

CS 744: SPARK STREAMING

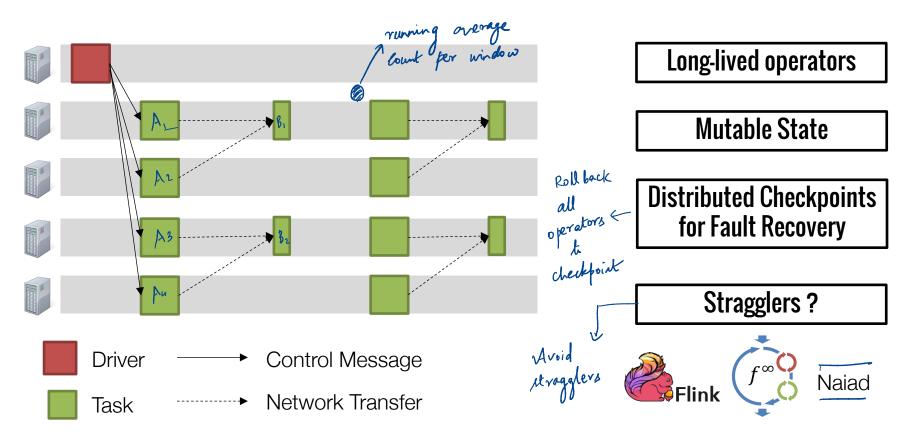
Shivaram Venkataraman Fall 2020

ADMINISTRIVIA

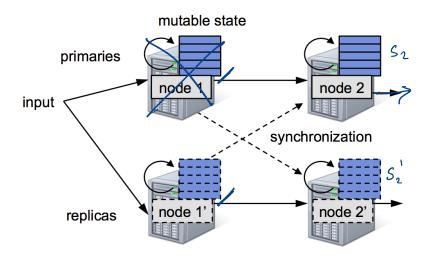
- Midterm grades this week ASAP
- Course Projects feedback Hor CRP

U Hopefully you are working on this! (1) Assign grades for project proposale (2) mid rementer vipdate -> Nov 20th

CONTINUOUS OPERATOR MODEL



CONTINUOUS OPERATORS



Replication to provide fault tolerance =) Multiple copies (say 2?) of each operator 2x resources required Overhead 9 (1) (2) Replicos need to be in sync => S2 and S2' should be the > reed to nake sure reflicas are synchronized during normal computation overhead

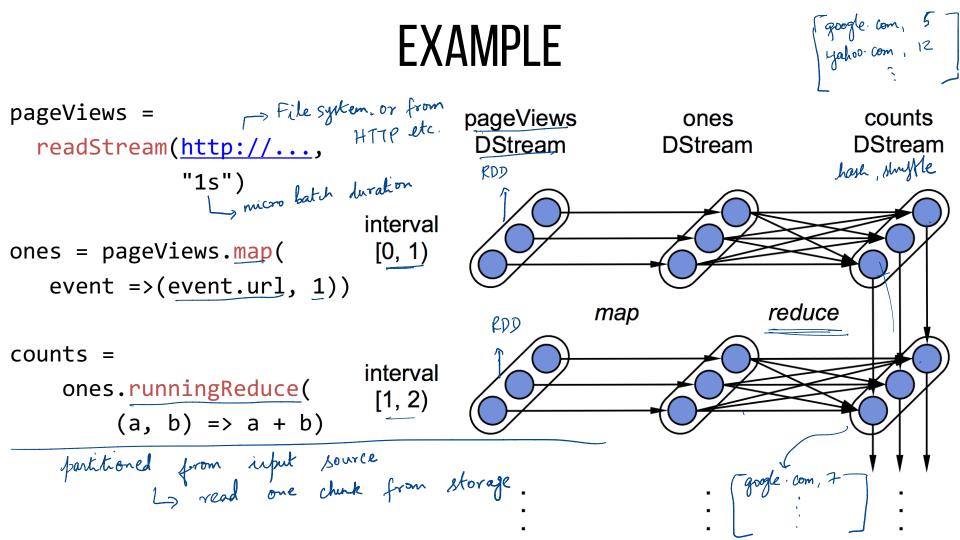
SPARK STREAMING: GOALS

- Scalability to hundreds of nodes To handle high tput streams Ι.
- Minimal cost beyond base processing (no replication) 2.

Second-scale recovery from faults and stragglers 4.

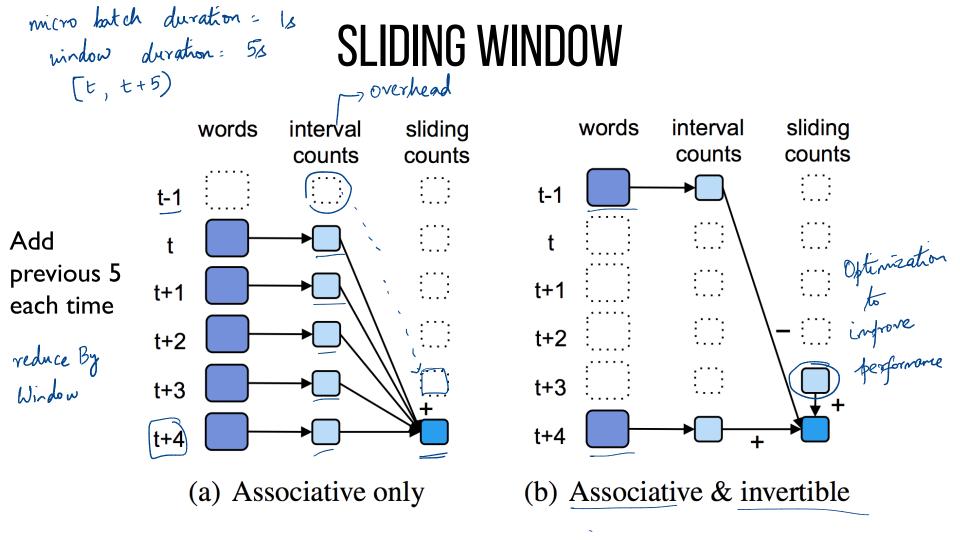
$$t_{1} < ---> t_{2}$$

NISCRFTI7FD STRFAMS (DSTREAMS) micro bostch duration = 1 s -> overheads in - every micro batch botch computation run short, deterministic tasks to compute incremental output batch operation state → t = 1: input - every batch operation is stateless input 1 immutable state is stored as immutable → t = 2: dataset - each part of the state can be recovered independently D-Stream 2 D-Stream 1 ron-deterministic is opposite -> Use lineage to do recovery I if you re-run output night made <- random < 5 : 0 offpat 0 else output 1 deterministic be difficult



DSTREAM API

Transformations Stateless: map, reduce, group By, join -> similar to RDD API Stateful: stiding window("5s") \rightarrow RDDs with data in [0,5), [1,6), [2,7) reduceByWindow("5s", (a, b) => a + b) tereates a stiding window and aggregates RDDs that belong to it.



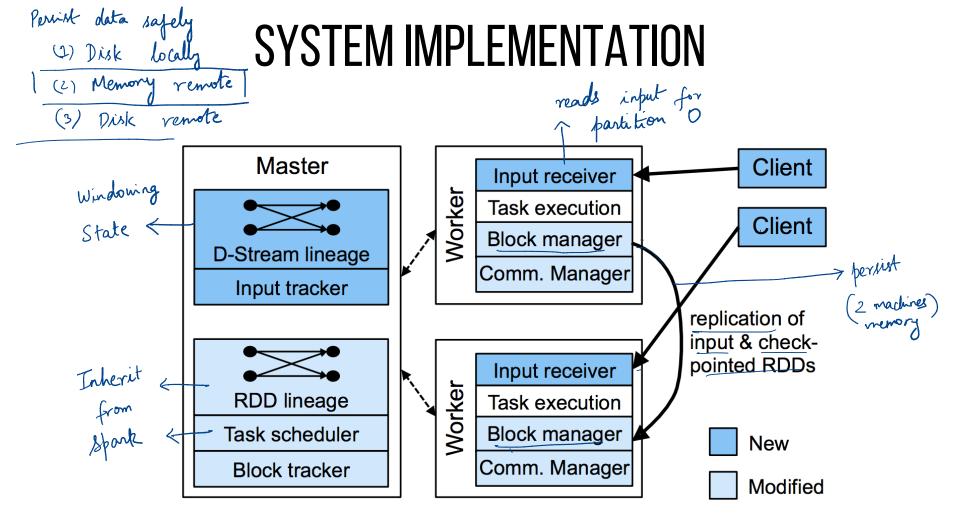
SIAIF MANAGEMENT

Servicen which has

all events for a

Tracking State: streams of (Key, Event) \rightarrow (Key, State) \rightarrow

user satisfying some criteria [login -> logout] events.track(user (key, ev) => 1, \rightarrow Initiatize state (key, st, ev) => ev == Exit ? null : 1, update: given preventate and a new event return new state State Timeout: forget old states "30s" Atate event Oper t = 1 to 2



OPTIMIZATIONS (0,1)

Map

(1,2) ♀ schedule before ♀ prer finishes

Timestep Pipelining - Juse together may operations

No barrier across timesteps unless needed

Tasks from the next timestep scheduled before current finishes

Checkpointing

Async I/O, as RDDs are immutable

Forget lineage after checkpoint

Can be done by storing to remote memory

FAULT TOLERANCE: PARALLEL RECOVERY

Worker failure

WN

N9

W3

- Need to recompute state RDDs stored on worker these might be Re-execute tasks running on the worker used for future tegy

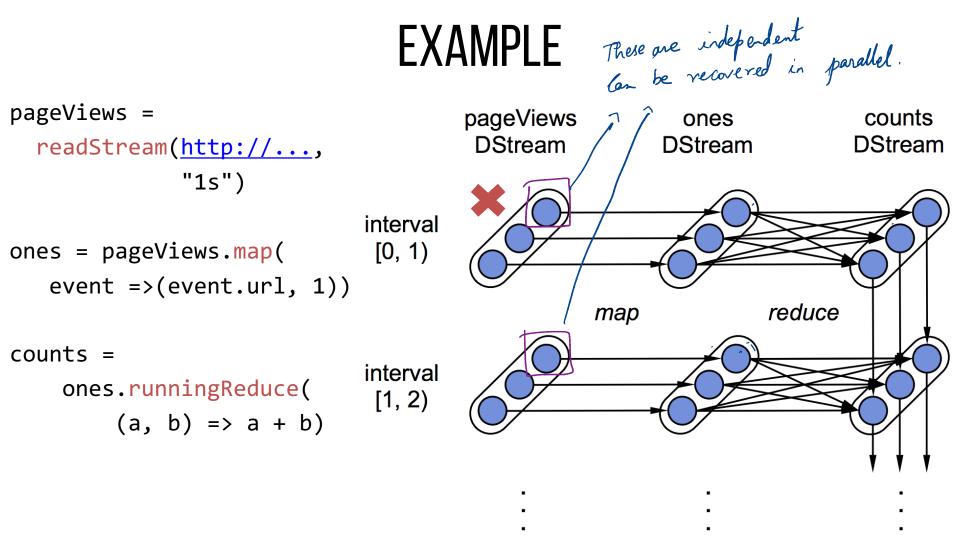
Strategy

- Run all independent recovery tasks in parallel
- Parallelism from partitions in timestep and across timesteps

t=152 5: 0 10 1 any dependencies parallelism across partition W2 N3

W4 w5

6



FAULT TOLERANCE

Straggler Mitigation

Use speculative execution \rightarrow fall back

Task runs more than 1.4x longer than median task \rightarrow straggler

Master Recovery ---- Runs forever MR Master -> retry the job on failure

- At each timestep, save graph of DStreams and Scala function objects --- Workers connect to a new master and report their RDD partitions - Note: No problem if a given RDD is computed twice (determinism).

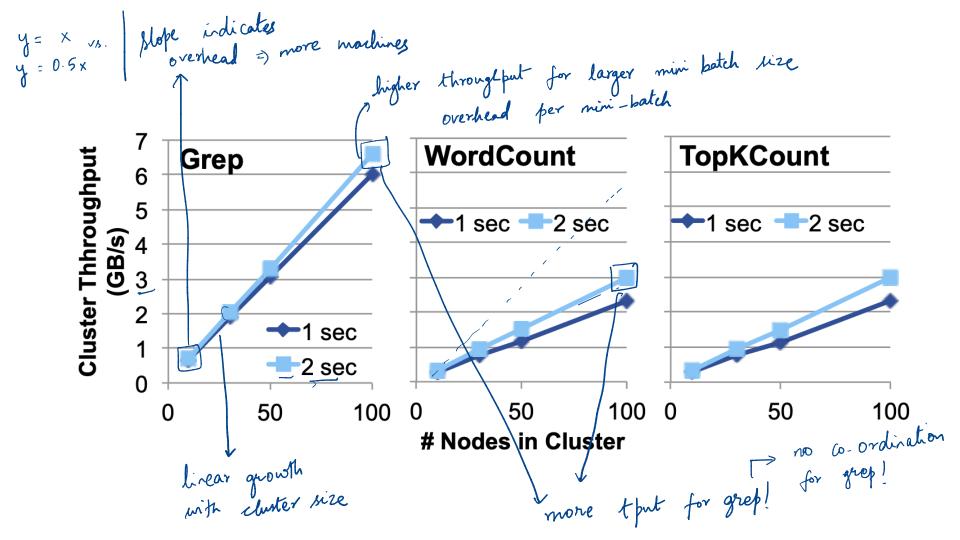
SUMMARY

Micro-batches: New approach to stream processing

Simplifies fault tolerance, straggler mitigation

Unifying batch, streaming analytics

DISCUSSION https://forms.gle/eiqbjJTU95bMQLtm9



If the latency bound was made to 100ms, how do you think the above figure would change? What could be the reasons for it?

too low latery - low tput overheads in task scheduling tracking RDDs etc. if we go to 1000 mochines => overheads could be l linear scaling night not last?

Consider the pros and cons of approaches in Naiad vs Spark Streaming. What application properties would you use to decide which system to choose?

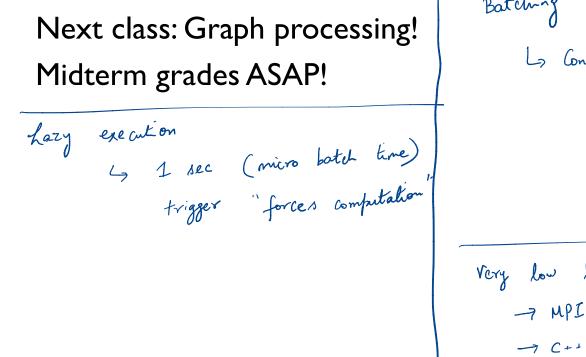
Naid latency sensitive

Spark Streaming

failurers skragglers

iterative + streaming work flows

NEXT STEPS



Batching ?! La Continuous operator] event = not optimal B (10 events> L> batching Very low latency -7 MPI - based -> C++ Actor model L) Erlang -> Telephone