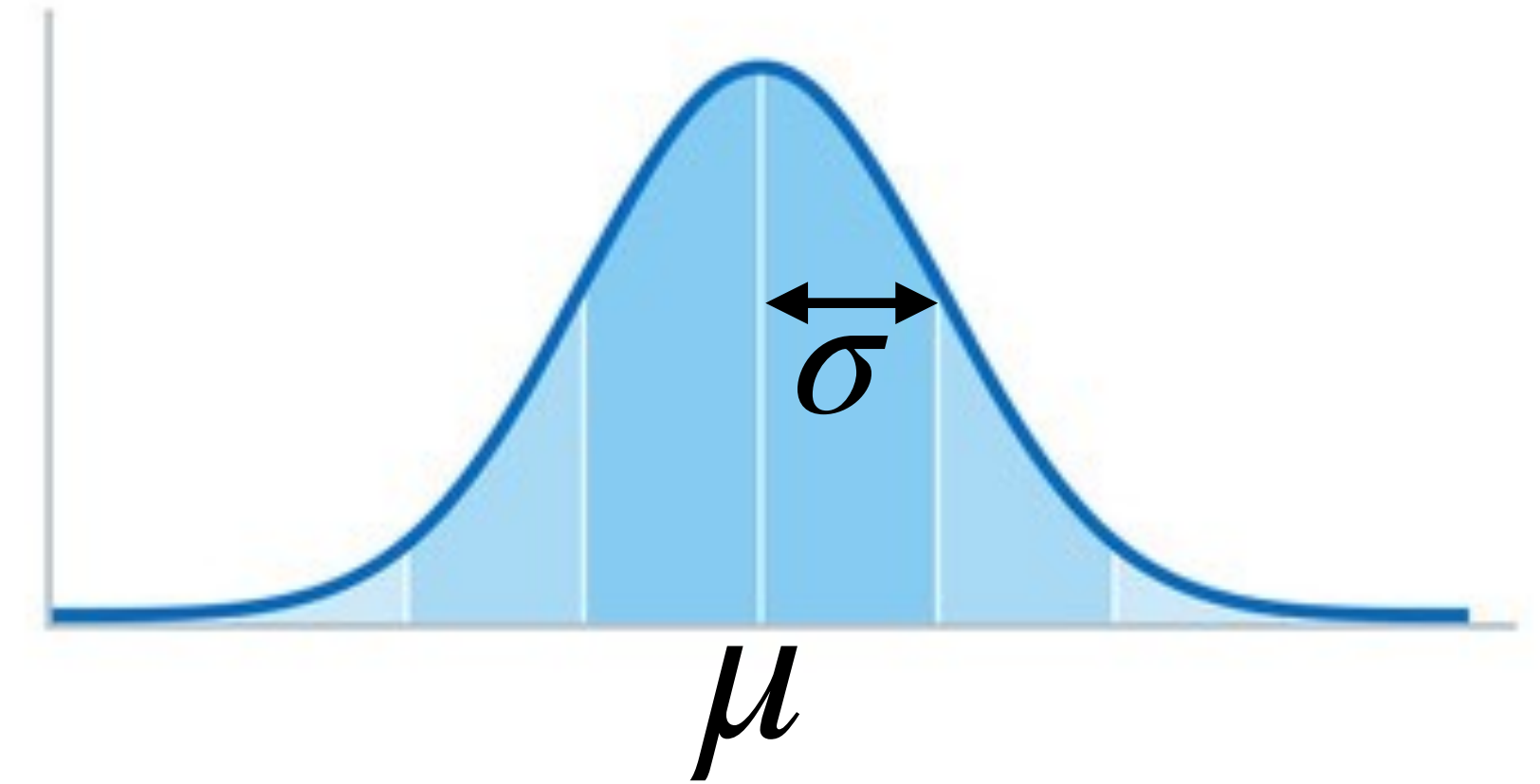
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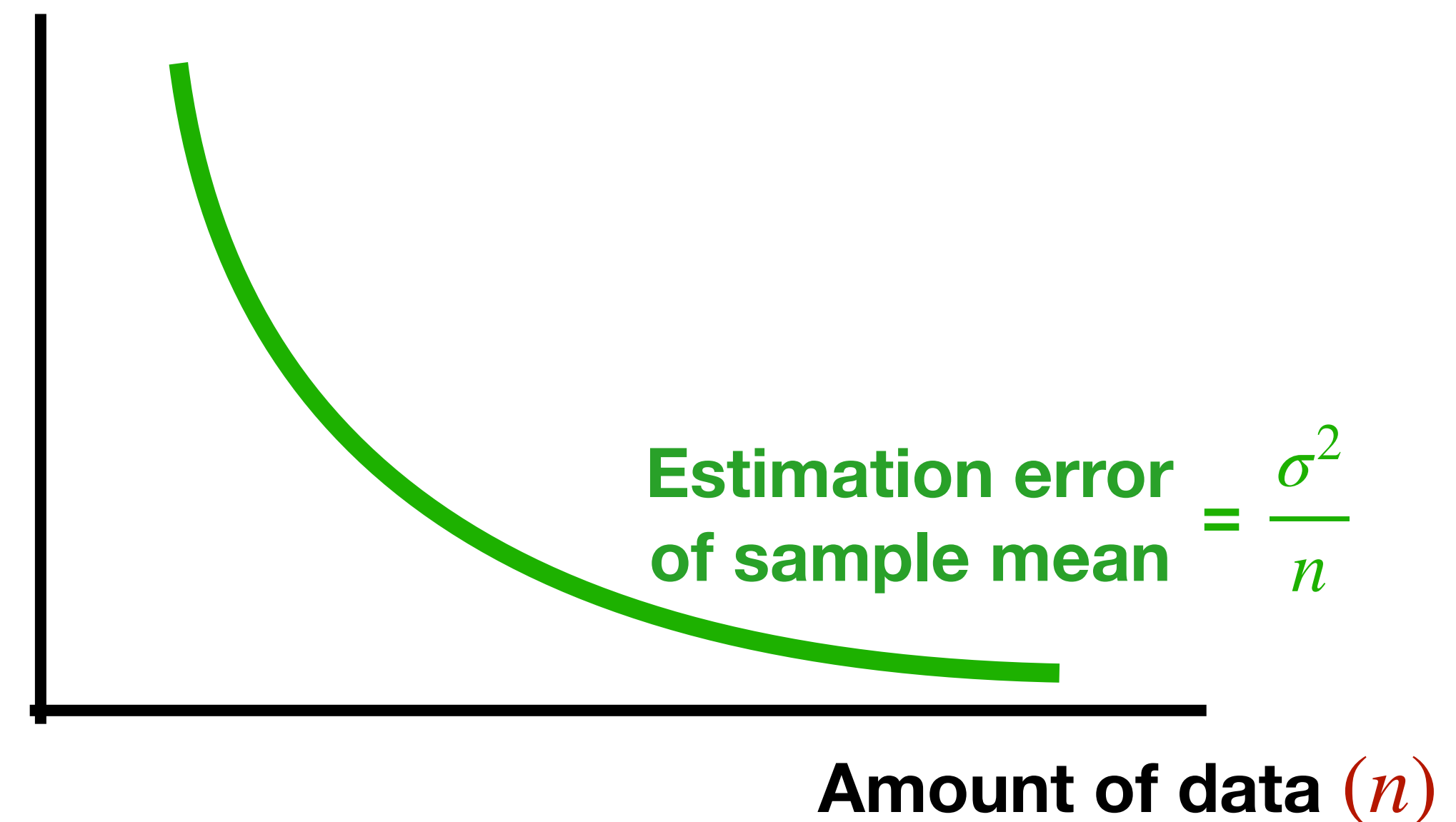
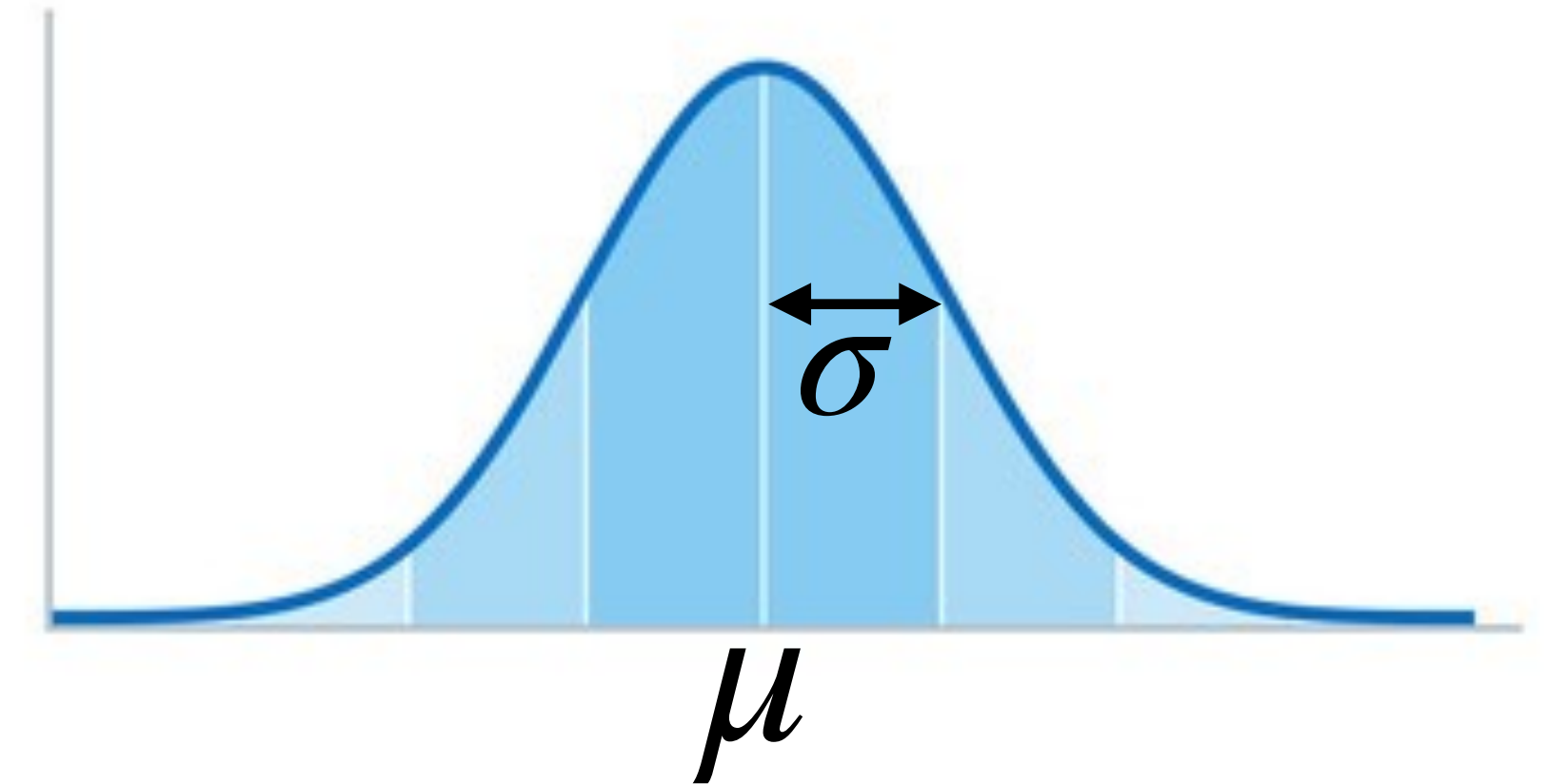
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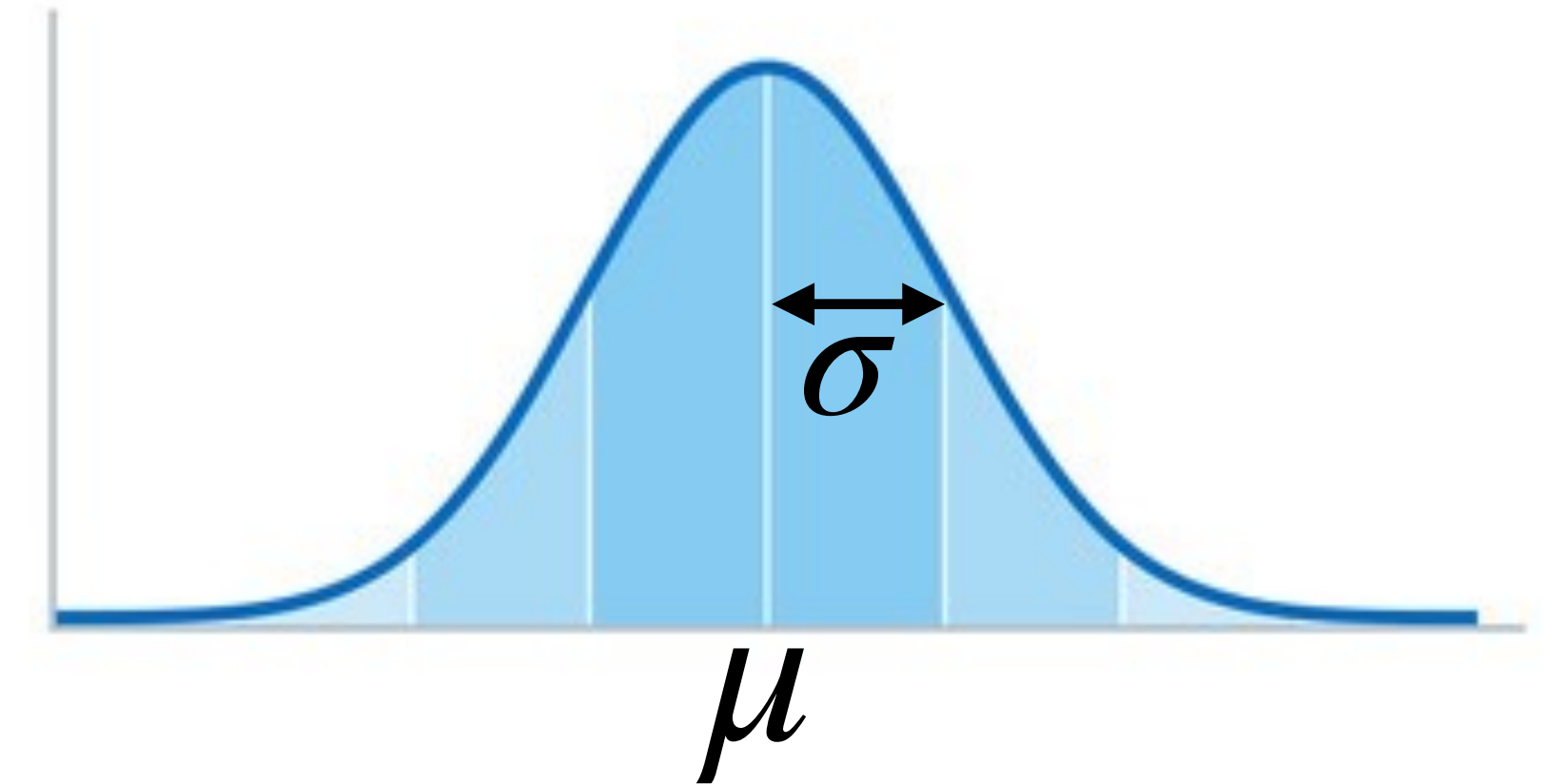
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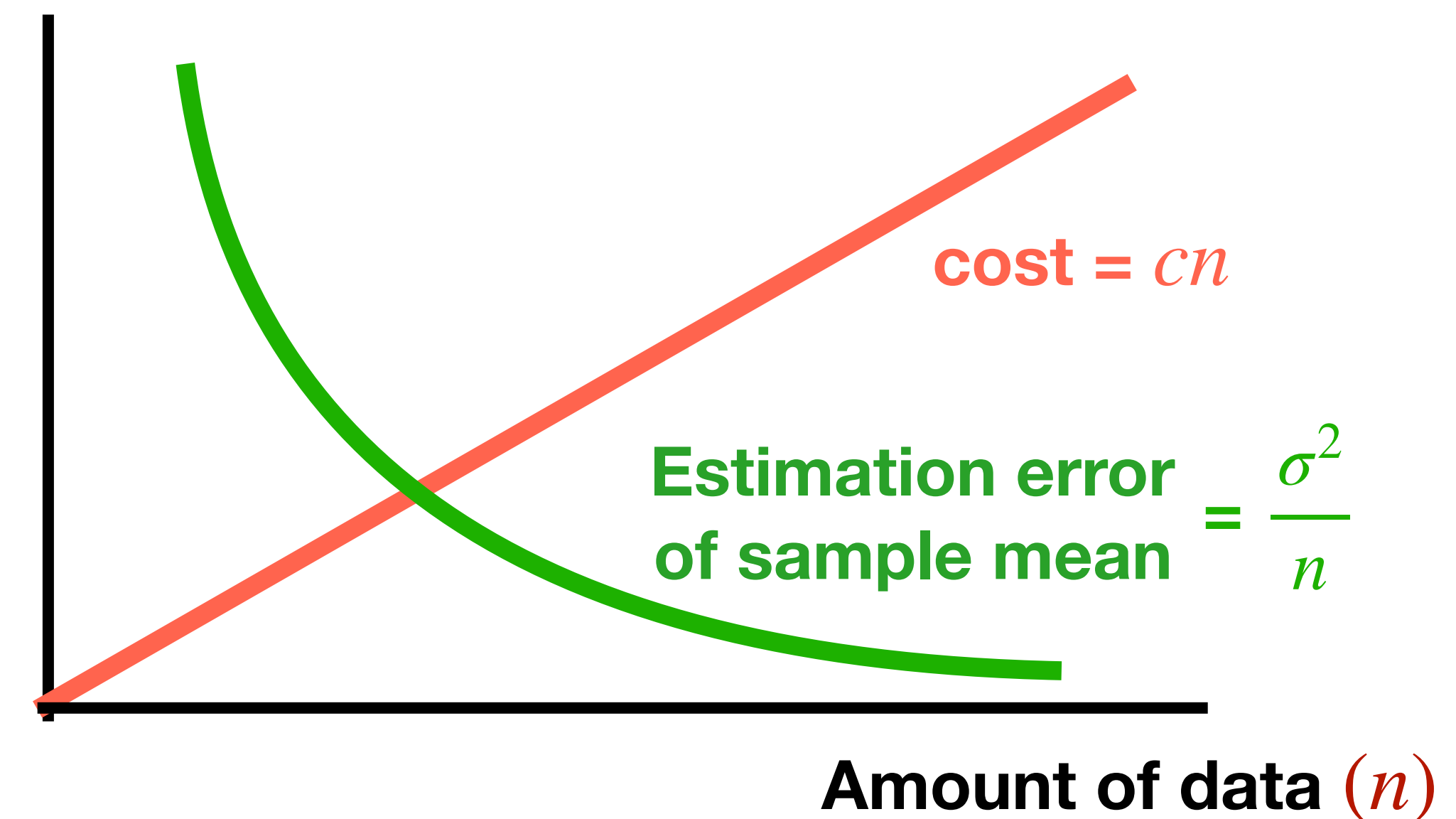


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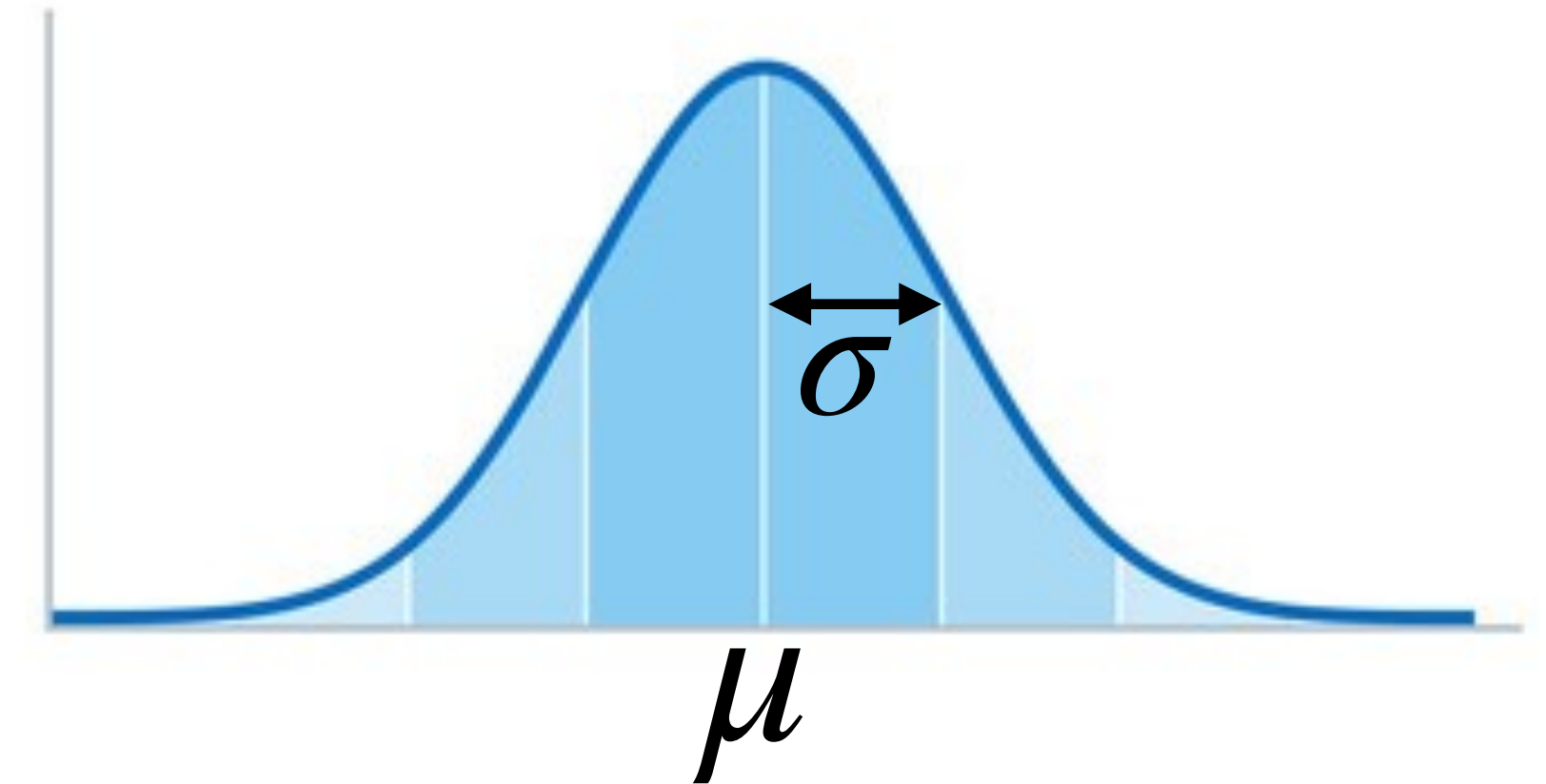


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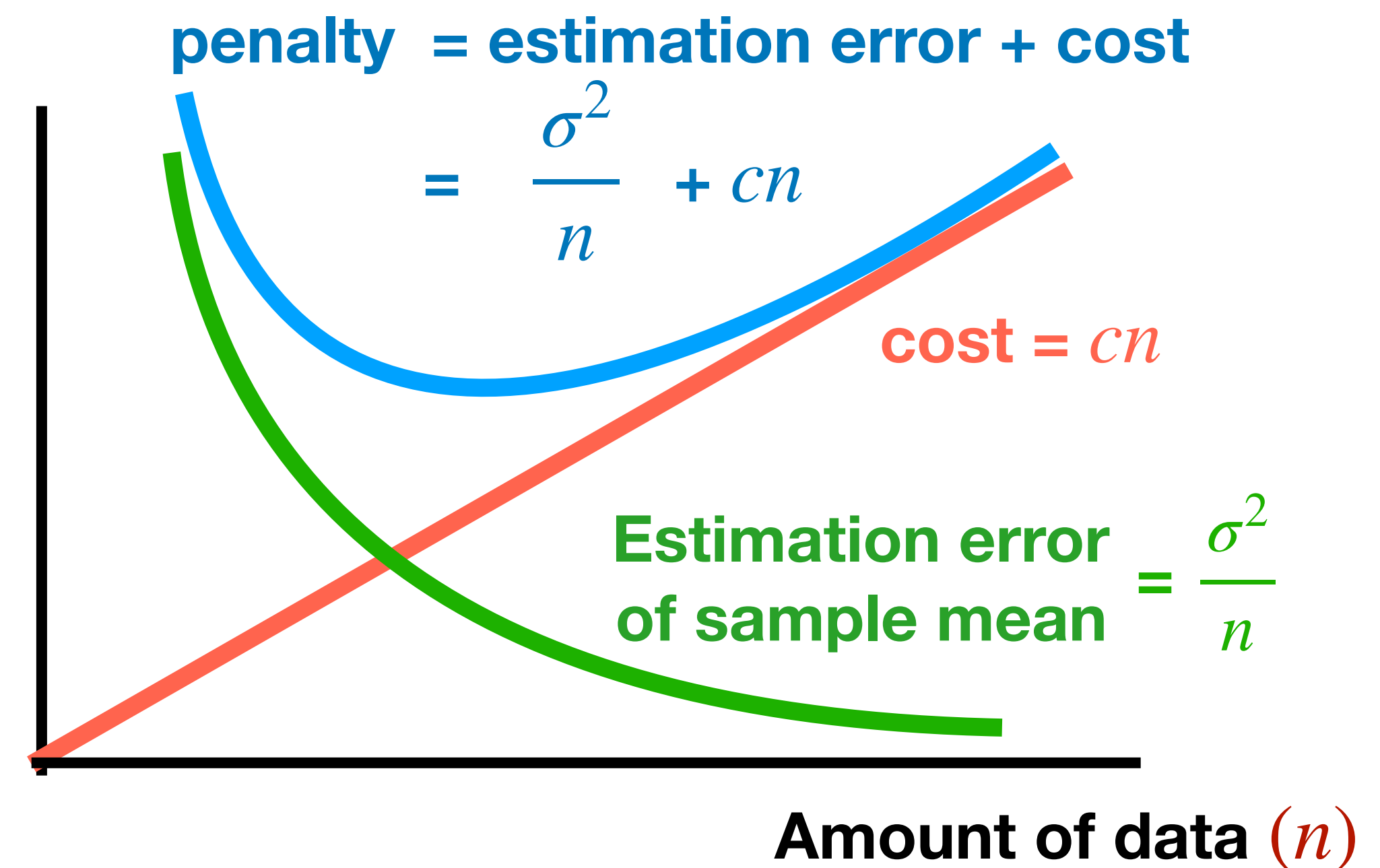


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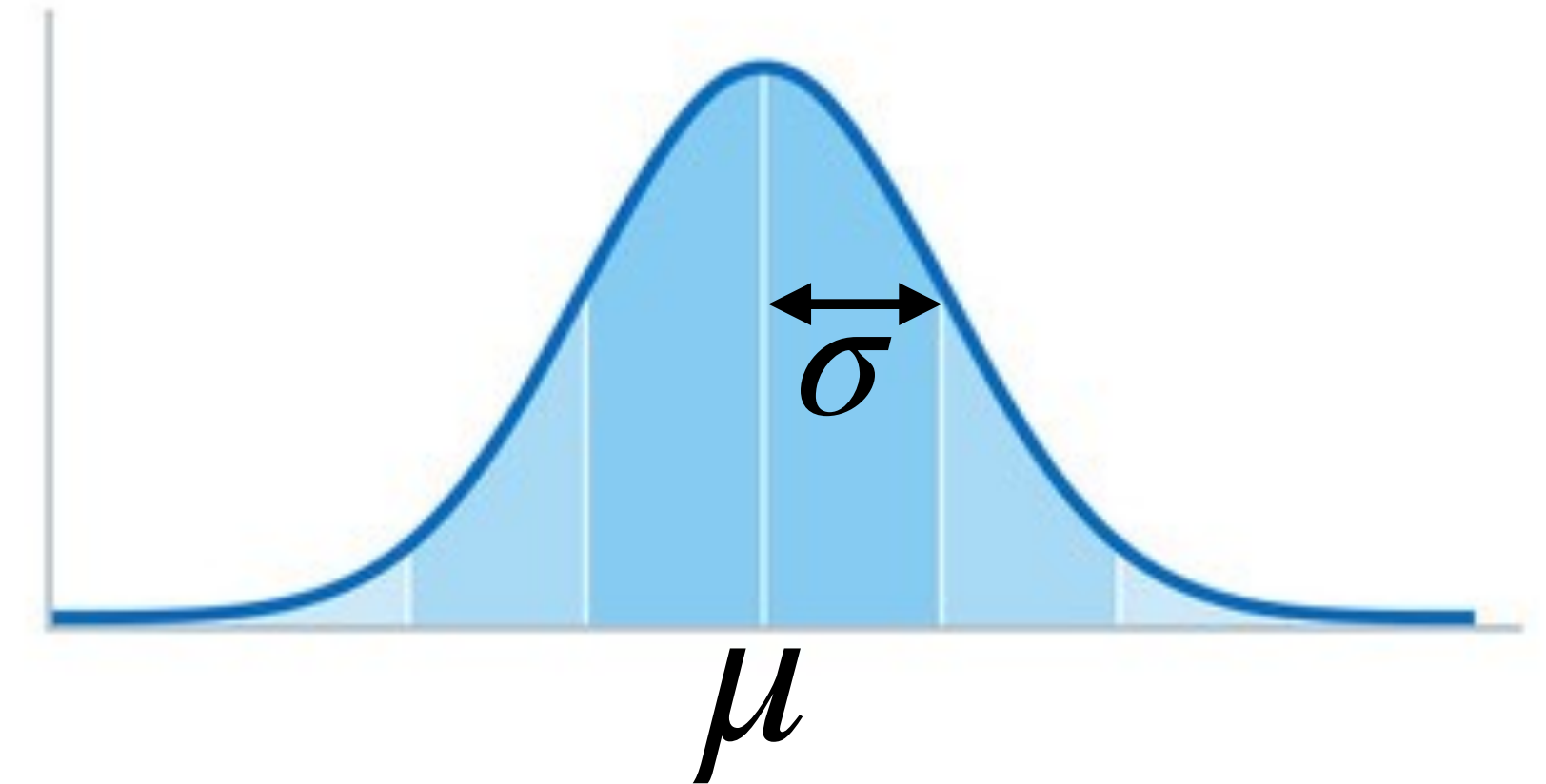


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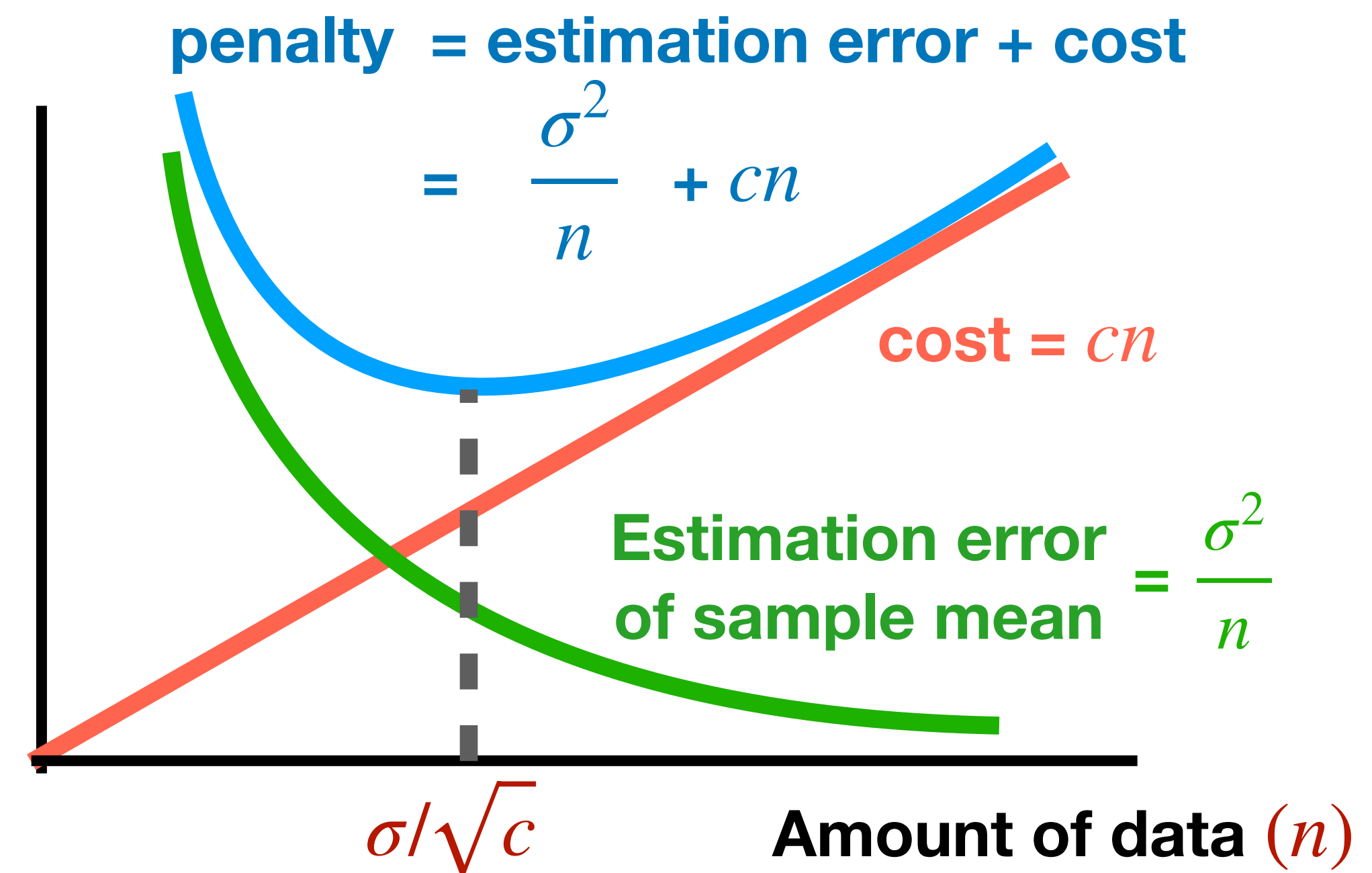
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- When *working on her own*, agent will collect σ/\sqrt{c} points to minimize penalty.



- Now consider m agents collecting and sharing their data.

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- *Social penalty* of all m agents if they collectively collect n_{tot} points.

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Only $\times 1/\sqrt{m}$ when compared to working on her own (σ/\sqrt{c} points).

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- But she has $\times \sqrt{m}$ data.

	Amount of data she needs to collect (n_i)	Amount of data available to her (n_{tot})	Penalty $\frac{\sigma^2}{n_{\text{tot}}} + cn_i$
Working on her own			
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Agents can reduce data collection costs, and improve estimation error by sharing data with others.

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- ▶ Naive mechanism 2: “pool and share, but only if you contribute enough data”
 - ▶ Agents can fabricate and then discard after receiving others’ data.

Each agent i will:

- Collect n_i points $X_i = \{x_{i,1}, \dots, x_{i,n_i}\}$ and submit n'_i points $Y_i = \{y_{i,1}, \dots, y_{i,n'_i}\}$.

Agents may collect any number of points, and lie (e.g withhold, fabricate) about what they collect.

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The mechanism:

- To each agent, allocates a noisy version A_i of the others' data. The noise is proportional to how much the agent's submission Y_i differs from the others' submissions $\{Y_j\}_{j \neq i}$.

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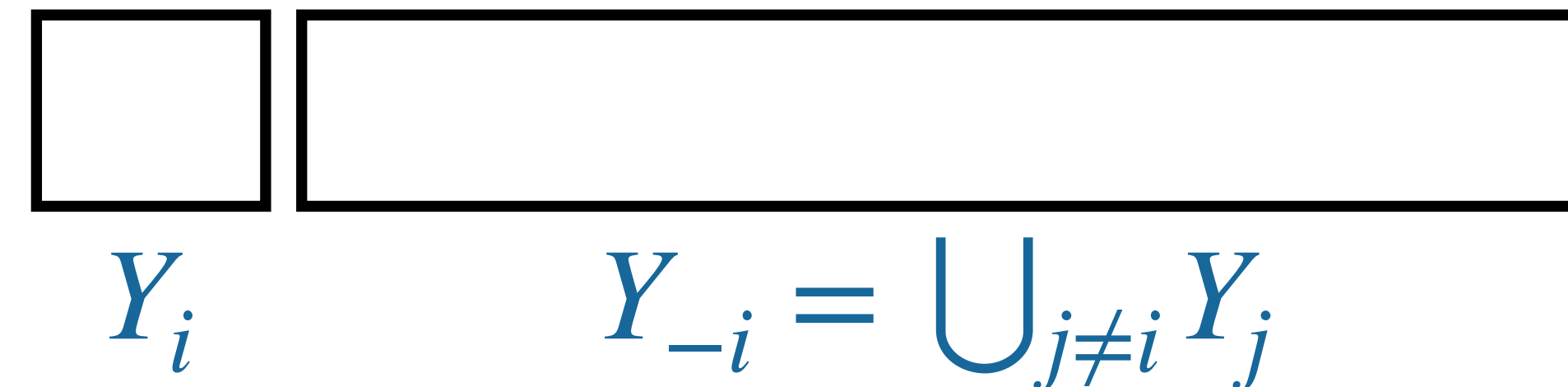
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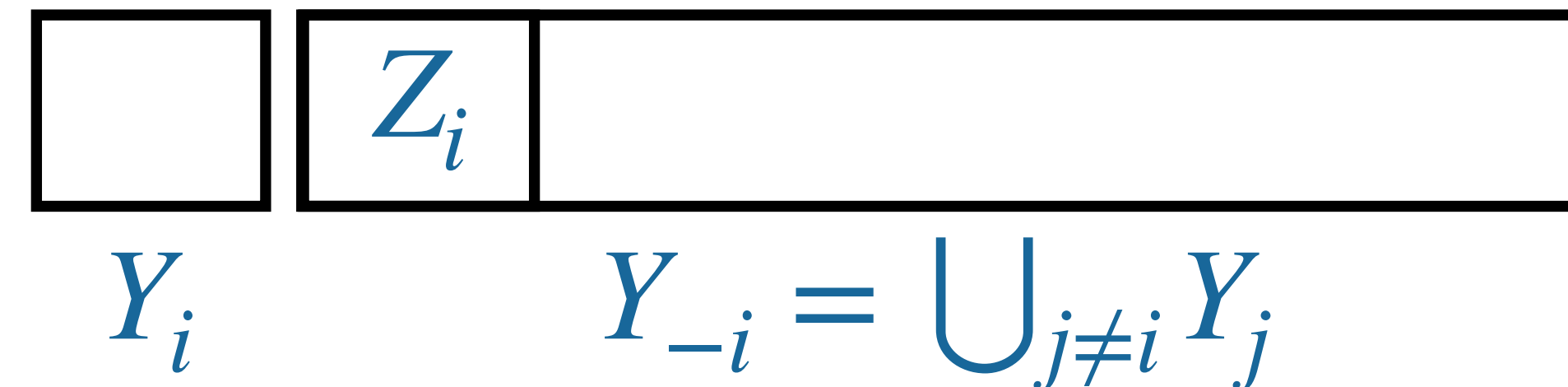


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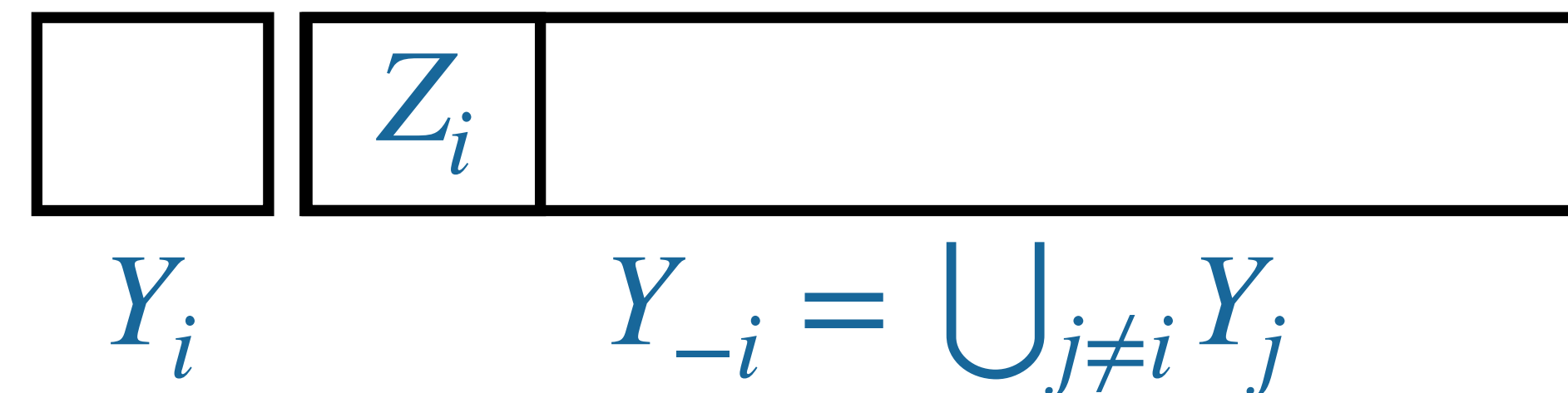


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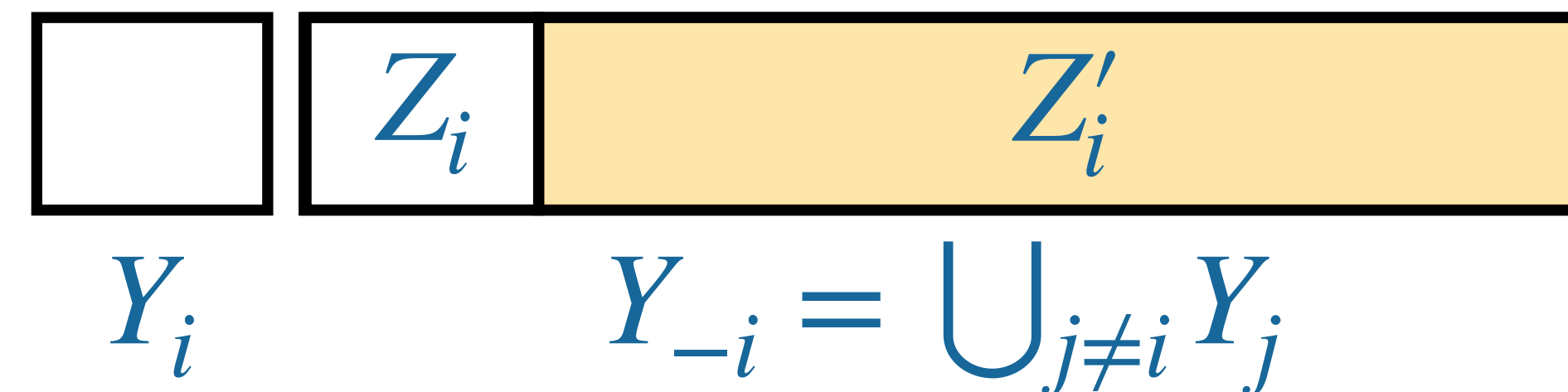


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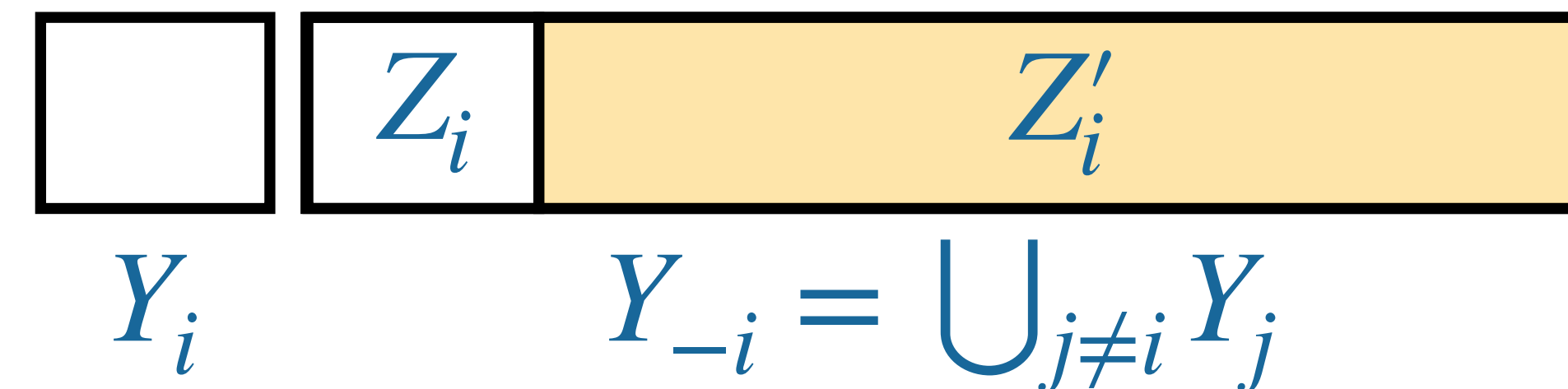


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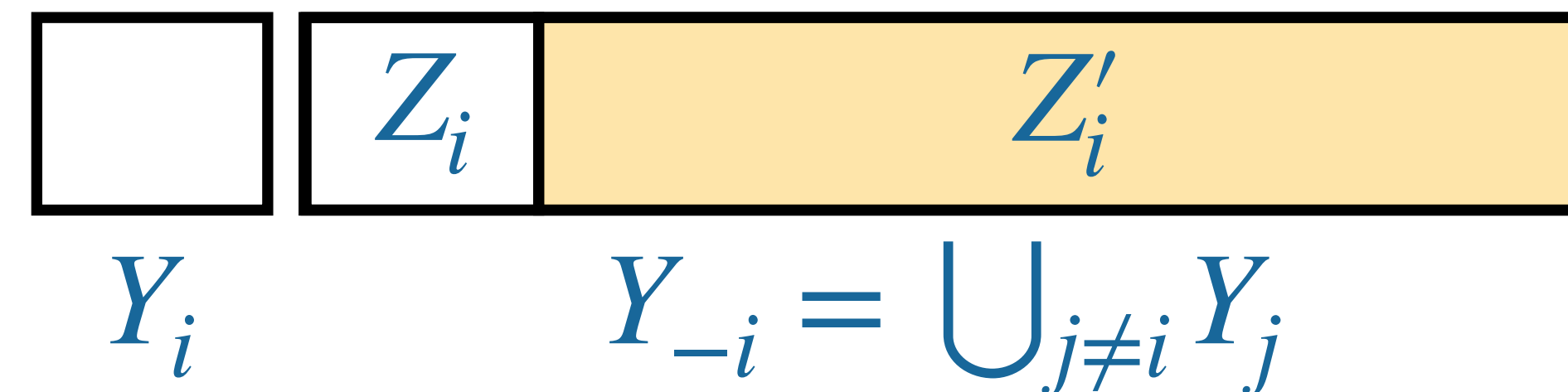
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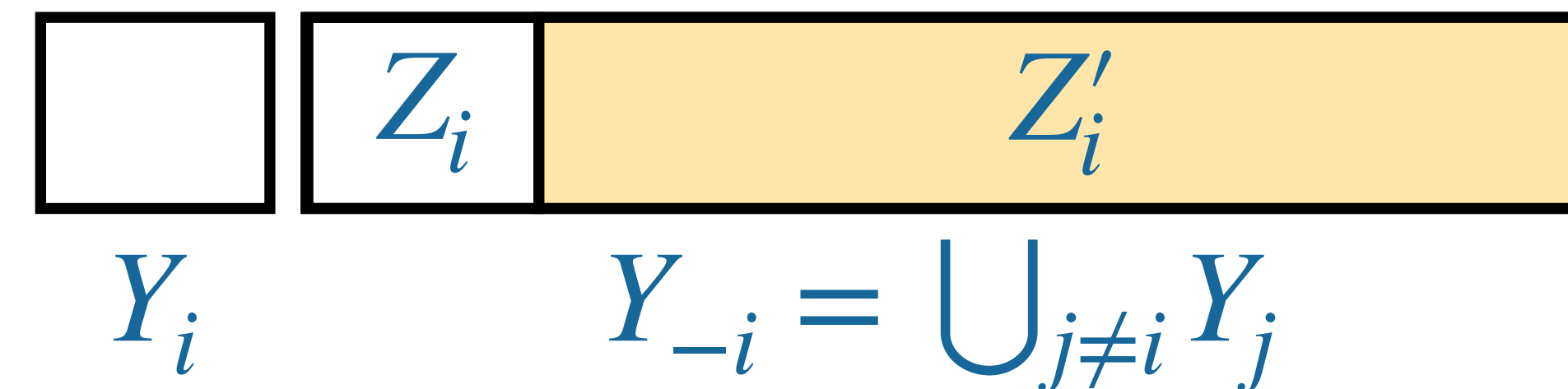
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Z'_i is the corrupted dataset.

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Theorem: The recommended strategy profile s^* is a Nash equilibrium. Moreover, at s^* , the mechanism is individually rational and approximately efficient with $P(M, s^*) \leq 2 \cdot \inf_{M,s} P(M, s)$.

Theorem: The recommended strategy profile s^\star is a Nash equilibrium. Moreover, at s^\star , the mechanism is individually rational and approximately efficient with $P(M, s^\star) \leq 2 \cdot \inf_{M,s} P(M, s)$.

Theorem (high-dimensional distributions with bounded variance): The recommended strategy profile s^\star is an $\tilde{O}(1/m)$ -approximate Nash equilibrium. Moreover, the mechanism is individually rational and approximately efficient with $P(M, s^\star) \leq (2 + \tilde{O}(1/m)) \cdot \inf_{M,s} P(M, s)$.

We need to show that $s^{\star} = \{(n_i^{\star}, f_i^{\star}, h_i^{\star})\}_i$ is a Nash equilibrium, i.e

$$p_i(M, (s_i^{\star}, s_{-i}^{\star})) \leq p_i(M, (s_i, s_{-i}^{\star})) \quad \text{for all agents } i \text{ and all deviations } s_i$$

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Step 2: Then, we will show the agent's penalty is minimized when she collects n_i^{\star} samples under $(f_i^{\star}, h_i^{\star})$, i.e

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Or equivalently,

$$\sup_{\mu \in \mathbb{R}} \mathbb{E}_{\mu} \left[(h_i^* (X_i, f_i^*(X_i), A_i) - \mu)^2 \right] = \inf_{f_i, h_i} \sup_{\mu \in \mathbb{R}} \mathbb{E}_{\mu} \left[(h_i (X_i, f_i(X_i), A_i) - \mu)^2 \right]$$

We are given $X_1^n = \{X_1, \dots, X_n\}$, drawn i.i.d from $\mathcal{N}(\mu, \sigma^2)$ where σ^2 is known. Let $h(X_1^n)$ be an estimator for μ . We wish to show

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We will apply the same recipe to prove step 1,

$$\inf_{f_i, h_i} \sup_{\mu \in \mathbb{R}} \mathbb{E}_{\mu} \left[\left(h_i (X_i, f_i(X_i), A_i) - \mu \right)^2 \right] = \sup_{\mu \in \mathbb{R}} \mathbb{E}_{\mu} \left[\left(h_i^{\star} (X_i, f_i^{\star}(X_i), A_i) - \mu \right)^2 \right]$$

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- ▶ $Z'_i \leftarrow \left\{ z + \epsilon_z, \quad \text{for all } z \in Y_{-i} \setminus Z_i, \quad \text{where } \epsilon_z \sim \mathcal{N}(0, \eta_i^2) \right\}.$

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1. Not just the estimator h_i but also the submission function f_i .
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 - ▶ In fact, X_i, Z_i, Z'_i is not even jointly Gaussian.

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We show

$$\inf_{f_i, h_i} \sup_{\mu \in \mathbb{R}} \mathbb{E}_{\mu} \left[(h_i(X_i, f_i(X_i), A_i) - \mu)^2 \right] \leq \sup_{\mu \in \mathbb{R}} \mathbb{E}_{\mu} \left[(h_i^*(X_i, f_i^*(X_i), A_i) - \mu)^2 \right]$$

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Proof idea:

- ▶ When $f_i^* = \text{identity}$, first condition on X_i, Z_i , then $Z_i' \sim \mathcal{N}(0, \sigma^2 + \eta^2)$.

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- ▶ μ, X_i, Z_i, Z'_i is not jointly Gaussian, but $\mu \mid X_i, Z_i, Z'_i$ is Gaussian.

$$\begin{aligned} &\geq \mathbb{E}_{\text{data}} \left[\left(|Z'_i| \left(\sigma^2 + \alpha^2 \left(\frac{1}{|f_i(X_i)|} \sum_{y \in f_i(X_i)} y - \frac{1}{|Z_i|} \sum_{z \in Z_i} z \right)^2 \right)^{-1} + \frac{|X_i| + |Z_i|}{\sigma^2} + \frac{1}{\tau^2} \right)^{-1} \right] \\ &= \dots = R_\tau(n_i) \quad (\text{say}) \longleftarrow \text{To minimize w.r.t } f_i, \text{ choose } f_i(X_i) = \left\{ \left(1 + \sigma^2 / (|X| \tau^2) \right)^{-1} x, \forall x \in X_i \right\} \\ &\quad \text{and apply Hardy-Littlewood inequality.} \end{aligned}$$

Choose prior $\Lambda = \mathcal{N}(0, \tau^2)$ for μ . Then for any f_i, h_i , we have

$$\begin{aligned} \sup_{\mu \in \mathbb{R}} \mathbb{E}_{\text{data} \sim \mu} \left[(h_i(X_i, f_i(X_i), A_i) - \mu)^2 \right] &\geq \mathbb{E}_{\mu \sim \Lambda} \left[\mathbb{E}_{\text{data} \sim \mu} \left[(h_i(X_i, f_i(X_i), A_i) - \mu)^2 \mid \mu \right] \right] \longleftarrow \text{sup} \geq \text{avg} \\ &= \mathbb{E}_{\text{data} \sim \mu} \left[\mathbb{E}_{\mu \sim \Lambda} \left[(h_i(X_i, f_i(X_i), A_i) - \mu)^2 \mid \text{data} \right] \right] \longleftarrow \text{Swap order of expectation} \end{aligned}$$

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Step 2: Then, we will show the agent's penalty is minimized when she collects n_i samples under (f_i^\star, h_i^\star) , i.e

$$p_i \left(M, \left((n_i^\star, f_i^\star, h_i^\star), s_{-i}^\star \right) \right) \leq p_i \left(M, \left((n_i, f_i^\star, h_i^\star), s_{-i}^\star \right) \right) \quad \text{for all } n_i \in \mathbb{N}$$

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$$\text{RHS} = p_i \left(M, \left((n_i, f_i^\star, h_i^\star), s_{-i}^\star \right) \right) = \mathbb{E}_{Z \sim \mathcal{N}(0,1)} \left[\left(\frac{(m-2)n_i^\star}{\left(\sigma^2 + \alpha^2 \left(\sigma^2/n_i + \sigma^2/n_i^\star \right) Z^2 \right)} + \frac{n_i + n_i^\star}{\sigma^{-2}} \right)^{-1} \right] + cn_i$$

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- The term inside \mathbb{E} is convex in n_i . Hence so is $p_i \left(M, \left((n_i, f_i^\star, h_i^\star), s_{-i}^\star \right) \right)$.
- Minimized at $n_i = n_i^\star$ (by our choice of α).

- ▶ For each agent i :
 - ▶ $Z_i \leftarrow$ sample $n^* = \sigma/\sqrt{cm}$ points from others' subn
 - ▶ Set noise variance $\eta_i^2 = \alpha^2 (\text{mean}(Y_i) - \text{mean}(Z_i))^2$

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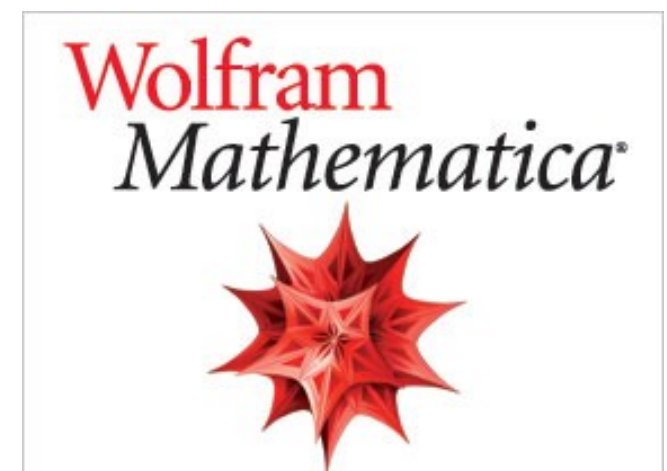
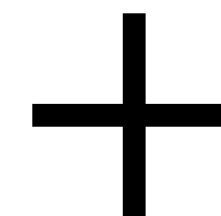
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1. Mechanism design for collaborative normal mean estimation

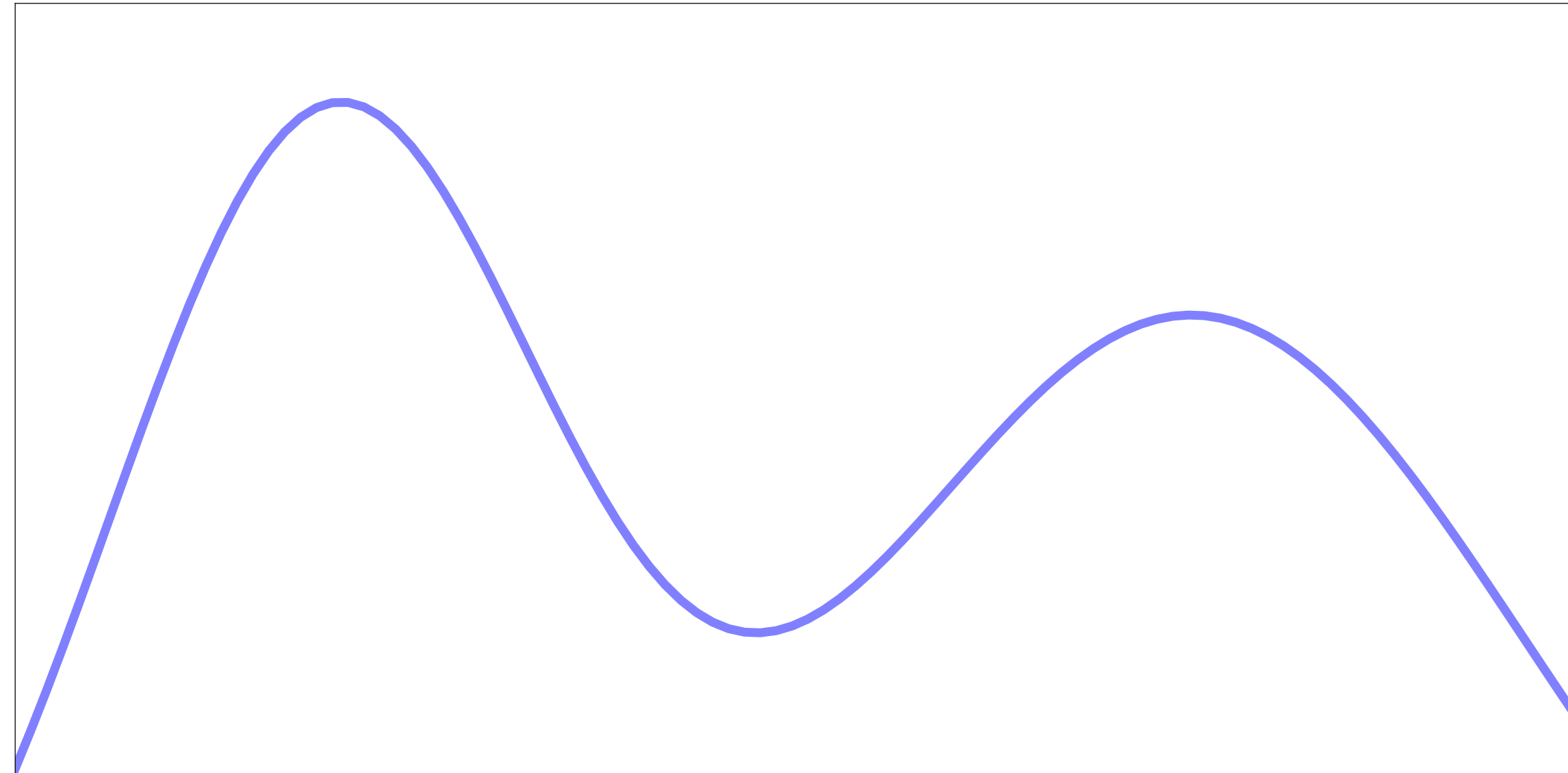
(Chen, Zhu, Kandasamy, *NeurIPS 2023*)

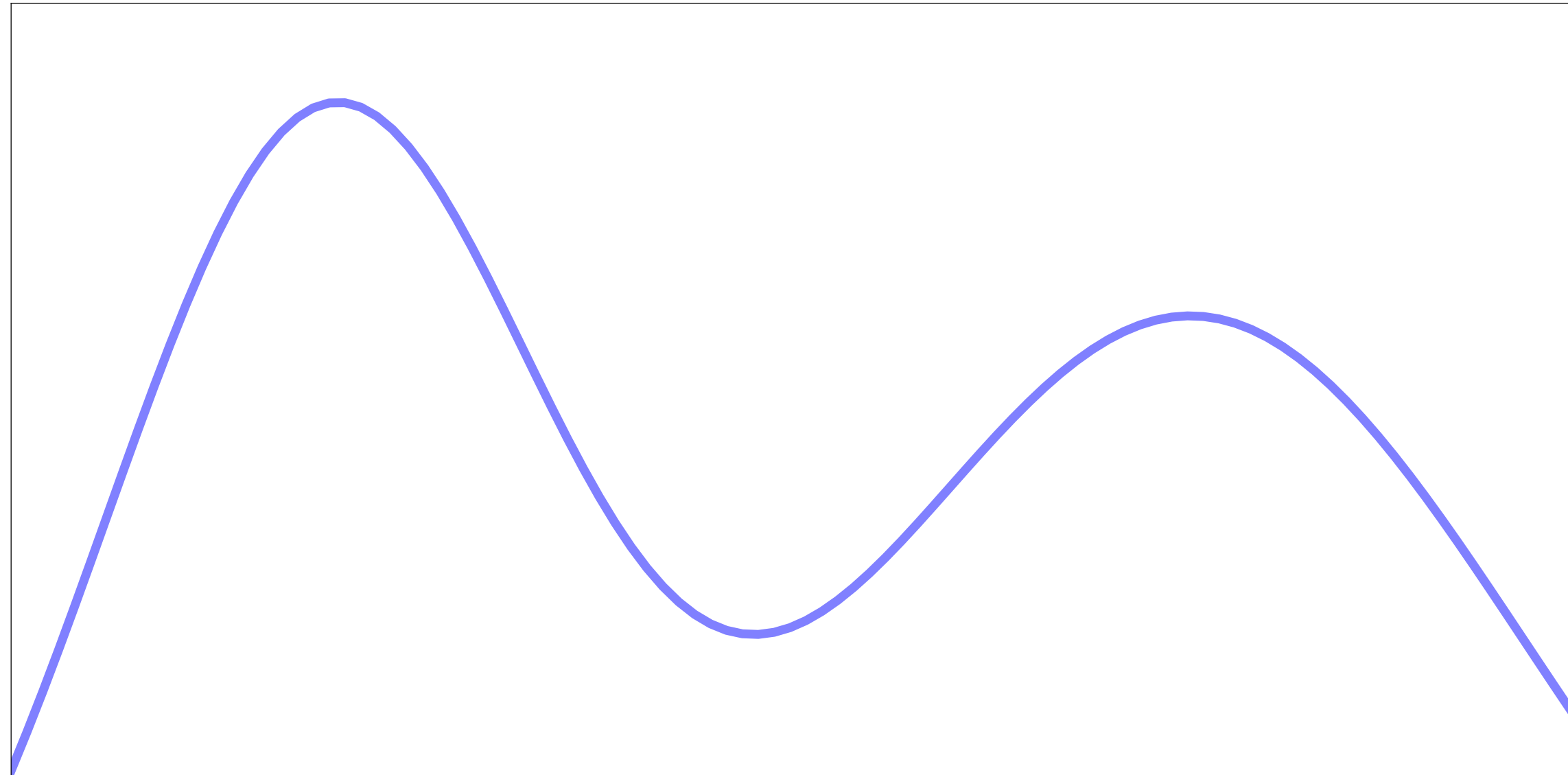
- ▶ Intuitions, overview of results
- ▶ Problem formalism
- ▶ Mechanism and theoretical analysis

2. Extensions

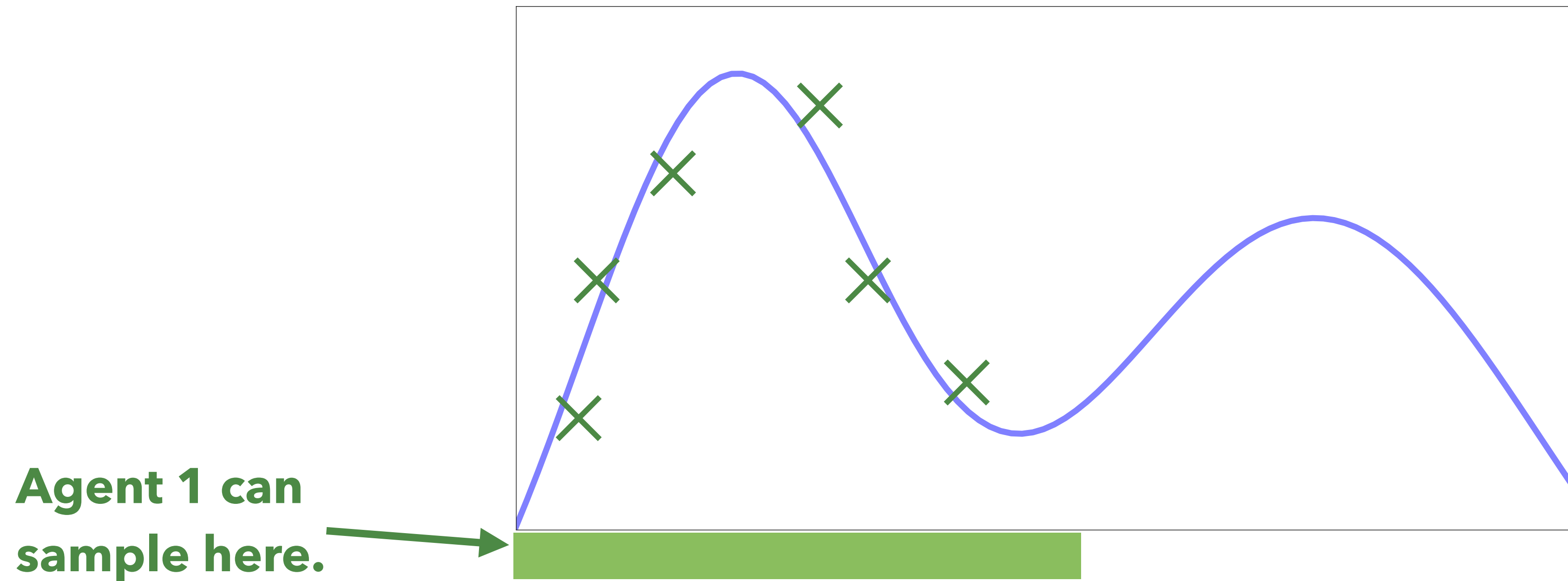
(Clinton, Chen, Zhu, Kandasamy, *Ongoing work*)

- ▶ **Multiple distributions with asymmetric data collection capabilities**
- ▶ **Collaborative supervised learning and experiment design**

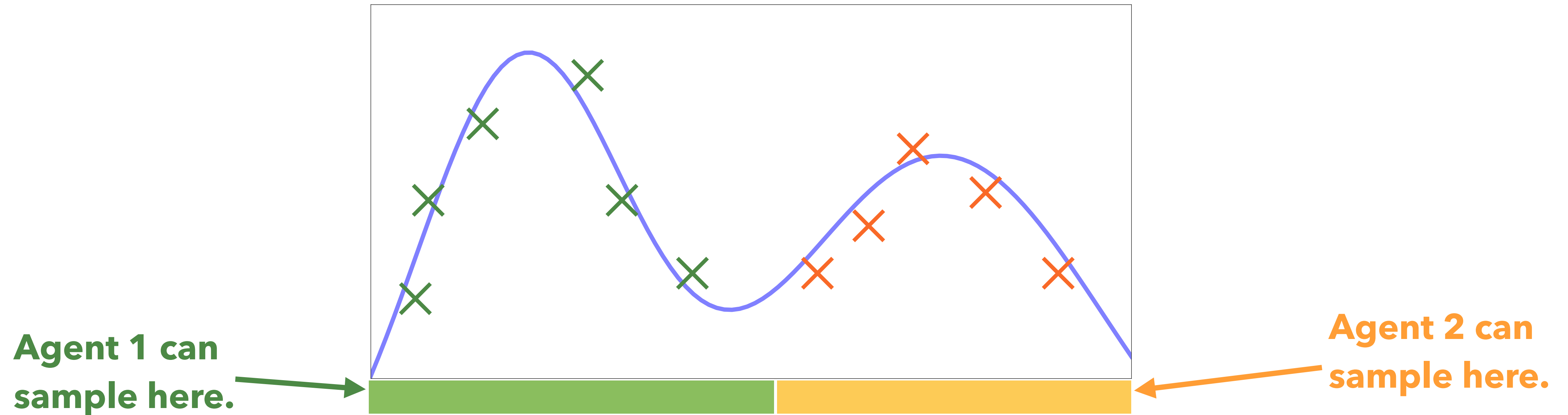




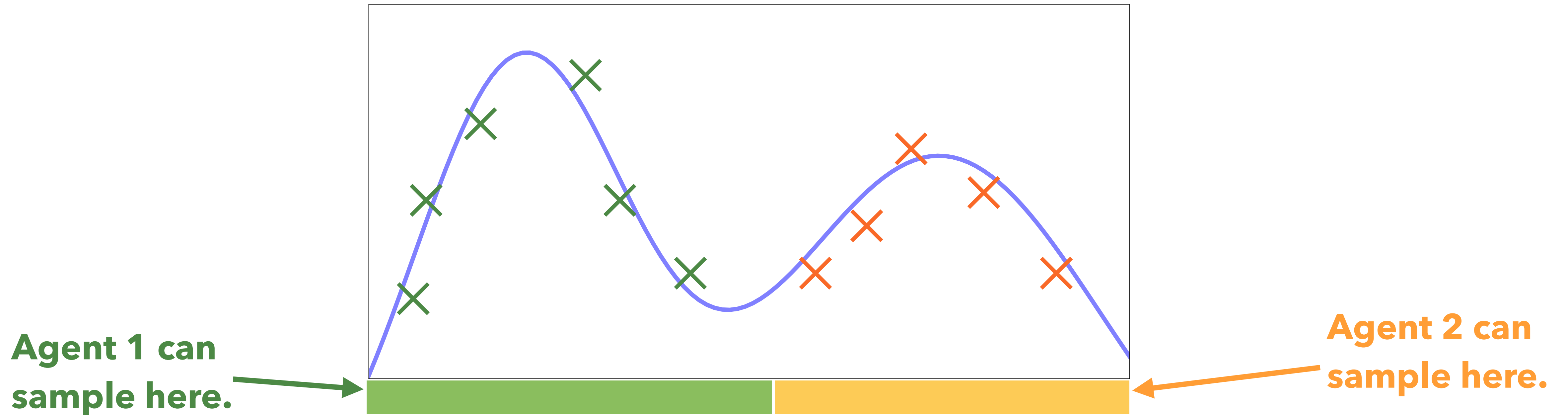
Data sharing when there is asymmetric data collection capabilities.



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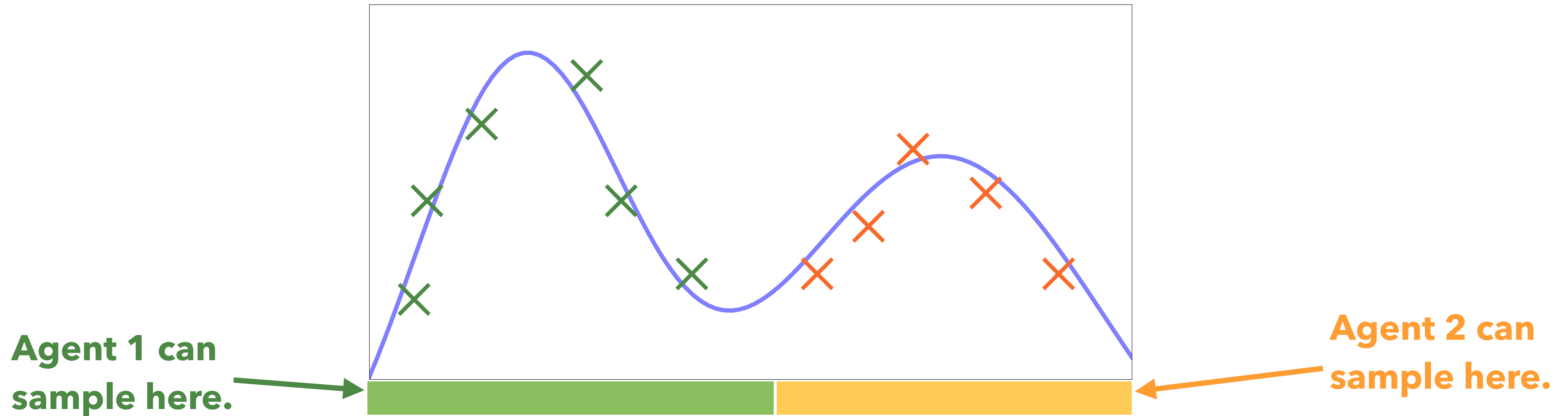


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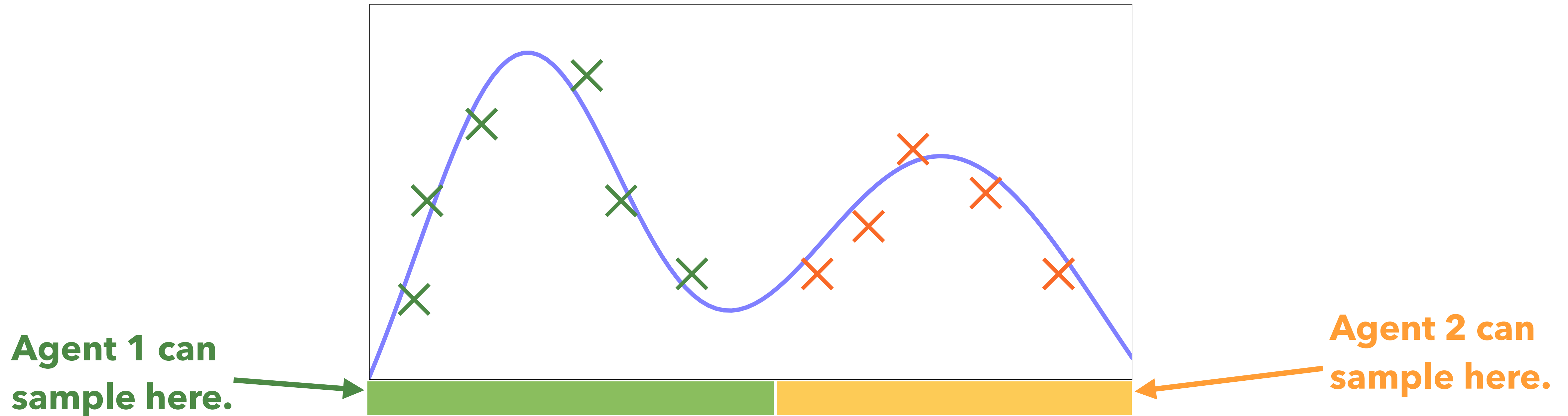
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+ Agents will be more willing to collaborate due to complementarity of data.

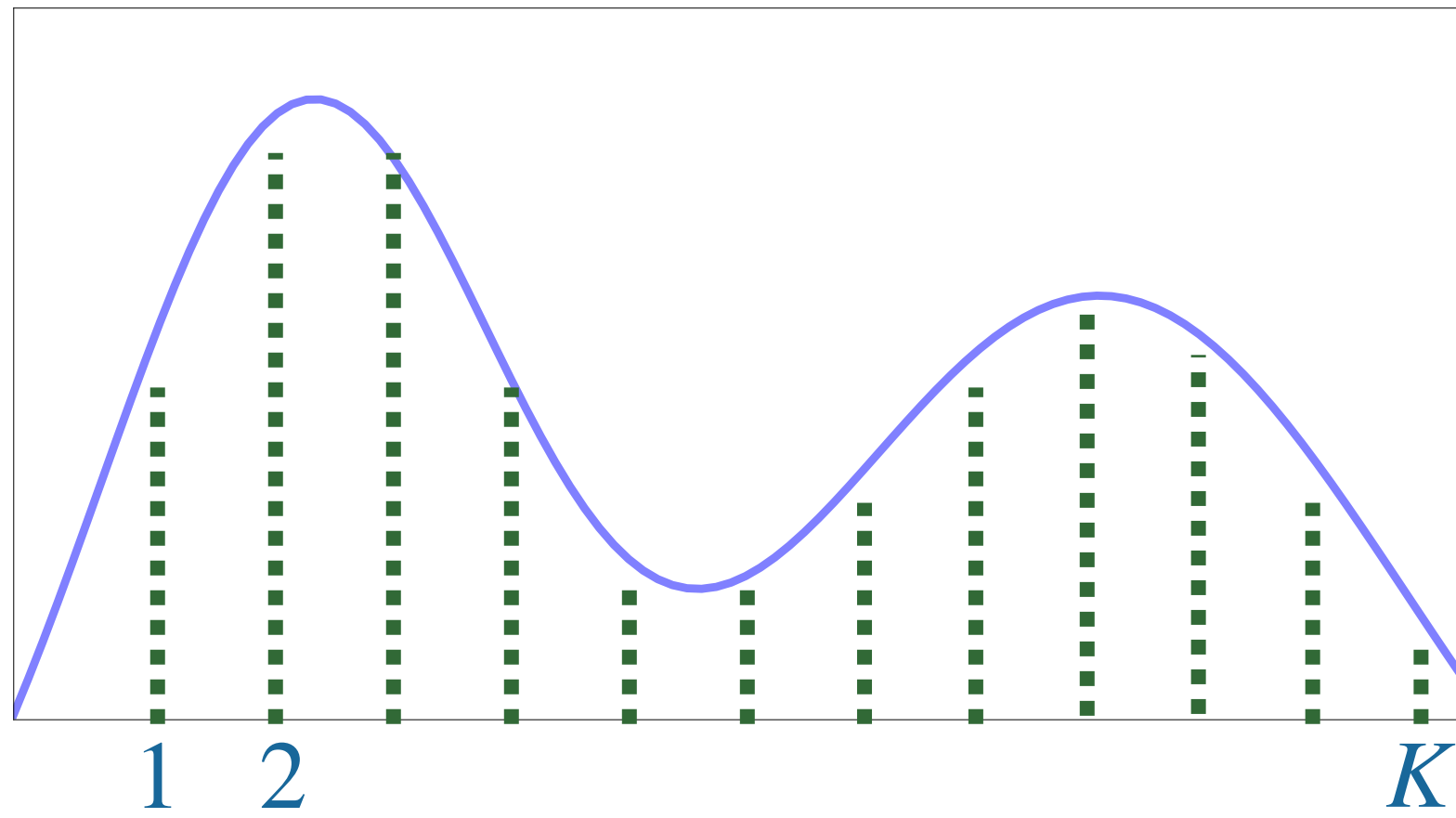


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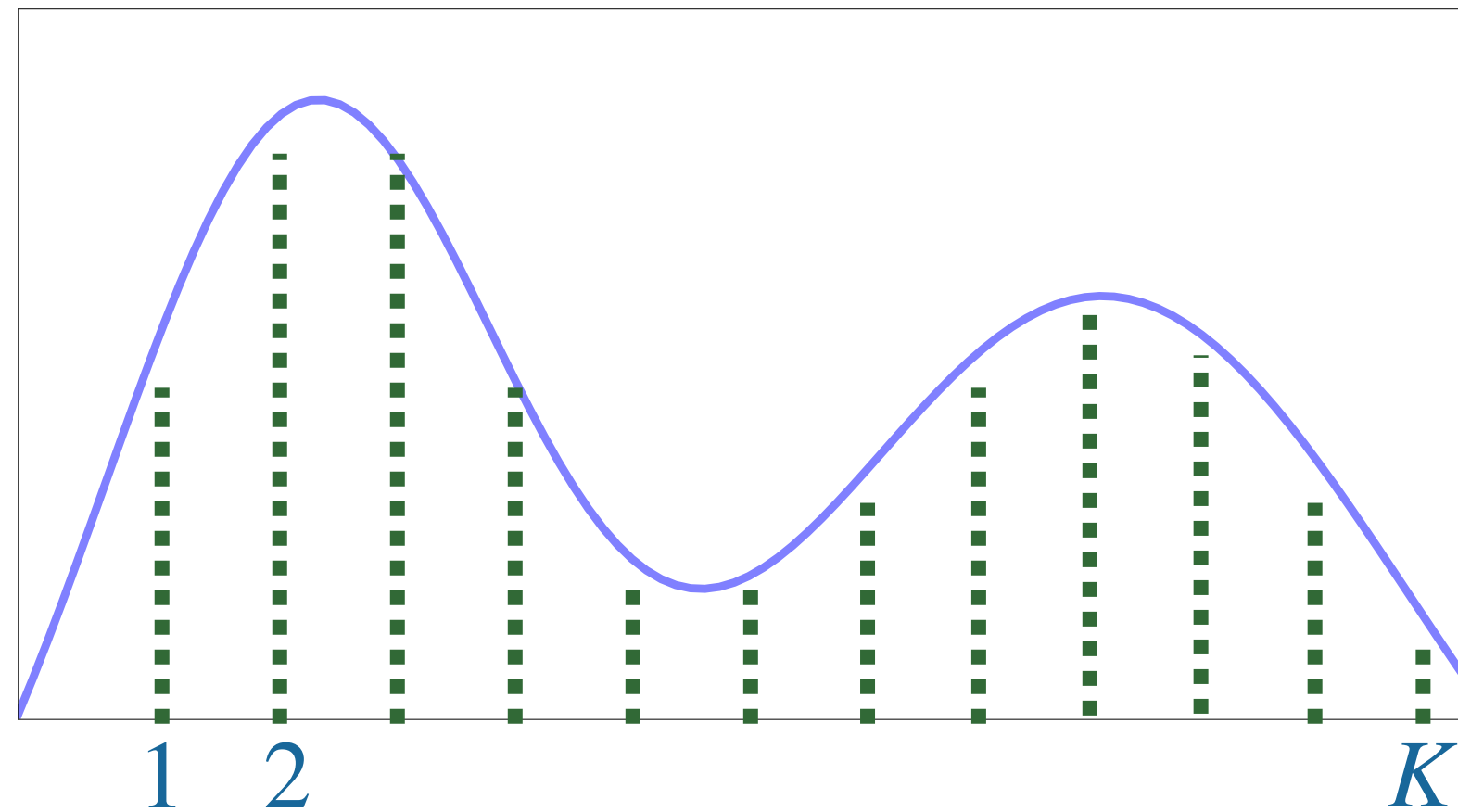
E.g: hospitals in different locations, researchers with different experimental equipment etc.

- + Agents will be more willing to collaborate due to complementarity of data.
- No way to validate an agent's data with other similar data.

Consider estimating K distributions (e.g discretizing the domain)



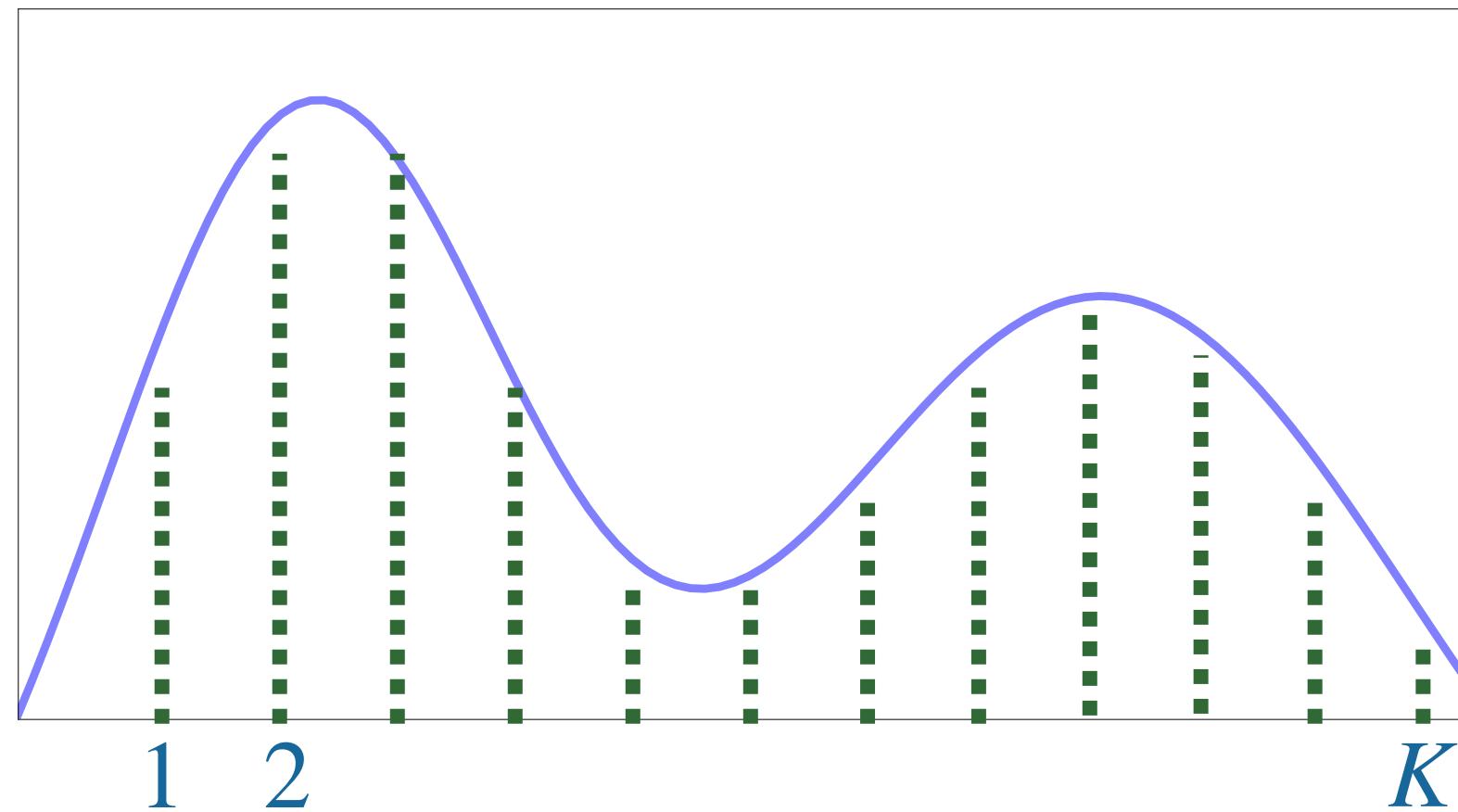
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Agent i can sample from distribution k at cost $c_{i,k}$.

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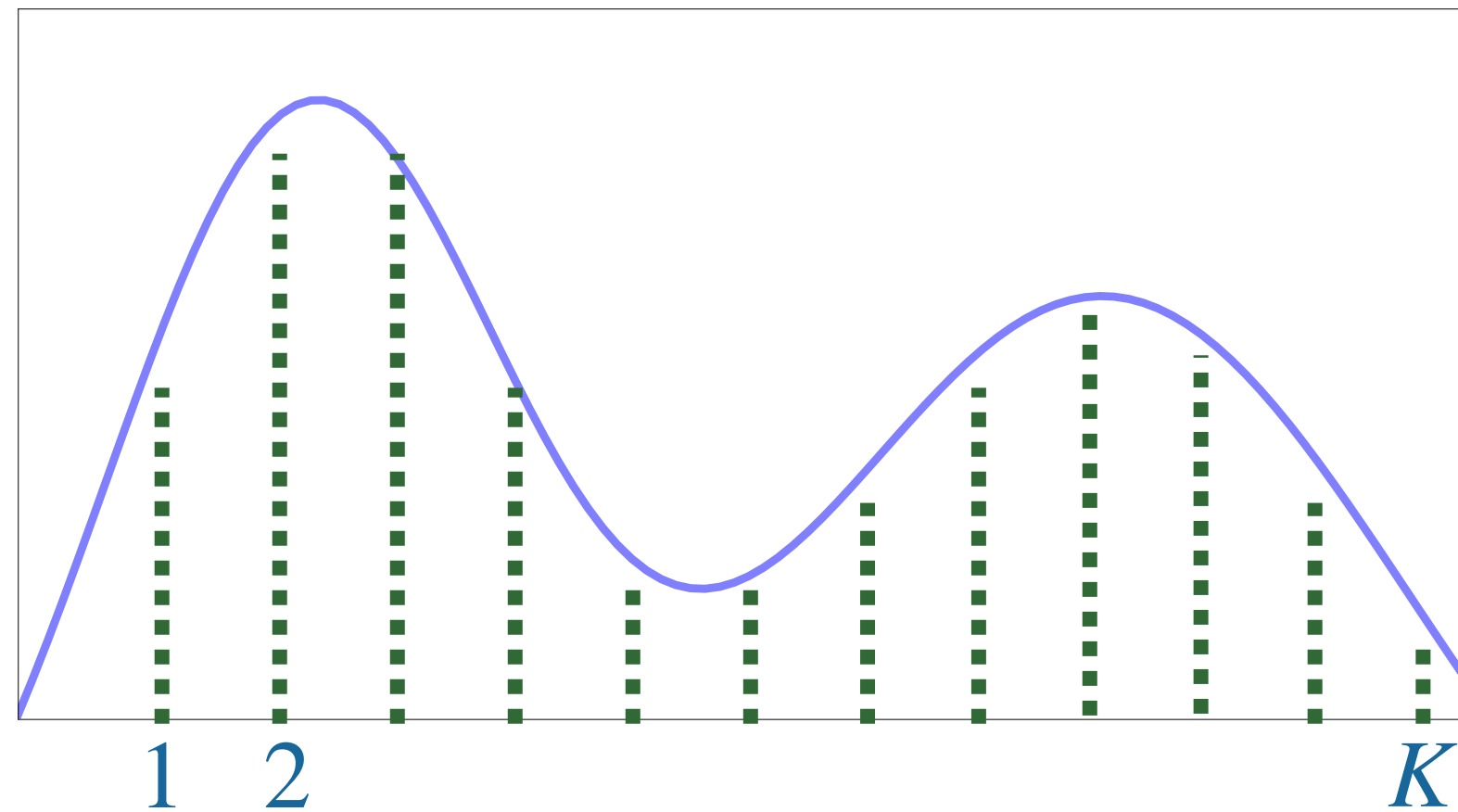
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Overview of our solution:

- ▶ Uses axiomatic bargaining to define idealized *collaboration targets* assuming agents will always report truthfully.

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Overview of our solution:

- ▶ Uses axiomatic bargaining to define idealized *collaboration targets* assuming agents will always report truthfully.
- ▶ Enforces truthful behaviour, via corruption and other techniques.

Theorem: There exists a NIC and IR mechanism for which,

$$P(M, s^\star) \leq 8\sqrt{m} \cdot \inf_{M,s} P(M, s)$$

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Theorem (hardness): There exists a set of costs $\{c_{i,k}\}_{i,k}$ such that for any mechanism M and any Nash equilibrium s^{\star} of this mechanism, we have

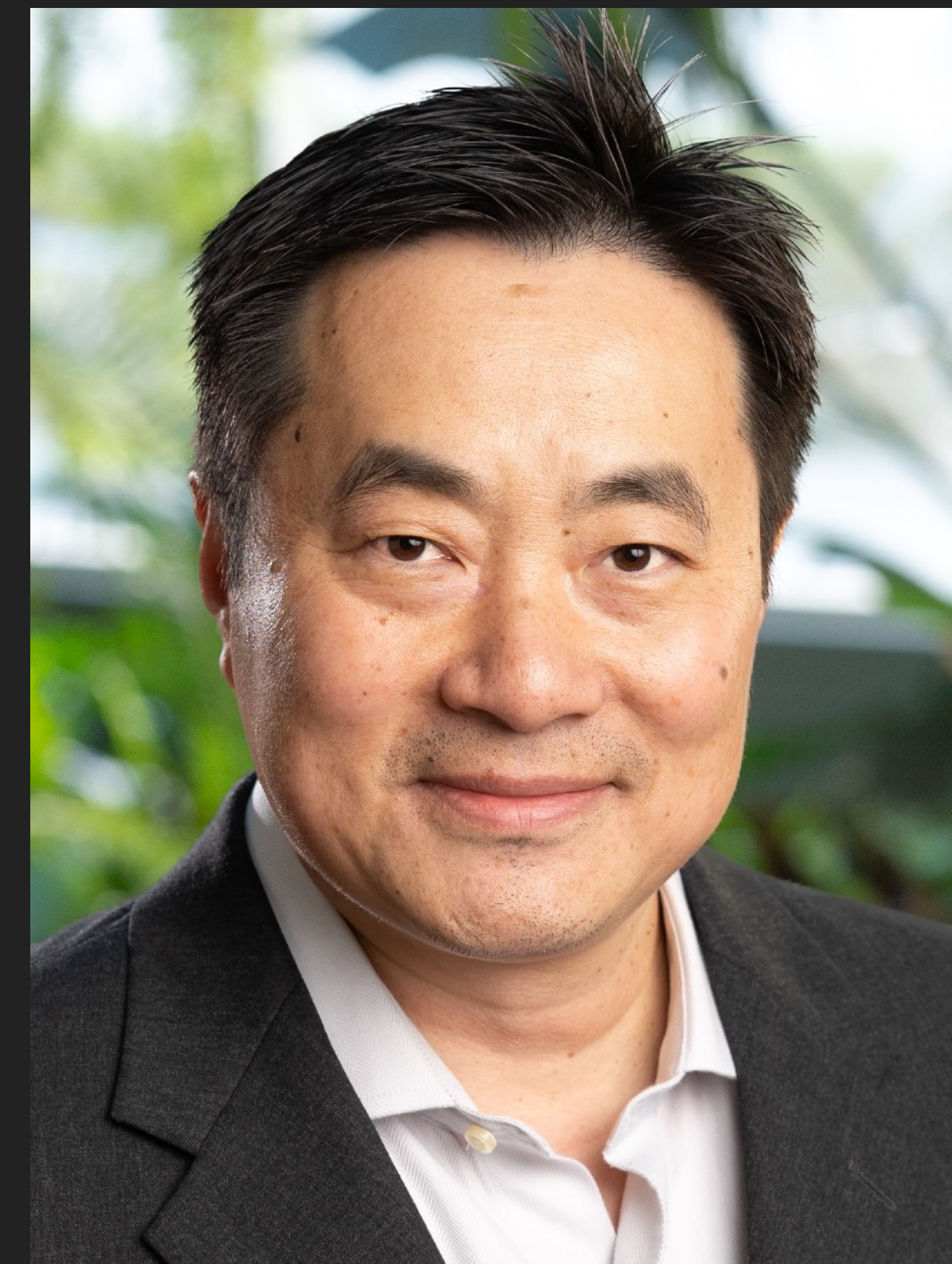
$$P(M, s^{\star}) \geq \mathcal{O}\left(\sqrt{m}\right) \cdot \inf_{M,s} P(M, s)$$



Yiding Chen



Alex Clinton



Jerry Zhu

THANK YOU!

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- ▶ Data sharing has many benefits
 - ▶ Maximize the value created by data.
 - ▶ Democratize data.
- ▶ But strategic agents can free-ride in naive mechanisms, either by not contributing data, or contributing fabricated datasets.
- ▶ For mean estimation, our mechanism is IR and NIC while achieving a factor 2 of the global minimum social penalty.

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When agents have to report truthfully ($\mathcal{S} = \mathbb{N} \times \mathcal{H}$):

Theorem: The “pool and share, but only if you contribute enough data” mechanism is NIC and IR and achieves the global minimum penalty $\inf_{M,s} P(M, s)$.