

CS726, Fall 2016
Midterm Examination

Thursday, October 27, 2016, 7:15pm–9:15pm.

Answer ALL questions below. One handwritten sheet of notes (written front and back) is allowed. EXPLAIN ALL YOUR ANSWERS.

1. Consider the unconstrained optimization problem $\min_{x \in \mathbb{R}^n} f(x)$, for smooth convex f . Suppose that the problem has a solution x^* , with optimal value $f^* = f(x^*)$. Suppose that we have an algorithm that yields the following guaranteed improvement at each iteration:

$$f(x^{k+1}) - f^* \leq \left(1 - \frac{\hat{c}}{k+1}\right) (f(x^k) - f^*), \quad k = 0, 1, 2, \dots,$$

for some constant $\hat{c} \in (0, 1)$. Find, approximately, the number of iterations K required to satisfy $f(x^K) - f^* \leq \epsilon$, for a given $\epsilon > 0$. (Hint: You can use the fact that $\sum_{i=1}^K (1/i) \approx \log K$, for large integers K .)

2. Suppose that $f : \mathbb{R}^n \rightarrow \mathbb{R}$ is a smooth convex function, and consider the optimization problem $\min_{x \in \mathbb{R}^n} f(x)$. Suppose that an algorithm generates a sequence of iterates $\{x^k\}$ such that $f(x^{k+1}) < f(x^k)$ for all k , and $\nabla f(x^k) \rightarrow 0$.
 - (a) Can we say that “the sequence $\{x^k\}$ converges to a solution of the optimization problem”? Prove this claim if it is true, and give a counterexample if it is false.
 - (b) If f is *strongly convex*, we know that the optimization problem has a unique solution x^* , and that the level set $\mathcal{L} := \{x \mid f(x) \leq f(x^0)\}$ is compact. With the additional assumption that f is strongly convex, can we say that $\lim_{k \rightarrow \infty} x^k = x^*$? Explain.
3. Consider the unconstrained optimization problem $\min_{x \in \mathbb{R}^n} f(x)$, for smooth f . Suppose we implement a line search method in which at iterate x^k , the search direction p^k is defined to have a single nonzero element, that is the *negative of the element of largest absolute value in $\nabla f(x^k)$* . That is, we choose $i_k \in \{1, 2, \dots, n\}$ such that

$$|[\nabla f(x^k)]_{i_k}| \geq |[\nabla f(x^k)]_i|, \quad \text{for all } i = 1, 2, \dots, n,$$

and set

$$p^k = -[\nabla f(x^k)]_{i_k} e_{i_k},$$

where e_{i_k} is the vector which has all zero components except for a 1 in position i_k . Find a constant $\bar{\epsilon} > 0$ such that

$$\nabla f(x^k)^T p^k \leq -\bar{\epsilon} \|p^k\| \|\nabla f(x^k)\|.$$

4. Suppose that for some algorithm for minimizing a smooth convex function f , whose minimizer is x^* , there is a constant $\gamma > 0$ such that

$$f(x^{k+1}) \leq f(x^k) - \gamma \|\nabla f(x^k)\|^2.$$

Suppose too that there is a constant $c > 0$ such that

$$\|\nabla f(x)\| \geq c[f(x) - f(x^*)]^{1/2},$$

where x^* is the solution of the problem. Find a value of the constant $r \in (0, 1)$ such that

$$f(x^{k+1}) - f(x^*) \leq r (f(x^k) - f(x^*)).$$

5. Suppose that f is a quadratic function of the form

$$f(x) = \frac{1}{2}x^T Ax - b^T x,$$

where A is symmetric positive definite. Suppose that for some starting point x^0 , we initialize the conjugate gradient method by setting

$$r^0 = Ax^0 - b, \quad p^0 = -r^0.$$

Suppose that the conjugate gradient method subsequently generates search directions p^1, p^2, \dots .

- (a) The search directions p^0, p^1, p^2 are known to be *conjugate*. Write down the conjugacy condition. (You just need to state the definition; you don't need to prove that this property holds.)
- (b) Consider the problem of minimizing f over the subspace spanned by the first k search directions, where $k < n$. To do this, we define a function $h(\sigma)$ for $\sigma = (\sigma_0, \sigma_1, \dots, \sigma_{k-1})^T \in \mathbb{R}^k$ by

$$h(\sigma) = f(x^0 + \sigma_0 p^0 + \sigma_1 p^1 + \dots + \sigma_{k-1} p^{k-1}).$$

Show that $h : \mathbb{R}^k \rightarrow \mathbb{R}$ is a quadratic function, of the form

$$h(\sigma) = \frac{1}{2}\sigma^T B\sigma - c^T \sigma + \beta,$$

and write down the matrix B , the vector c , and the scalar β .

- (c) Assuming that $p^i \neq 0$ for all $i = 0, 1, \dots, k-1$, write down the optimal values of σ_i , $i = 0, 1, \dots, k-1$, that is the values that minimize h .