

① (a), (b), (c)

$$\begin{array}{c}
 v_1 = v_2 = v_3 = v_4 = \\
 x_1 \quad x_2 \quad x_3 \quad x_4 \quad | \\
 \hline
 -u_1 \quad y_1 = \begin{array}{|c|c|c|c|c|} \hline 3 & 1 & 0 & -2 & -3 \\ \hline \end{array} \\
 -u_2 \quad y_2 = \begin{array}{|c|c|c|c|c|} \hline -1 & 1 & 2 & 1 & -1 \\ \hline \end{array} \\
 -u_3 \quad y_3 = \begin{array}{|c|c|c|c|c|} \hline 1 & 3 & 4 & 0 & -5 \\ \hline \end{array}
 \end{array}$$

②

$$\begin{array}{c}
 u_1 = u_2 = u_3 = u_4 = 1 \\
 x_1 \quad y_1 \quad x_2 \quad x_3 \quad x_4 \quad | \\
 \hline
 -u_1 \quad y_1 = \begin{array}{|c|c|c|c|c|} \hline 4 & 1 & -2 & -3 & -2 \\ \hline \end{array} \\
 -u_2 \quad x_2 = \begin{array}{|c|c|c|c|c|} \hline 1 & 1 & -2 & -1 & 1 \\ \hline \end{array} \\
 -u_3 \quad y_3 = \begin{array}{|c|c|c|c|c|} \hline 4 & 3 & -2 & -3 & -2 \\ \hline \end{array}
 \end{array}$$

$$\begin{array}{c}
 u_1 = u_2 = u_3 = u_4 = \\
 y_1 \quad y_2 \quad x_2 \quad x_{41} \quad | \\
 \hline
 -u_1 \quad x_1 = \begin{array}{|c|c|c|c|c|} \hline \frac{1}{4} & \frac{1}{4} & \frac{1}{2} & \frac{3}{4} & \frac{1}{2} \\ \hline \end{array} \\
 -u_2 \quad x_2 = \begin{array}{|c|c|c|c|c|} \hline \frac{1}{4} & \frac{3}{4} & \frac{3}{2} & \frac{1}{4} & \frac{3}{2} \\ \hline \end{array} \\
 -u_3 \quad y_3 = \begin{array}{|c|c|c|c|c|} \hline 1 & 2 & 0 & 0 & 0 \\ \hline \end{array}
 \end{array}$$

③ (a) Row dependence: $A_3 = A_1 + 2A_2$.
 (b) Column dependence revealed by v_i relationship.
 One such relationship is

④

$$A_{.3} = -\frac{1}{2} A_{.1} + \frac{3}{2} A_{.2}$$

Another is

$$A_{.4} = -\frac{3}{4} A_{.1} + \frac{1}{4} A_{.2}$$

⑤ (c) Get solutions by setting $y_1 = y_2 = y_3 = 0$:

$$\begin{aligned}
 x_1 &= \frac{1}{2} x_3 + \frac{3}{4} x_4 + \frac{1}{2} \\
 x_2 &= -\frac{3}{2} x_3 + \frac{1}{4} x_4 + \frac{3}{2}
 \end{aligned}$$

Define $x_3 = \lambda$, $x_4 = \mu$, get

$$S = \left\{ \begin{pmatrix} \frac{1}{2} \\ \frac{3}{2} \\ 0 \\ 0 \end{pmatrix} + \lambda \begin{pmatrix} \frac{1}{2} \\ -\frac{3}{2} \\ 1 \\ 0 \end{pmatrix} + \mu \begin{pmatrix} \frac{3}{4} \\ -\frac{1}{4} \\ 0 \\ 1 \end{pmatrix} \text{ for } \lambda, \mu \in \mathbb{R} \right\}$$

(2)

| | x_1 | x_2 | x_3 | 1 |
|---------|-------|-------|-------|----|
| $x_2 =$ | 1 | 1 | -1 | 1 |
| $x_1 =$ | (2) | 1 | 6 | -6 |
| $z =$ | 3 | 2 | 9 | 0 |

(a)

| | x_1 | x_2 | x_3 | 1 |
|---------|---------------|----------------|-------|---|
| $x_2 =$ | $\frac{1}{2}$ | $\frac{1}{2}$ | -4 | 4 |
| $x_1 =$ | $\frac{1}{2}$ | $-\frac{1}{2}$ | (-3) | 3 |
| $z =$ | $\frac{3}{2}$ | $\frac{1}{2}$ | 0 | 9 |

(2)

optimal!

solution is $x = \begin{pmatrix} 3 \\ 0 \\ 0 \end{pmatrix}$

(b) Get additional solutions by pivoting on x_3 column.

| | x_1 | x_2 | x_3 | 1 |
|---------|---------------|----------------|----------------|---|
| $x_1 =$ | $\frac{1}{6}$ | $\frac{7}{6}$ | $\frac{4}{3}$ | 0 |
| $x_2 =$ | $\frac{1}{6}$ | $-\frac{1}{6}$ | $-\frac{1}{3}$ | 1 |
| $z =$ | $\frac{3}{2}$ | $\frac{1}{2}$ | 0 | 9 |

(2)

solution: $\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$

full set of solutions is the convex hull of these two vertices.

(2)

$$\left\{ \begin{array}{l} [3, 2] \\ 0 \\ (1, -2) \end{array} \right\} : x \in [0, 1]$$

③

| | x_1 | x_2 | x_3 | 1 |
|---------|-------|-------|-------|----|
| $x_4 =$ | 2 | -3 | 1 | -4 |
| $x_5 =$ | 3 | -5 | 1 | -9 |
| $z =$ | 4 | 8 | 2 | 0 |

Scheme II - Pivot

x_4 with x_3
 \uparrow equality \uparrow free

| | x_1 | x_2 | x_3 | 1 |
|---------|-------|-------|-------|----|
| $x_3 =$ | -2 | 3 | 1 | 4 |
| $x_5 =$ | 1 | -2 | 1 | -5 |
| $z =$ | 0 | 12 | 2 | 8 |

remove x_4 column

| | x_1 | x_2 | 1 |
|---------|-------|-------|----|
| $x_3 =$ | -2 | 3 | 4 |
| $x_5 =$ | 1 | -2 | -5 |
| $z =$ | 0 | 12 | 8 |

move x_3 to end

| | x_1 | x_2 | 1 |
|---------|-------|-------|----|
| $x_5 =$ | 1 | -2 | -5 |
| $z =$ | 0 | 12 | 8 |
| $x_3 =$ | -2 | 3 | 4 |

one step of dual simplex selects first (1,1)

| | x_5 | x_2 | 1 |
|---------|-------|-------|----|
| $x_1 =$ | 1 | 2 | 5 |
| $z =$ | 0 | 12 | 8 |
| $x_3 =$ | -2 | -1 | -6 |

optimal $x =$

④

set $x_5 = \alpha \geq 0$ to get a ray of solutions

$$\begin{aligned} x_1 &= \alpha + 5 \\ x_2 &= 0 \\ x_3 &= -2\alpha - 6 \end{aligned}$$

$$x = \left\{ \begin{pmatrix} 5 \\ 0 \\ -6 \end{pmatrix} + \alpha \begin{pmatrix} 1 \\ 0 \\ -2 \end{pmatrix} : \alpha \geq 0 \right\}$$

$$b) \max 4u_1 + 9u_2 \quad \text{s.t.} \quad 2u_1 + 3u_2 \leq 4$$

$$-3u_1 - 5u_2 \leq 6$$

$$u_1 + u_2 \geq 2$$

$$u_2 \geq 0$$

(2)

$$\textcircled{4} \text{ (a) } \max_{u \in \mathbb{R}} u \quad \text{s.t.} \quad \begin{aligned} ua &\leq c \\ -uf &\leq -d \\ u &\geq 0 \end{aligned}$$

which is equivalent to

$$\max_u u \quad \text{s.t.} \quad \begin{aligned} ua &\leq c \\ uf &\geq d \\ u &\geq 0 \end{aligned}$$

②

(b) No. u is bounded above by

$$\textcircled{1} \quad \min_{i=1, \dots, n} \left(\frac{c_i}{a_i} \right)$$

(c) Yes. If the lower bound

$$\max_i \frac{d_i}{f_i}$$

①

is greater than upper bound $\min \frac{c_i}{a_i}$

then dual can be infeasible

$$\text{(d) Solution is } u^* = \min \frac{c_i}{a_i}$$

$$\text{provided that } \min \frac{c_i}{a_i} \geq \max \frac{d_i}{f_i}$$

①

Yes, uniquely defined by this formula.

e) KKT conditions are

$$0 \leq c - au \perp x \geq 0$$

(2)

$$0 \leq ut - d \perp y \geq 0$$

$$0 \leq a^T x - f^T y - 1 \perp u \geq 0$$

$$\text{need } x_i = 0 \text{ if } \frac{c_i}{a_i} > ut$$

$$\text{need } y_i = 0 \text{ if } \frac{d_i}{f_i} < ut$$