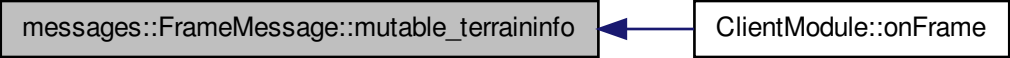


messages::FrameMessage::mutable_terraininfo



```
graph LR; A[ClientModule::onFrame] --> B[messages::FrameMessage::mutable_terraininfo];
```

The diagram consists of two rectangular boxes. The box on the left is shaded gray and contains the text 'messages::FrameMessage::mutable_terraininfo'. The box on the right is white and contains the text 'ClientModule::onFrame'. A dark blue arrow points from the right box to the left box, indicating a call or relationship from the right-hand entity to the left-hand entity.

ClientModule::onFrame