B.1 Introduction

Years ago, IBM sold expensive mainframes to large organizations, and a problem arose: what if the organization wanted to run different operating systems on the machine at the same time? Some applications had been developed on one OS, and some on others, and thus the problem. As a solution, IBM introduced yet another level of indirection in the form of a virtual machine monitor (VMM) (also called a hypervisor) [G74].

Specifically, the monitor sits between one or more operating systems and the hardware and gives the illusion to each running OS that it controls the machine. Behind the scenes, however, the monitor actually is in control of the hardware, and must multiplex running OSes across the physical resources of the machine. Indeed, the VMM serves as an operating system for operating systems, but at a much lower level; the OS must still think it is interacting with the physical hardware. Thus, transparency is a major goal of VMMs.

Thus, we find ourselves in a funny position: the OS has thus far served as the master illusionist, tricking unsuspecting applications into thinking they have their own private CPU and a large virtual memory, while secretly switching between applications and sharing memory as well. Now, we have to do it again, but this time underneath the OS, who is used to being in charge. How can the VMM create this illusion for each OS running on top of it?

THE CRUX:
HOW TO VIRTUALIZE THE MACHINE UNDERNEATH THE OS
The virtual machine monitor must transparently virtualize the machine underneath the OS; what are the techniques required to do so?
B.2 Motivation: Why VMMs?

Today, VMMs have become popular again for a multitude of reasons. Server consolidation is one such reason. In many settings, people run services on different machines which run different operating systems (or even OS versions), and yet each machine is lightly utilized. In this case, virtualization enables an administrator to consolidate multiple OSes onto fewer hardware platforms, and thus lower costs and ease administration.

Virtualization has also become popular on desktops, as many users wish to run one operating system (say Linux or Mac OS X) but still have access to native applications on a different platform (say Windows). This type of improvement in functionality is also a good reason.

Another reason is testing and debugging. While developers write code on one main platform, they often want to debug and test it on the many different platforms that they deploy the software to in the field. Thus, virtualization makes it easy to do so, by enabling a developer to run many operating system types and versions on just one machine.

This resurgence in virtualization began in earnest the mid-to-late 1990’s, and was led by a group of researchers at Stanford headed by Professor Mendel Rosenblum. His group’s work on Disco [B+97], a virtual machine monitor for the MIPS processor, was an early effort that revived VMMs and eventually led that group to the founding of VMware [V98], now a market leader in virtualization technology. In this chapter, we will discuss the primary technology underlying Disco and through that window try to understand how virtualization works.

B.3 Virtualizing the CPU

To run a virtual machine (e.g., an OS and its applications) on top of a virtual machine monitor, the basic technique that is used is limited direct execution, a technique we saw before when discussing how the OS virtualizes the CPU. Thus, when we wish to “boot” a new OS on top of the VMM, we simply jump to the address of the first instruction and let the OS begin running. It is as simple as that (well, almost).

Assume we are running on a single processor, and that we wish to multiplex between two virtual machines, that is, between two OSes and their respective applications. In a manner quite similar to an operating system switching between running processes (a context switch), a virtual machine monitor must perform a machine switch between running virtual machines. Thus, when performing such a switch, the VMM must save the entire machine state of one OS (including registers, PC, and unlike in a context switch, any privileged hardware state), restore the machine state of the to-be-run VM, and then jump to the PC of the to-be-run VM and thus complete the switch. Note that the to-be-run VM’s PC may be within the OS itself (i.e., the system was executing a system call) or it may simply be within a process that is running on that OS (i.e., a user-mode application).
We get into some slightly trickier issues when a running application or
OS tries to perform some kind of privileged operation. For example, on
a system with a software-managed TLB, the OS will use special privi-
ileged instructions to update the TLB with a translation before restarting
an instruction that suffered a TLB miss. In a virtualized environment, the
OS cannot be allowed to perform privileged instructions, because then it
controls the machine rather than the VMM beneath it. Thus, the VMM
must somehow intercept attempts to perform privileged operations and
thus retain control of the machine.

A simple example of how a VMM must interpose on certain operations
arises when a running process on a given OS tries to make a system call. For example, the process may be trying to call open() on a file, or may be
calling read() to get data from it, or may be calling fork() to create a
new process. In a system without virtualization, a system call is achieved
with a special instruction; on MIPS, it is a trap instruction, and on x86, it
is the int (an interrupt) instruction with the argument 0x80. Here is the
open library call on FreeBSD [B00] (recall that your C code first makes a
library call into the C library, which then executes the proper assembly
sequence to actually issue the trap instruction and make a system call):

```
open:
push dword mode
push dword flags
push dword path
mov eax, 5
push eax
int 80h
```

On UNIX-based systems, open() takes just three arguments: int
open(char *path, int flags, mode_t mode). You can see in the
code above how the open() library call is implemented: first, the argu-
ments get pushed onto the stack (mode, flags, path), then a 5
gets pushed onto the stack, and then int 80h is called, which trans-
fers control to the kernel. The 5, if you were wondering, is the pre-agreed
upon convention between user-mode applications and the kernel for the
open() system call in FreeBSD; different system calls would place dif-
ferent numbers onto the stack (in the same position) before calling the trap
instruction int and thus making the system call1.

When a trap instruction is executed, as we’ve discussed before, it usu-
ally does a number of interesting things. Most important in our example
here is that it first transfers control (i.e., changes the PC) to a well-defined
trap handler within the operating system. The OS, when it is first start-
ing up, establishes the address of such a routine with the hardware (also

1Just to make things confusing, the Intel folks use the term “interrupt” for what almost
any sane person would call a trap instruction. As Patterson said about the Intel instruction
set: “It’s an ISA only a mother could love.” But actually, we kind of like it, and we’re not its
mother.

© 2008–23, ARPACI-DUSSEAU
Process | Hardware | Operating System
---|---|---
1. Execute instructions (add, load, etc.) | 3. Switch to kernel mode; Jump to trap handler | 4. In kernel mode; Handle system call; Return from trap
2. System call: Trap to OS | | 5. Switch to user mode; Return to user code
6. Resume execution (@PC after trap) | | 7. Resume execution (PC after trap)

**Figure B.1: Executing a System Call**

a privileged operation) and thus upon subsequent traps, the hardware knows where to start running code to handle the trap. At the same time of the trap, the hardware also does one other crucial thing: it changes the mode of the processor from **user mode** to **kernel mode**. In user mode, operations are restricted, and attempts to perform privileged operations will lead to a trap and likely the termination of the offending process; in kernel mode, on the other hand, the full power of the machine is available, and thus all privileged operations can be executed. Thus, in a traditional setting (again, without virtualization), the flow of control would be like what you see in Figure B.1.

On a virtualized platform, things are a little more interesting. When an application running on an OS wishes to perform a system call, it does the exact same thing: executes a trap instruction with the arguments carefully placed on the stack (or in registers). However, it is the VMM that controls the machine, and thus the VMM who has installed a trap handler that will first get executed in kernel mode.

So what should the VMM do to handle this system call? The VMM doesn’t really know **how** to handle the call; after all, it does not know the details of each OS that is running and therefore does not know what each call should do. What the VMM does know, however, is **where** the OS’s trap handler is. It knows this because when the OS booted up, it tried to install its own trap handlers; when the OS did so, it was trying to do something privileged, and therefore trapped into the VMM; at that time, the VMM recorded the necessary information (i.e., where this OS’s trap handlers are in memory). Now, when the VMM receives a trap from a user process running on the given OS, it knows exactly what to do: it jumps to the OS’s trap handler and lets the OS handle the system call as it should. When the OS is finished, it executes some kind of privileged instruction to return from the trap (**rett** on MIPS, **iret** on x86), which again bounces into the VMM, which then realizes that the OS is trying to return from the trap and thus performs a real return-from-trap and thus
Process | Operating System
---|---
1. System call: Trap to OS

| | | VMM
---|---|---
1. System call: Trap to OS

| Process | Operating System | VMM |
---|---|---
1. System call: Trap to OS

| | | |
|---|---|
2. OS trap handler: Decode trap and execute appropriate syscall routine; When done: return from trap

2. Process trapped: Call OS trap handler (at reduced privilege)

3. OS trap handler: Decode trap and execute syscall; When done: issue return-from-trap

3. Resume execution (@PC after trap)

4. OS tried return from trap: Do real return from trap

5. Resume execution (@PC after trap)

returns control to the user and puts the machine back in user mode. The entire process is depicted in Figures B.2 and B.3, both for the normal case without virtualization and the case with virtualization (we leave out the exact hardware operations from above to save space).

As you can see from the figures, a lot more has to take place when virtualization is going on. Certainly, because of the extra jumping around, virtualization might indeed slow down system calls and thus could hurt performance.

You might also notice that we have one remaining question: what mode should the OS run in? It can’t run in kernel mode, because then it would have unrestricted access to the hardware. Thus, it must run in some less privileged mode than before, be able to access its own data structures, and simultaneously prevent access to its data structures from user processes.

In the Disco work, Rosenblum and colleagues handled this problem quite neatly by taking advantage of a special mode provided by the MIPS hardware known as supervisor mode. When running in this mode, one still doesn’t have access to privileged instructions, but one can access a...
You should now have a basic idea of how the processor is virtualized: the VMM acts like an OS and schedules different virtual machines to run, and some interesting interactions occur when privilege levels change. But we have left out a big part of the equation: how does the VMM virtualize memory?

Each OS normally thinks of physical memory as a linear array of pages, and assigns each page to itself or user processes. The OS itself, of course, already virtualizes memory for its running processes, such that each process has the illusion of its own private address space. Now we must add another layer of virtualization, so that multiple OSes can share the actual physical memory of the machine, and we must do so transparently.

This extra layer of virtualization makes “physical” memory a virtualization on top of what the VMM refers to as machine memory, which is the real physical memory of the system. Thus, we now have an additional
## Process Operating System

1. Load from memory: TLB miss: Trap

2. OS TLB miss handler:
   - Extract VPN from VA;
   - Do page table lookup;
   - If present and valid:
     - get PFN, update TLB;
     - Return from trap

3. Resume execution
   - (@PC of trapping instruction);
   - Instruction is retried;
   - Results in TLB hit

Figure B.5: **TLB Miss Flow without Virtualization**

layer of indirection: each OS maps virtual-to-physical addresses via its per-process page tables; the VMM maps the resulting physical mappings to underlying machine addresses via its per-OS page tables. Figure B.4 depicts this extra level of indirection.

In the figure, there is just a single virtual address space with four pages, three of which are valid (0, 2, and 3). The OS uses its page table to map these pages to three underlying physical frames (10, 3, and 8, respectively). Underneath the OS, the VMM performs a further level of indirection, mapping PFNs 3, 8, and 10 to machine frames 6, 10, and 5 respectively. Of course, this picture simplifies things quite a bit; on a real system, there would be $V$ operating systems running (with $V$ likely greater than one), and thus $V$ VMM page tables; further, on top of each running operating system $O_S$, there would be a number of processes $P_i$ running ($P_i$ likely in the tens or hundreds), and hence $P_i$ (per-process) page tables within $O_S$.

To understand how this works a little better, let’s recall how address translation works in a modern paged system. Specifically, let’s discuss what happens on a system with a software-managed TLB during address translation. Assume a user process generates an address (for an instruction fetch or an explicit load or store); by definition, the process generates a virtual address, as its address space has been virtualized by the OS. As you know by now, it is the role of the OS, with help from the hardware, to turn this into a physical address and thus be able to fetch the desired contents from physical memory.

Assume we have a 32-bit virtual address space and a 4-KB page size. Thus, our 32-bit address is chopped into two parts: a 20-bit virtual page number (VPN), and a 12-bit offset. The role of the OS, with help from the hardware TLB, is to translate the VPN into a valid physical page frame number (PFN) and thus produce a fully-formed physical address which can be sent to physical memory to fetch the proper data. In the common case, we expect the TLB to handle the translation in hardware, thus mak-
Process Operating System Virtual Machine Monitor

1. Load from mem TLB miss: Trap

2. VMM TLB miss handler: Call into OS TLB handler (reducing privilege)

3. OS TLB miss handler:
   - Extract VPN from VA;
   - Do page table lookup;
   - If present and valid, get PFN, update TLB

4. Trap handler:
   - Unprivileged code trying to update the TLB;
   - OS is trying to install VPN-to-PFN mapping;
   - Update TLB instead with VPN-to-MFN (privileged);
   - Jump back to OS (reducing privilege)

5. Return from trap

6. Trap handler:
   - Unprivileged code trying to return from a trap;
   - Return from trap

7. Resume execution (@PC of instruction);
   - Instruction is retried;
   - Results in TLB hit

Figure B.6: TLB Miss Flow with Virtualization

As you can see, a TLB miss causes a trap into the OS, which handles the fault by looking up the VPN in the page table and installing the translation in the TLB.

With a virtual machine monitor underneath the OS, however, things again get a little more interesting. Let’s examine the flow of a TLB miss again (see Table B.6 for a summary). When a process makes a virtual memory reference and misses in the TLB, it is not the OS TLB miss handler that runs; rather, it is the VMM TLB miss handler, as the VMM is the true privileged owner of the machine. However, in the normal case, the VMM TLB handler doesn’t know how to handle the TLB miss, so it immediately jumps into the OS TLB miss handler; the VMM knows the location of this handler because the OS, during “boot”, tried to install its own trap handlers. The OS TLB miss handler then runs, does a page ta-
Our discussion has centered around software-managed TLBs and the work that needs to be done when a miss occurs. But you might be wondering: how does the virtual machine monitor get involved with a hardware-managed TLB? In those systems, the hardware walks the page table on each TLB miss and updates the TLB as need be, and thus the VMM doesn’t have a chance to run on each TLB miss to sneak its translation into the system. Instead, the VMM must closely monitor changes the OS makes to each page table (which, in a hardware-managed system, is pointed to by a page-table base register of some kind), and keep a shadow page table that instead maps the virtual addresses of each process to the VMM’s desired machine pages [AA06]. The VMM installs a process’s shadow page table whenever the OS tries to install the process’s OS-level page table, and thus the hardware chugs along, translating virtual addresses to machine addresses using the shadow table, without the OS even noticing.

This set of actions also hints at how a VMM must manage the virtualization of physical memory for each running OS; just like the OS has a page table for each process, the VMM must track the physical-to-machine mappings for each virtual machine it is running. These per-machine page tables need to be consulted in the VMM TLB miss handler in order to determine which machine page a particular “physical” page maps to, and even, for example, if it is present in machine memory at the current time (i.e., the VMM could have swapped it to disk).

Finally, as you might notice from this sequence of operations, TLB misses on a virtualized system become quite a bit more expensive than in a non-virtualized system. To reduce this cost, the designers of Disco added a VMM-level “software TLB”. The idea behind this data structure is simple. The VMM records every virtual-to-physical mapping that it sees the OS try to install; then, on a TLB miss, the VMM first consults its software TLB to see if it has seen this virtual-to-physical mapping before, and what the VMM’s desired virtual-to-machine mapping should be. If the VMM finds the translation in its software TLB, it simply installs the virtual-to-machine mapping directly into the hardware TLB, and thus skips all the back and forth in the control flow above [B+97].
In many situations, it is good to assume that the OS cannot be modified in order to work better with virtual machine monitors (for example, because you are running your VMM under an unfriendly competitor’s operating system). However, this is not always the case, and when the OS can be modified (as we saw in the example with demand-zeroing of pages), it may run more efficiently on top of a VMM. Running a modified OS to run on a VMM is generally called para-virtualization [WSG02], as the virtualization provided by the VMM isn’t a complete one, but rather a partial one requiring OS changes to operate effectively. Research shows that a properly-designed para-virtualized system, with just the right OS changes, can be made to be nearly as efficient a system without a VMM [BD+03].

The Information Gap

Just like the OS doesn’t know too much about what application programs really want, and thus must often make general policies that hopefully work for all programs, the VMM often doesn’t know too much about what the OS is doing or wanting; this lack of knowledge, sometimes called the information gap between the VMM and the OS, can lead to various inefficiencies [B+97]. For example, an OS, when it has nothing else to run, will sometimes go into an idle loop just spinning and waiting for the next interrupt to occur:

```c
while (1)  
    ; // the idle loop
```

It makes sense to spin like this if the OS is in charge of the entire machine and thus knows there is nothing else that needs to run. However, when a VMM is running underneath two different OSes, one in the idle loop and one usefully running user processes, it would be useful for the VMM to know that one OS is idle so it can give more CPU time to the OS doing useful work.

Another example arises with demand zeroing of pages. Most operating systems zero a physical frame before mapping it into a process’s address space. The reason for doing so is simple: security. If the OS gave one process a page that another had been using without zeroing it, an information leak across processes could occur, thus potentially leaking sensitive information. Unfortunately, the VMM must zero pages that it gives to each OS, for the same reason, and thus many times a page will be zeroed twice, once by the VMM when assigning it to an OS, and once by the OS when assigning it to a process. The authors of Disco had no great solution to this problem: they simply changed the OS (IRIX) to not zero pages that it knew had been zeroed by the underlying VMM [B+97].
**TIP: USE IMPLICIT INFORMATION**

Implicit information can be a powerful tool in layered systems where it is hard to change the interfaces between systems, but more information about a different layer of the system is needed. For example, a block-based disk device might like to know more about how a file system above it is using it; similarly, an application might want to know what pages are currently in the file-system page cache, but the OS provides no API to access this information. In both these cases, researchers have developed powerful inferencing techniques to gather the needed information implicitly, *without* requiring an explicit interface between layers [AD+01,S+03]. Such techniques are quite useful in a virtual machine monitor, which would like to learn more about the OSes running above it without requiring an explicit API between the two layers.

There are many other similar problems to these described here. One solution is for the VMM to use inference (a form of implicit information) to overcome the problem. For example, a VMM can detect the idle loop by noticing that the OS switched to low-power mode. A different approach, seen in para-virtualized systems, requires the OS to be changed. This more explicit approach, while harder to deploy, can be quite effective.

### B.6 Summary

Virtualization is in a renaissance. For a multitude of reasons, users and administrators want to run multiple OSes on the same machine at the same time. The key is that VMMs generally provide this service transparently; the OS above has little clue that it is not actually controlling the hardware of the machine. The key method that VMMs use to do so is to extend the notion of limited direct execution; by setting up the hardware to enable the VMM to interpose on key events (such as traps), the VMM can completely control how machine resources are allocated while preserving the illusion that the OS requires.

You might have noticed some similarities between what the OS does for processes and what the VMM does for OSes. They both virtualize the hardware after all, and hence do some of the same things. However, there is one key difference: with the OS virtualization, a number of new abstractions and nice interfaces are provided; with VMM-level virtualization, the abstraction is identical to the hardware (and thus not very nice). While both the OS and VMM virtualize hardware, they do so by providing completely different interfaces; VMMs, unlike the OS, are not particularly meant to make the hardware easier to use.

There are many other topics to study if you wish to learn more about virtualization. For example, we didn’t even discuss what happens with I/O, a topic that has its own new and interesting issues when it comes to
virtualized platforms. We also didn’t discuss how virtualization works when running “on the side” with your OS in what is sometimes called a “hosted” configuration. Read more about both of these topics if you’re interested [SVL01]. We also didn’t discuss what happens when a collection of operating systems running on a VMM uses too much memory.

Finally, hardware support has changed how platforms support virtualization. Companies like Intel and AMD now include direct support for an extra level of virtualization, thus obviating many of the software techniques in this chapter. Perhaps, in a chapter yet-to-be-written, we will discuss these mechanisms in more detail.
References

[AA06] “A Comparison of Software and Hardware Techniques for x86 Virtualization” by Keith Adams and Ole Agesen. ASPLOS ’06, San Jose, California. A terrific paper from two VMware engineers about the surprisingly small benefits of having hardware support for virtualization. Also an excellent general discussion about virtualization in VMware, including the crazy binary-translation tricks they have to play in order to virtualize the difficult-to-virtualize x86 platform.

[AD+01] “Information and Control in Gray-box Systems” by Andrea C. Arpaci-Dusseau and Remzi H. Arpaci-Dusseau. SOSP ’01, Banff, Canada. Our own work on how to infer information and even exert control over the OS from application level, without change to the OS. The best example therein: determining which file blocks are cached using a probabilistic probe-based technique; doing so allows applications to better utilize the cache, by first scheduling work that will result in hits.


[BD+03] “Xen and the Art of Virtualization” by Paul Barham, Boris Dragovic, Keir Fraser, Steven Hand, Tim Harris, Alex Ho, Rolf Neugebauer, Ian Pratt, Andrew Warfield. SOSP ’03, Bolton Landing, New York. The paper that shows that with para-virtualized systems, the overheads of virtualized systems can be made to be incredibly low. So successful was this paper on the Xen virtual machine monitor that it launched a company.

[B+97] “Disco: Running Commodity Operating Systems on Scalable Multiprocessors” by Edouard Bugnion, Scott Devine, Kinshuk Govil, Mendel Rosenblum. SOSP ’97. The paper that reintroduced the systems community to virtual machine research; well, perhaps this is unfair as Bressoud and Schneider [BS95] also did, but here we began to understand why virtualization was going to come back. What made it even clearer, however, is when this group of excellent researchers started VMware and made some billions of dollars.

[B+17] “Hardware and Software Support for Virtualization” by Edouard Bugnion, Jason Nieh, Dan Tsafir. Morgan and Claypool, 2017. Undoubtedly the best place to get the latest on how virtualization works in modern systems. Unfortunately, you’ll have to read a short book to figure it out!

[BS95] “Hypervisor-based Fault-tolerance” by Thomas C. Bressoud, Fred B. Schneider. SOSP ’95. One of the earliest papers to bring back the hypervisor, which is just another term for a virtual machine monitor. In this work, however, such hypervisors are used to improve system tolerance of hardware faults, which is perhaps less useful than some of the more practical scenarios discussed in this chapter; however, still quite an intriguing paper in its own right.


[SVL01] “Virtualizing I/O Devices on VMware Workstation’s Hosted Virtual Machine Monitor” by Jeremy Sugerman, Ganesh Venkitachalam and Beng-Hong Lim. USENIX ’01, Boston, Massachusetts. Provides a good overview of how I/O works in VMware using a hosted architecture which exploits many native OS features to avoid reimplementing them within the VMM.

[V98] by VMware corporation. Available: http://www.vmware.com/ . This may be the most useless reference in this book, as you can clearly look this up yourself. Anyhow, the company was founded in 1998 and is a leader in the field of virtualization.

[S+03] “Semantically-Smart Disk Systems” by Muthiah Sivathanu, Vijayan Prabhakaran, Florintina I. Popovic, Timothy E. Denehy, Andrea C. Arpaci-Dusseau, Remzi H. Arpaci-Dusseau. FAST ’03, San Francisco, California, March 2003. Our work again, this time showing how a dumb block-based device can infer much about what the file system above it is doing, such as deleting a file. The technology used therein enables interesting new functionality within a block device, such as secure delete, or more reliable storage.

[WSG02] “Scale and Performance in the Denali Isolation Kernel” by Andrew Whitaker, Marianne Shaw, and Steven D. Gribble. OSDI ’02, Boston, Massachusetts. The paper that introduces the term paravirtualization. Although one can argue that Bugnion et al. [B+97] introduce the idea of paravirtualization in the Disco paper, Whitaker et al. take it further and show how the idea can be more general than what was thought before.