Virtualizing Memory CS 537: Introduction to Operating Systems

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Administrivia

- Project 2 Due Feb 6th, 11:59pm
- Pinned Posts on Piazza:
 - Remote Development Through VSCode
 - Pregrade Check Script

Agenda

- Goals of Memory Virtualization
- Understand Address Space
- Memory API (malloc() and free())
- Address Translation (Base & Bounds)
- CPU Virtualization (2 lectures: mechanism + policy)
- Memory Virtualization (6 lectures)

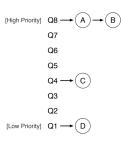
Review: CPU Scheduling

• Design scheduling policy:

- Understanding Workload (interactive vs. batch programs)
- Using metrics to optimize type of performance (turnaround time, response time)
- Incorporating non-preemptive or preemptive concepts
- Scheduler Types & Issues:
 - FIFO/FCFS, SJF, STCF, RR
 - MLFQ
 - Using past behavior to predict future behavior
 - Handling mix of IO vs CPU bound jobs
 - Handling tricky processes
 - Tuning length of time slice, number of queues, boosting length
- Other Goals/Metrics (fairness) and Policies (Lottery)

MLFQ Review

Quiz 3 MLFQ: http://tinyurl.com/cs537-sp24-q3



RULES:



Rule 1: If Priority(A) > Priority(B) then A runs Rule 2: If Priority(A) == Priority(B) then A&B run in RR

Rule 3: Processes start at top priority

Rule 4: Once a job uses up its time allotment at a given level (regardless of how many times it has given up the CPU), its priority is reduced Rule 5: After some time period S, move all the jobs in the system to the topmost queue.

Memory Early Days

Multiprogramming Goals

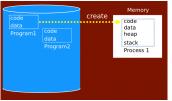
Uniprogramming: One process runs at a time ÓKB Operating System (code, data, etc.) 64KB Current Program (code, data, etc.) max

- Transparency: Process is unaware of sharing
- Protection: Cannot corrupt OS or other processes' memory
- Efficiency: Do not waste memory or slow down processes
- Sharing: Enable sharing between cooperating processes

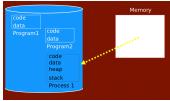
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Alternative 1: Time Sharing

Step 1







Step 3

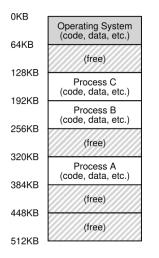
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• Storing process and loading another is extremely slow!

• Better Alternative: Space Sharing!

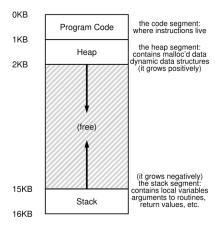
Alternative 2: Space Sharing



Protection becomes extremely important, don't want a process to be able to read or write some other process's memory.

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Abstraction: Address Space



View of memory from program's perspective.

- Heap can become fragmented
- Stack does not

Demo

vm-intro/va.c

What Variables Go Where (Stack, Heap, Code/Static)?

int J;

```
int* foo(int Y, int *Z) {
        int *A = malloc(sizeof(int));
        *A = 2:
        Y = 3:
        *Z = 4;
        return A:
}
void main() {
        J = 10;
        int A = 0:
        int *B;
        B = malloc(sizeof(int));
        *B = 5:
        int *C = foo(A,B);
        printf("A:%d, B:%d,",A,*B);
        printf("C:%d, J:%d\n",*C,J);
        free(B);
        free(C);
}
```

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Memory Access

```
#include <stdio.h>
#include <stdlib.h>
int main() {
    int x;
    x = x + 3;
}
```

0x10: movl 0x8(%rbp), %edi 0x13: addl \$0x3, %edi 0x19: movl %edi, 0x8(%rbp)

%rbp is the base pointer: points to base of current stack frame

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Memory Access (cont.)

Initial %rip = 0×10 %rbp = 0×200

0x10: movl 0x8(%rbp), %edi 0x13: addl \$0x3, %edi 0x19: movl %edi, 0x8(%rbp)

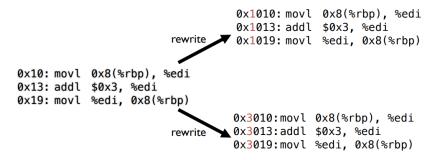
%rbp is the base pointer: points to base of current stack frame%rip is instruction pointer (program counter) Fetch instruction at addr 0x10 Exec: **load from addr 0x208**

Fetch instruction at addr 0x13 Exec: **no memory access**

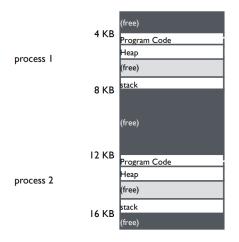
Fetch instruction at addr 0x19 Exec: **store to addr 0x208**

Space Sharing Attempt 1 (Static Relocation)

Idea: OS rewrites each program as it is loaded and placed in memory Change jumps, loads of static data, etc.



Static Relocation Memory Layout



0x1010:movl 0x8(%rbp), %edi 0x1013:addl \$0x3, %edi 0x1019:movl %edi, 0x8(%rbp)

0x3010:movl 0x8(%rbp), %edi 0x3013:addl \$0x3, %edi 0x3019:movl %edi, 0x8(%rbp)

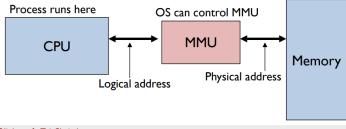
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Static Relocation Disadvantages

- No Protection
 - Process can destroy OS or other processes
 - No privacy
- Cannot move address space after it has been placed
 - May not be able to allocate new process

Space Sharing Attempt 2 (Dynamic Relocation)

- Requires hardware support (Memory Management Unit (MMU))
- MMU dynamically changes process address at every memory reference
 - Process generates **logical** or **virtual** addresses (in their address space)
 - Memory hardware uses physical or real addresses



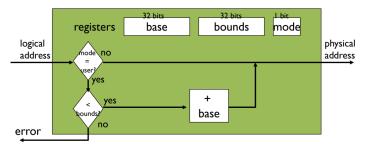
Dynamic Relocation Hardware Support

- Kernel Mode: OS runs
 - Allows instructions for manipulating MMU
 - OS access to all of physical memory
- User mode: process runs
 - Perform translation of logical address to physical address

Dynamic Relocation with **Base+Bounds**

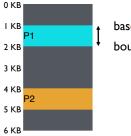
Translation on every memory access of user process

- MMU compares logical address to **bounds register** if logical address is greater, then generate error
- MMU adds base register to logical address to form physical address



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Base+Bounds Example



base register bounds register Every process has its own set of base and bounds register values

OS sets registers when loading process

Process can be moved, just need to update its base register

Process is restricted to its address space

Hardware Requirements

Hardware Requirements	Notes
Privileged mode	Needed to prevent user-mode processes
	from executing privileged operations
Base/bounds registers	Need pair of registers per CPU to support
	address translation and bounds checks
Ability to translate virtual addresses	Circuitry to do translations and check
and check if within bounds	limits; in this case, quite simple
Privileged instruction(s) to	OS must be able to set these values
update base/bounds	before letting a user program run
Privileged instruction(s) to register	OS must be able to tell hardware what
exception handlers	code to run if exception occurs
Ability to raise exceptions	When processes try to access privileged
	instructions or out-of-bounds memory

Figure 15.3: Dynamic Relocation: Hardware Requirements

OS Requirements

OS Requirements	Notes	
Memory management	Need to allocate memory for new processes;	
	Reclaim memory from terminated processes;	
	Generally manage memory via free list	
Base/bounds management	Must set base/bounds properly upon context switch	
Exception handling	Code to run when exceptions arise;	
	likely action is to terminate offending process	

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Limited Direct Execution (Dynamic Relocation) @ Boot

OS @ boot (kernel mode)	Hardware	(No Program Yet)
initialize trap table		
	remember addresses of system call handler timer handler illegal mem-access handler illegal instruction handler	
start interrupt timer initialize process table initialize free list	start timer; interrupt after X ms	

Figure 15.5: Limited Direct Execution (Dynamic Relocation) @ Boot

Good Running Process

OS @ run (kernel mode)	Hardware	Program (user mode)
To start process A:		
allocate entry		
in process table		
alloc memory for process		
set base/bound registers		
return-from-trap (into A)		
	restore registers of A	
	move to user mode	
	jump to A's (initial) PC	
		Process A runs
		Fetch instruction
	translate virtual address	
	perform fetch	
		Execute instruction
	if explicit load/store: ensure address is legal translate virtual address	
	perform load/store	
		(A runs)

Context Switch

(A runs...)

Timer interrupt move to **kernel mode** jump to handler

Handle timer

decide: stop A, run B
call switch() routine
save regs(A)
to proc-struct(A)
(including base/bounds)
restore regs(B)
from proc-struct(B)
(including base/bounds)
return-from-trap (into B)

restore registers of B move to **user mode** jump to B's PC



Bad Process

Process B runs Execute bad load

Load is out-of-bounds; move to **kernel mode** jump to trap handler

Handle the trap

decide to kill process B deallocate B's memory free B's entry in process table

Figure 15.6: Limited Direct Execution (Dynamic Relocation) @ Runtime

Advantages and Disadvantages

Advantages

- Provides protection across address spaces
- Supports Dynamic relocation Can place process at different locations initially and move address spaces later
- Simple, inexpensive implementation: few registers, little logic in MMU
- Fast: add and compare in parallel

Disadvantages

- Each process must be allocated contiguously in physical memory – must allocate memory that may not be used by process
- No partial sharing: Cannot share parts of address space

Disadvantages

- Each process must be allocated contiguously
- Must allocate memory that may not be used by process
- No partial sharing: Cannot share parts of address space

