PERSISTENCE: JOURNALING, LFS

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CS 537, Spring 2019
Project 5: Out now. Last Project!

Discussion today: Project 5
AGENDA / LEARNING OUTCOMES

How to use journaling to maintain consistency during crashes?

How to design a filesystem that performs better for small writes?
RECAP
FS POINTERS: INODE, DIRECTORIES

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**FFS POLICY SUMMARY**

File inodes: allocate in same group with dir

Dir inodes: allocate in new group with fewer used inodes than average group

First data block: allocate near inode

Other data blocks: allocate near previous block

Large file data blocks: after 48KB, go to new group.

Move to another group (w/ fewer than avg blocks) every subsequent 1MB.
Solution #1:

FSCK = file system checker

Strategy:

After crash, scan whole disk for contradictions and “fix” if needed
Keep file system off-line until FSCK completes

For example, how to tell if data bitmap block is consistent?

Read every valid inode+indirect block
If pointer to data block, the corresponding bit should be 1; else bit is 0
FSCK CHECKS

Do superblocks match?
Is the list of free blocks correct?
Do number of dir entries equal inode link counts?
Do different inodes ever point to same block?
Are there any bad block pointers?
Do directories contain “.” and “..”?
…
BUNNY 18

https://tinyurl.com/cs537-sp19-bunny18
BUNNY 18

Inode Bitmap : 10000000
Inode Table : [size=1,ptr=0,type=d] [ ] [ ] [ ] [ ] [ ] [ ]
Data Bitmap : 10000000
Data : [("." 0), (".." 0)] [ ] [ ] [ ] [ ] [ ] [ ]

There are only eight inodes and eight data blocks; each of these is managed by a corresponding bitmap. The inode table shows the contents of each of eight inodes, with an individual inode enclosed between square brackets; in the initial state above, only inode 0 is in use. When an inode is used, its size and pointer field are updated accordingly (in this question, files can only be one block in size; hence a single inode pointer); when an inode is free, it is marked with a pair of empty brackets like these “[]”. Note there are only two file types: directories (type=d) and regular files (type=r). Data blocks are either “in use” and filled with something, or “free” and marked accordingly with “[]”. Directory contents are shown in data blocks as comma-separated lists of tuples like: (“name”, inode number). The root inode number is zero.

(a) INITIAL STATE: state(i) as above to FINAL STATE (a):

Inode Bitmap : 11000000
Inode Table : [size=1,ptr=0,type=d] [size=0,ptr=-,type=r] [ ] [ ] [ ] [ ] [ ]
Data Bitmap : 10000000
Data : [ ("." 0), (".." 0), ("f" 1) ] [ ] [ ] [ ] [ ] [ ] [ ]

Operation that caused this change?
(f) FILE SYSTEM STATE: Consistent or inconsistent? If inconsistent, how to fix?

Inode Bitmap : 11100000
Inode Table : [size=1,ptr=0,type=d] [size=1,ptr=1,type=r] [size=1,ptr=2,type=r] [] [] [] [] [] []
Data Bitmap : 11100000
Data : [("." 0), (".." 0)] [DATA] [DATA] [] [] [] [] [] []

Not consistent. Inode 1, 2 are not pointed to by any dir. Put them in lost+found/0001.
Delete the inode 1, 2 data 1, 2 update bitmaps.
CONSISTENCY SOLUTION #2: JOURNALING

Goals
- Ok to do some *recovery work* after crash, but not to read entire disk
- Don’t move file system to just any consistent state, get *correct* state

Atomicity
- Definition of atomicity for *concurrency*: operations in critical sections are not interrupted by operations on related critical sections
- Definition of atomicity for *persistence*: collections of writes are not interrupted by crashes; either (all new) or (all old) data is visible
ORDERING FOR CONSISTENCY

transaction: write C to block 4; write T to block 6

write order

Barrier before appear
Correctness after
Parallelism

Journal → log
Tx Start block 4
Tx: End 4, 6
Write to block 4, 6
Tx Valid → 0

Journal can be reused
Checkpointing
Rollback replay
Rollback A
A
B
Barriers
1) Before journal commit, ensure journal entries complete
2) Before checkpoint, ensure journal commit complete
3) Before free journal, ensure in-place updates complete

write order
9,10,11
12
4,6
12
Can we get rid of barrier between (9, 10, 11) and 12?

In last transaction block, store checksum of rest of transaction.

During recovery: If checksum does not match, treat as not valid.

Write order before 9, 10, 11, 12.

Compute checksum.
**OTHER OPTIMIZATIONS**

**Batched updates**
- If two files are created, inode bitmap, inode etc. get written twice
- Mark as dirty in-memory and batch updates

**Circular log**
- Journal: T1, T2, T3, T4
- 0 to 28 MB

**Diagram notes**
- Wait for timer (Soo)
- Batch all ops into 1 transaction
- Bitmap once
- Inode once
- Write Tn
- Linked list
- Add, last, start
- Checkpt, finish, more head
How to avoid writing all disk blocks twice?

Observation: Most of writes are user data (esp sequential writes)

Strategy: journal all metadata, including superblock, bitmaps, inodes, indrects, directories

For regular data, write it back whenever convenient.
METADATA JOURNALING

transaction: append to inode 1

Crash !?!
Still only journal metadata

But write data **before** the transaction!
What happens if crash now?
B indicates D currently free, I does not point to D;
Lose D, but that might be acceptable
SUMMARY

Crash consistency: Important problem in filesystem design!

Two main approaches

FSCK: Fix file system image after crash happens

Too slow and only ensures consistency

Journaling

Write a transaction before in-place updates

Checksum, batching

Ordered journal avoids data writes
BUNNY 19: IDENTIFY THE KIND OF JOURNALING

We need to write data in block 5,6. Inode is block 4, bitmap in block 2. Journal is from blocks 8 to 15.

Write 5,6
Write 8, 9, 10
Barrier
Write 11
Barrier
Write 4, 2

Ordered journal

Write 8, 9, 10, 11, 12
Barrier
Write 13
Barrier
Write 2, 4, 5, 6

Data Journaling

Write 8, 9, 10, 11, 12, 13
Barrier
Write 2, 4, 5, 6

Checksum Optimistic

https://tinyurl.com/cs537-sp19-bunny19
LOG STRUCTURED FILE SYSTEM (LFS)
Motivation:
- Growing gap between sequential and random I/O performance
- RAID-5 especially bad with small random writes

Idea: use disk purely sequentially

Design for writes to use disk sequentially – how?
WHERE DO INODES GO?
LFS STRATEGY

File system buffers writes in main memory until “enough” data

- How much is enough?
- Enough to get good sequential bandwidth from disk (MB)

Write buffered data sequentially to new segment on disk

Never overwrite old info: old copies left behind
WHAT ELSE IS DIFFERENT FROM FFS?

What data structures has LFS removed?
- allocation structs: data + inode bitmaps

How to do reads?
- Inodes are no longer at fixed offset
  - Use **imap** structure to map:
    - inode number => inode location on disk
READING IN LFS

1. Read the Checkpoint region
2. Read all imap parts, cache in mem
3. To read a file:
   1. Lookup inode location in imap
   2. Read inode
   3. Read the file block

Similar to FFS
WHAT TO DO WITH OLD DATA?

Old versions of files $\rightarrow$ garbage

Approach 1: garbage is a feature!
  - Keep old versions in case user wants to revert files later
  - Versioning file systems
  - Example: Dropbox

Approach 2: garbage collection
GARBAGE COLLECTION

Need to reclaim space:
1. When no more references (any file system)
2. After newer copy is created (COW file system)

LFS reclaims **segments** (not individual inodes and data blocks)
- Want future overwrites to be to sequential areas
- Tricky, since segments are usually partly valid
GARBAGE COLLECTION

disk segments: USED USED USED USED FREE FREE

60% 10% 95% 35%
GARbage COLLECTION

When moving data blocks, copy new inode to point to it
When move inode, update imap to point to it
GARBAGE COLLECTION

General operation:
   Pick M segments, compact into N (where N < M).

Mechanism:
   How does LFS know whether data in segments is valid?

Policy:
   Which segments to compact?
GARBAGE COLLECTION MECHANISM

Is an inode the latest version?
- Check imap to see if this inode is pointed to
- Fast!

Is a data block the latest version?
- Scan ALL inodes to see if any point to this data
- Very slow!

How to track information more efficiently?
- **Segment summary** lists inode and data offset corresponding to each data block in segment (reverse pointers)
(N, T) = SegmentSummary[A];

inode = Read(imap[N]);

if (inode[T] == A)
    // block D is alive
else
    // block D is garbage
General operation:
Pick M segments, compact into N (where N < M).

Mechanism:
The segments
Use segment summary, imap to determine liveness

Policy:
Which segments to compact?
• clean most empty first
• clean coldest (ones undergoing least change)
• more complex heuristics…
CRASH RECOVERY

What data needs to be recovered after a crash?
– Need imap (lost in volatile memory)

Better approach?
– Occasionally save to checkpoint region the pointers to imap pieces

How often to checkpoint?
– Checkpoint often: random I/O
– Checkpoint rarely: lose more data, recovery takes longer
– Example: checkpoint every 30 secs
CRASH RECOVERY

memory:

ptrs to imap pieces

checkpoint

disk:

S0 S1 S2 S3

after last checkpoint

tail after last checkpoint
CHECKPOINT SUMMARY

Checkpoint occasionally (e.g., every 30s)

Upon recovery:
- read checkpoint to find most imap pointers and segment tail
- find rest of imap pointers by reading past tail

What if crash during checkpoint?
CHECKPOINT STRATEGY

Have two checkpoint regions
Only overwrite one checkpoint at a time
Use checksum/timestamps to identify newest checkpoint

disk: [ ] [ ] S0 S1 S2 S3
LFS SUMMARY

Journaling:
  Put final location of data wherever file system chooses
  (usually in a place optimized for future reads)

LFS:
  Puts data where it’s fastest to write, assume future reads cached in memory

Other COW file systems: WAFL, ZFS, btrfs
NEXT STEPS

Next class: Distributed systems

Project 5 is out!
Discussion: Project 5 walkthrough