

# **CONCURRENCY: LOCKS**

Shivaram Venkataraman

CS 537, Spring 2023

# ADMINISTRIVIA

- Access slides and notes at ~arebello instead of ~shivaram

<https://pages.cs.wisc.edu/~shivaram/cs537-sp23/>



<https://pages.cs.wisc.edu/~arebello/cs537-sp23/>

- Piazza and TAs for everything else

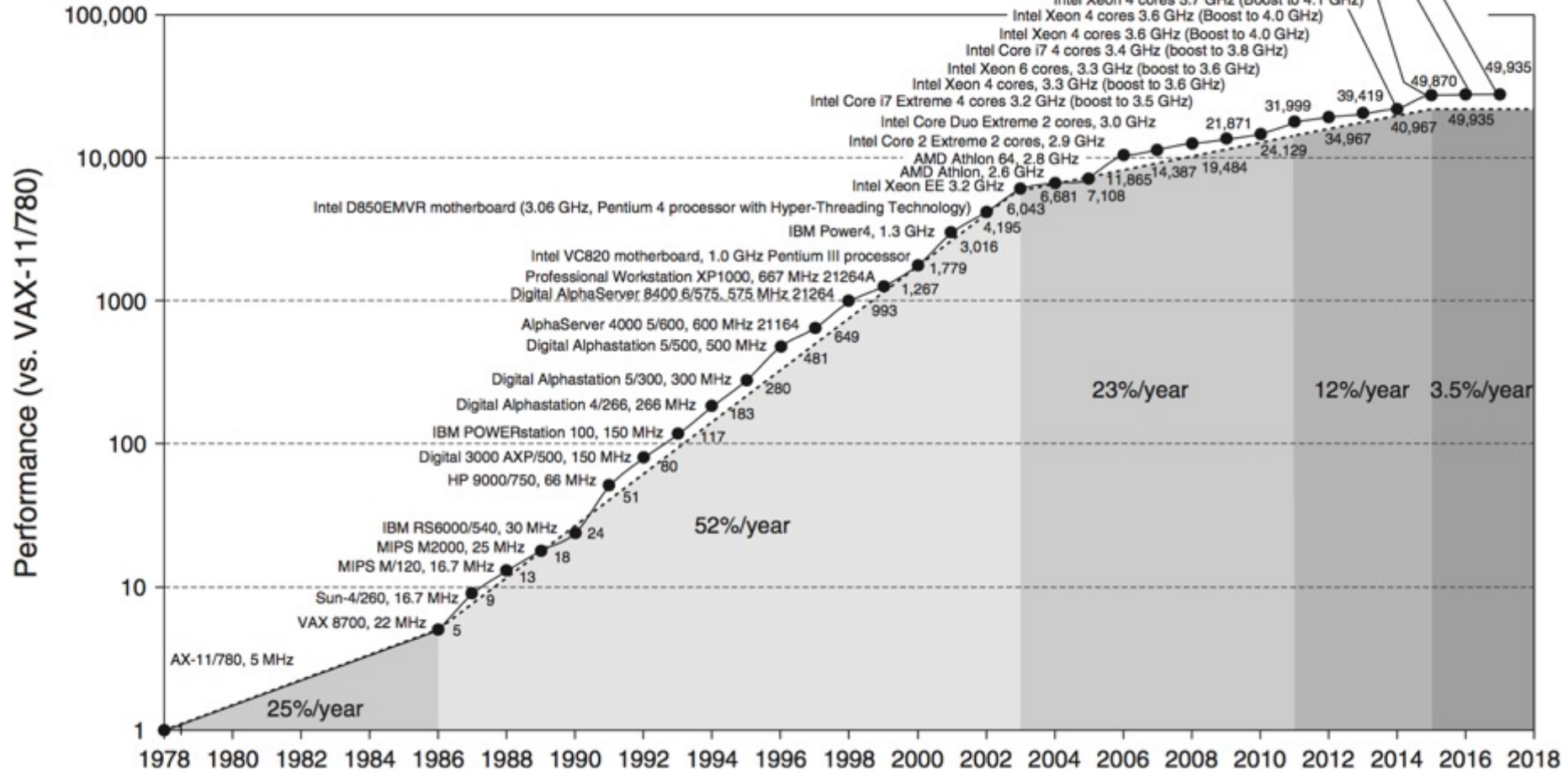
# AGENDA / LEARNING OUTCOMES

## Concurrency

What are some of the challenges in concurrent execution?  
How do we design locks to address this?

**RECAP**

# MOTIVATION FOR CONCURRENCY



# TIMELINE VIEW

$x = x + 1$

**Thread 1**

mov 0x123, %eax

10

← CTX switch →

add %0x1, %eax 10 + 1

mov %eax, 0x123

11

10

$x = x + 2$

**Thread 2**

mov 0x123, %eax

add %0x2, %eax

mov %eax, 0x123

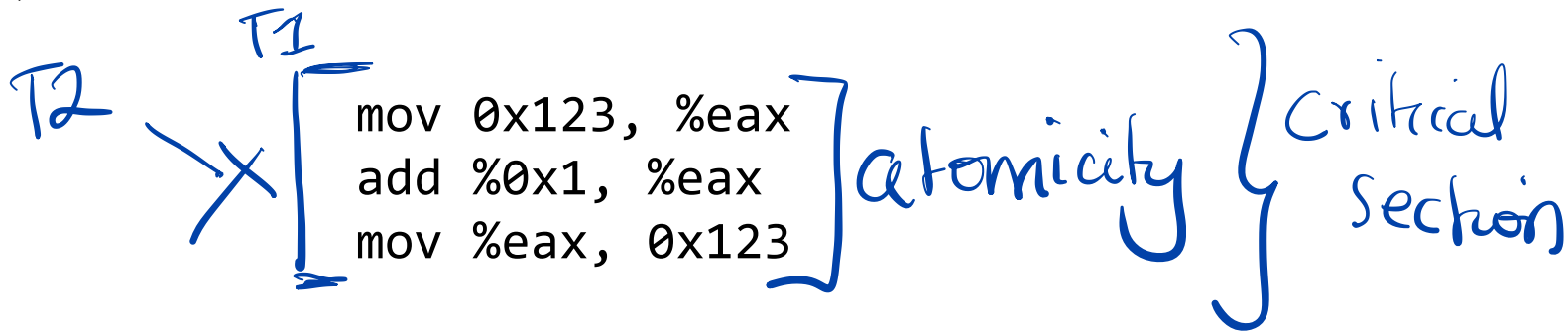
10  
12

12

# WHAT DO WE WANT?

Want 3 instructions to execute as an uninterruptable group

That is, we want them to be atomic



More general: Need mutual exclusion for critical sections  
if thread A is in critical section C, thread B isn't  
(okay if other threads do unrelated work)

# LOCK IMPLEMENTATION GOALS

API

lock() acquire()

unlock() release()

T1 T2 T3

## Correctness

- *Mutual exclusion* 

Only one thread in critical section at a time

- *Progress* (deadlock-free)

If several simultaneous requests, must allow one to proceed

- *Bounded* (starvation-free)

Must eventually allow each waiting thread to enter

Fairness: Each thread waits for same amount of time

Performance: CPU is not used unnecessarily



# IMPLEMENTING SYNCHRONIZATION

**Atomic operation:** No other instructions can be interleaved

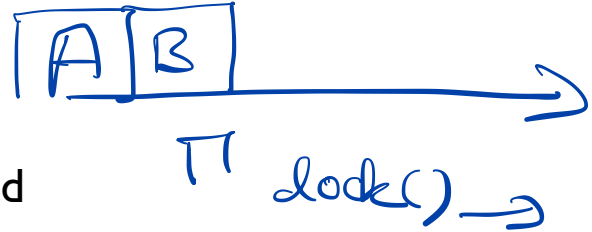
Approaches

- Disable interrupts
- Locks using loads/stores
- Using special hardware instructions

# IMPLEMENTING LOCKS: W/ INTERRUPTS

Turn off interrupts for critical sections

- Prevent dispatcher from running another thread
- Code between interrupts executes atomically



```
void acquire(lockT *l) {  
    disableInterrupts();  
}
```

```
void release(lockT *l) {  
    enableInterrupts();  
}
```

Disadvantages?

Only works on uniprocessors

Process can keep control of CPU for arbitrary length

Cannot perform other necessary work

# IMPLEMENTING LOCKS: W/ LOAD+STORE

Code uses a single **shared** lock variable

T1

```
// shared variable
boolean lock = false;
void acquire(Boolean *lock) {
    while (*lock) /* wait */ ;
    *lock = true; ←
}

```

T2 acquire()

```
void release(Boolean *lock) {
    *lock = false;
} →

```

T1

Does this work? What situation can cause this to not work?

# RACE CONDITION WITH LOAD AND STORE

\*lock == 0 initially

*acquire()*

Thread 1

Thread 2

while(\*lock == 1)

           *lock is 0*

\*lock = 1

while(\*lock == 1) *lock is 0*  
\*lock = 1 ←

Both threads grab lock!

Problem: Testing lock and setting lock are not atomic

# XCHG: ATOMIC EXCHANGE OR TEST-AND-SET (TAS)

A 100

`xchg(RA, 20)`

How do we solve this ? **Get help from the hardware!**

```
// xchg(int *addr, int newval)
// return what was pointed to by addr
// at the same time, store newval into addr
```

```
int xchg(int *addr, int newval) {
    int old = *addr;
    *addr = newval;
    return old;
}
```

single atomic instruction

```
movl 4(%esp), %edx
movl 8(%esp), %eax
xchgl (%edx), %eax
ret
```

# LOCK IMPLEMENTATION WITH XCHG

```
typedef struct __lock_t {  
    int flag;  
} lock_t;
```

```
void init(lock_t *lock) {  
    lock->flag = ??;  
}
```

```
void acquire(lock_t *lock) {  
    ????  
    // spin-wait (do nothing)  
}
```

```
void release(lock_t *lock) {  
    lock->flag = ??;  
}
```

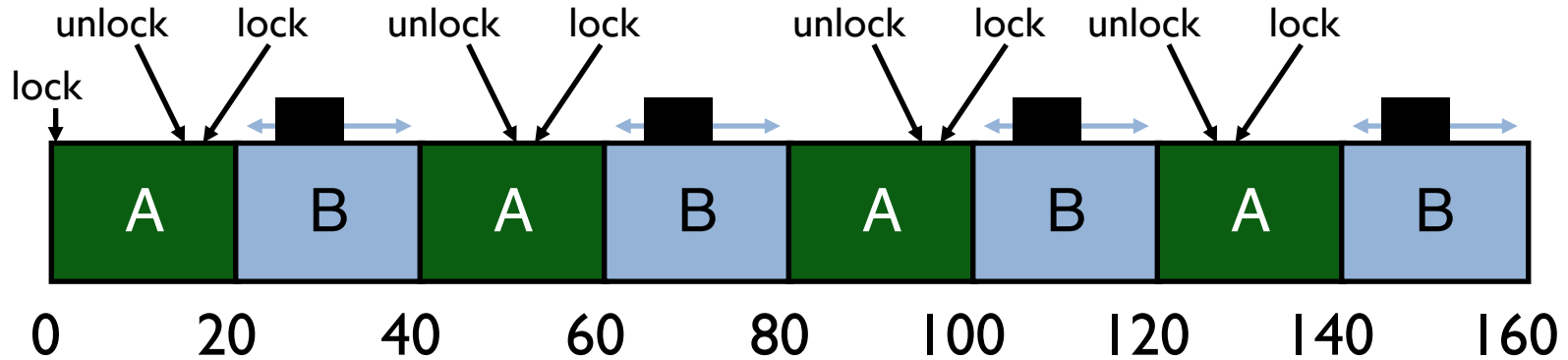
```
int xchg(int *addr, int newval)
```

# OTHER ATOMIC HW INSTRUCTIONS

```
int CompareAndSwap(int *addr, int expected, int new) {  
    int actual = *addr;  
    if (actual == expected)  
        *addr = new;  
    return actual;  
}
```

```
void acquire(lock_t *lock) {  
    while(CompareAndSwap(&lock->flag, 0, 1) == 0) ;  
    // spin-wait (do nothing)  
}
```

# BASIC SPINLOCKS ARE UNFAIR



Scheduler is unaware of locks/unlocks!



# FAIRNESS: TICKET LOCKS

Idea: reserve each thread's turn to use a lock.

Each thread spins until their turn.

Use new atomic primitive, fetch-and-add

```
int FetchAndAdd(int *ptr) {  
    int old = *ptr;  
    *ptr = old + 1;  
    return old;  
}
```

Acquire: Grab ticket; Spin while not thread's ticket != turn

Release: Advance to next turn

# TICKET LOCK EXAMPLE

A lock():

B lock():

C lock():

A unlock():

A lock():

B unlock():

C unlock():

A unlock():

Ticket



Turn



# TICKET LOCK IMPLEMENTATION

```
typedef struct __lock_t {
    int ticket;
    int turn;
}

void lock_init(lock_t *lock) {
    lock->ticket = 0;
    lock->turn = 0;
}
```

```
void acquire(lock_t *lock) {
    int myturn = FAA(&lock->ticket);
    // spin
    while (lock->turn != myturn);
}

void release(lock_t *lock) {
    FAA(&lock->turn);
}
```

# SPINLOCK PERFORMANCE

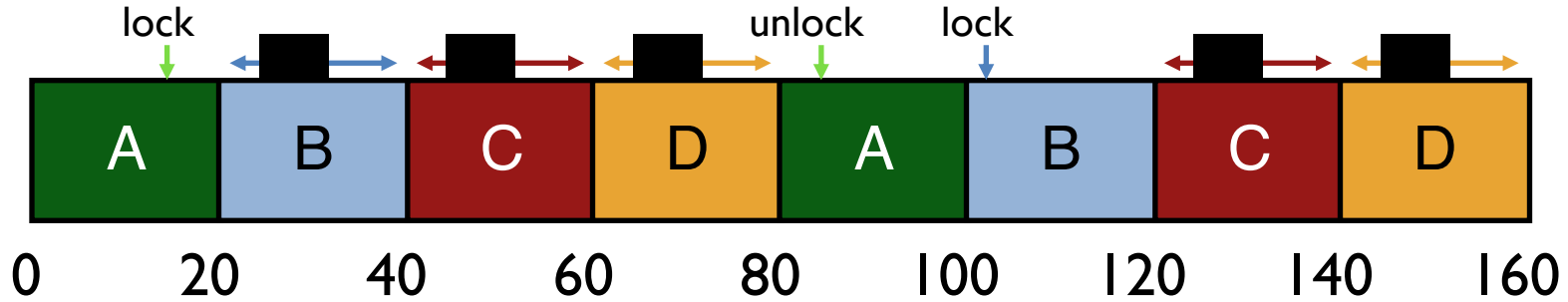
Fast when...

- many CPUs
- locks held a short time
- advantage: avoid context switch

Slow when...

- one CPU
- locks held a long time
- disadvantage: spinning is wasteful

# CPU SCHEDULER IS IGNORANT



CPU scheduler may run **B, C, D** instead of **A**  
even though **B, C, D** are waiting for **A**

# TICKET LOCK WITH YIELD

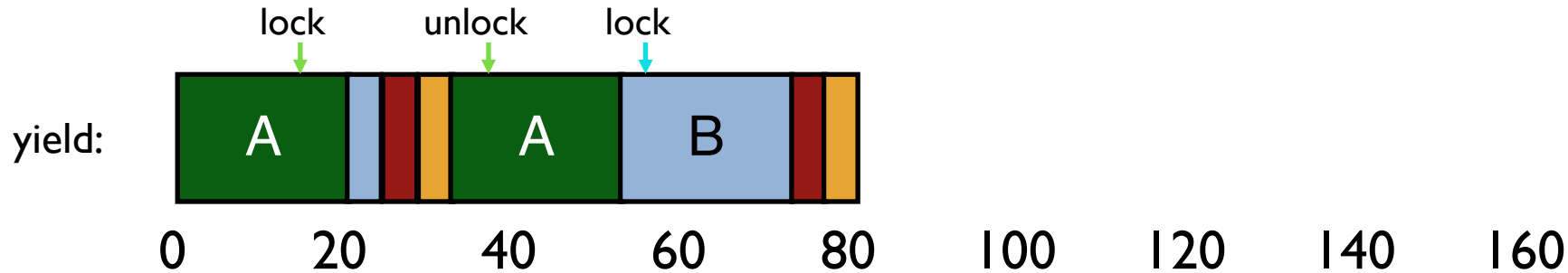
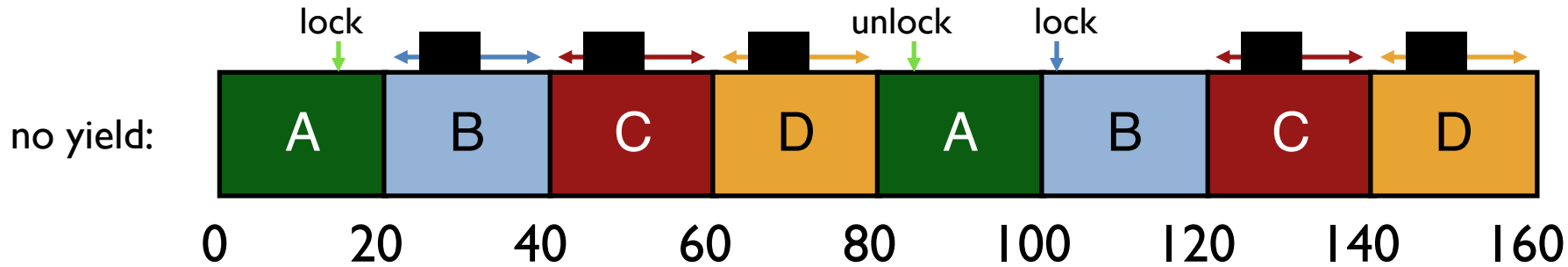
```
typedef struct __lock_t {
    int ticket;
    int turn;
}

void lock_init(lock_t *lock) {
    lock->ticket = 0;
    lock->turn = 0;
}
```

```
void acquire(lock_t *lock) {
    int myturn = FAA(&lock->ticket);
    while (lock->turn != myturn)
        yield();
}

void release(lock_t *lock) {
    FAA(&lock->turn);
}
```

# YIELD INSTEAD OF SPIN



# QUIZ 16

<https://tinyurl.com/cs537-sp23-quiz15>

```
a = 1
int b = xchg(&a, 2)
int c = CAS(&b, 2, 3)
int d = CAS(&b, 1, 3)
```

Final values

Assuming round-robin scheduling,  
10ms time slice. Processes A, B, C,  
D, E, F, G, H in the system

Timeline

A: lock() ... compute ... unlock()

B: lock() ... compute ... unlock()

C: lock()







# SPINLOCK PERFORMANCE

Waste of CPU cycles?

Without yield:  $O(\text{threads} * \mathbf{time\_slice})$

With yield:  $O(\text{threads} * \mathbf{context\_switch})$

Even with yield, spinning is slow with high thread contention

Next improvement: Block and put thread on waiting queue instead of spinning

# LOCK IMPLEMENTATION: BLOCK WHEN WAITING

Remove waiting threads from scheduler runnable queue  
(e.g., `park()` and `unpark(threadID)`)

Scheduler runs any thread that is **runnable**

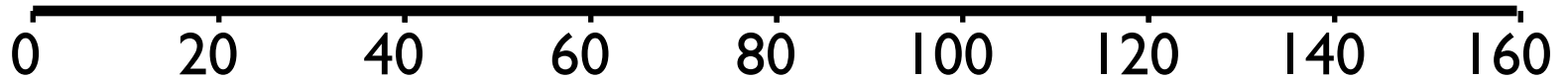
A B D contend for lock, C is not contending

A has 60 ms worth of work  
20ms is the timeslice

RUNNABLE: A, B, C, D

RUNNING:

WAITING:



# LOCK IMPLEMENTATION: BLOCK WHEN WAITING

```
typedef struct {
    bool lock = false;
    bool guard = false;
    queue_t q;
} LockT;
```

```
void acquire(LockT *l) {
    while (XCHG(&l->guard, true));
    if (l->lock) {
        qadd(l->q, tid);
        l->guard = false;
        park();    // blocked
    } else {
        l->lock = true;
        l->guard = false;
    }
}
```

```
void release(LockT *l) {
    while (XCHG(&l->guard, true));
    if (qempty(l->q)) l->lock=false;
    else unpark(qremove(l->q));
    l->guard = false;
}
```

# LOCK IMPLEMENTATION: BLOCK WHEN WAITING

(a) Why is **guard** used?

(b) Why okay to **spin** on guard?

(c) In `release()`, why not set `lock=false` when `unpark`?

(d) Is there a race condition?

```
void acquire(LockT *l) {
    while (XCHG(&l->guard, true));
    if (l->lock) {
        qadd(l->q, tid);
        l->guard = false;
        park();    // blocked
    } else {
        l->lock = true;
        l->guard = false;
    }
}
```

```
void release(LockT *l) {
    while (XCHG(&l->guard, true));
    if (qempty(l->q)) l->lock=false;
    else unpark(qremove(l->q));
    l->guard = false;
}
```

# RACE CONDITION

**Thread 1** (in lock)

```
if (l->lock) {  
    qadd(l->q, tid);  
    l->guard = false;
```

```
park();    // block
```

**Thread 2** (in unlock)

```
while (TAS(&l->guard, true));  
if (qempty(l->q)) // false!!  
else unpark(qremove(l->q));  
l->guard = false;
```

# BLOCK WHEN WAITING: FINAL CORRECT LOCK

```
typedef struct {  
    bool lock = false;  
    bool guard = false;  
    queue_t q;  
} LockT;
```

*setpark + unpark*  
*park() ← ignore*

**setpark()** fixes race condition

```
void acquire(LockT *l) {  
    while (TAS(&l->guard, true));  
    if (l->lock) {  
        qadd(l->q, tid);  
        setpark(); // notify of plan  
        l->guard = false;  
        park(); // unless unpark()  
    } else {  
        l->lock = true;  
        l->guard = false;  
    }  
}  
  
void release(LockT *l) {  
    while (TAS(&l->guard, true));  
    if (qempty(l->q)) l->lock=false;  
    else unpark(qremove(l->q));  
    l->guard = false;  
}
```



# SPIN-WAITING VS BLOCKING

Each approach is better under different circumstances

## Uniprocessor

Waiting process is scheduled → Process holding lock isn't

Waiting process should always relinquish processor

Associate queue of waiters with each lock (as in previous implementation)

## Multiprocessor

Waiting process is scheduled → Process holding lock might be

Spin or block depends on how long,  $t$ , before lock is released

Lock released quickly → Spin-wait

Lock released slowly → Block

Quick and slow are relative to context-switch cost,  $C$

# WHEN TO SPIN-WAIT? WHEN TO BLOCK?

If know how long,  $t$ , before lock released, can determine optimal behavior

How much CPU time is wasted when spin-waiting?

$t$

How much wasted when blocking?

What is the best action when  $t < C$ ?

When  $t > C$ ?

Problem:

Requires knowledge of future; too much overhead to do any special prediction

# TWO-PHASE WAITING

Theory: Bound worst-case performance; ratio of actual/optimal

When does worst-possible performance occur?

Spin for very long time  $t \gg C$

Ratio:  $t/C$  (unbounded)

Algorithm: Spin-wait for  $C$  then block  $\rightarrow$  Factor of 2 of optimal

Two cases:

$t < C$ : optimal spin-waits for  $t$ ; we spin-wait  $t$  too

$t > C$ : optimal blocks immediately (cost of  $C$ );

we pay spin  $C$  then block (cost of  $2C$ );

$2C / C \rightarrow 2$ -competitive algorithm

# NEXT STEPS

Midterm on Thursday 3/2

No class on Thursday

Next Tuesday: Condition Variables