Adversarially-Trained Nonnegative Matrix Factorization



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Adversarially-Trained NMF

Nonnegative Matrix Factorization (Lee and Seung, 1999)

Given a nonnegative data matrix $\mathbf{V} \in \mathbb{R}^{F \times N}_+$, approximate \mathbf{V} as

 $\mathbf{V} \approx \mathbf{W} \mathbf{H}$

where $\mathbf{W} \in \mathbb{R}^{F \times K}_+$ (basis) and $\mathbf{H} \in \mathbb{R}^{K \times N}_+$ (coefficient) matrices.

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One typically solves

 $\min_{\mathbf{W},\mathbf{H}\geq\mathbf{0}} D(\mathbf{V}\mid\mathbf{W}\mathbf{H}) \quad \text{e.g.} \quad D(\mathbf{V}\mid\mathbf{W}\mathbf{H}) = \left\|\mathbf{V}-\mathbf{W}\mathbf{H}\right\|_{\mathrm{F}}^{2},$

where $A \ge 0$ means that all the entries of A are nonnegative.

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 Adversarial training (Goodfellow et al., 2015; Madry et al., 2018; Tramèr et al., 2018)



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- Derive efficient algorithms for updating the adversary and (W, H).

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- Improve the predictive performance of NMF using adversarial training for matrix completion tasks.
- Derive efficient algorithms for updating the adversary and (W, H).
- Demonstrate the superior predictive performance of adversarially-trained NMF or AT-NMF over other methods on matrix completion tasks for three benchmark datasets.

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Formulation of AT-NMF

Consider an adversary that adds an arbitrary matrix $\mathbf{R} \in \mathbb{R}^{F \times N}_+$ to V to maximize the divergence between V and WH, AT-NMF is formulated as

$$\min_{\mathbf{W},\mathbf{H}\geq\mathbf{0}} \max_{\mathbf{R}\in\mathcal{R}} \|\mathbf{V}+\mathbf{R}-\mathbf{W}\mathbf{H}\|_{\mathrm{F}}^{2}$$

where the constraint set

$$\mathcal{R} = \left\{ \mathbf{R} : \|\mathbf{R}\|_{\mathrm{F}}^2 \leq \epsilon, \mathbf{V} + \mathbf{R} \geq \mathbf{0}
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- $\epsilon > 0$ is a constant indicating the adversary's power.
- To relax the problem, dualize the constraint $\|\mathbf{R}\|_{\mathrm{F}}^2 \leq \epsilon$ with Lagrange multiplier $\lambda > 0$, AT-NMF becomes

$$\min_{\mathbf{W},\mathbf{H}\geq\mathbf{0}} \max_{\mathbf{R}:\mathbf{V}+\mathbf{R}\geq\mathbf{0}} \|\mathbf{V}+\mathbf{R}-\mathbf{W}\mathbf{H}\|_{\mathrm{F}}^{2} - \lambda \|\mathbf{R}\|_{\mathrm{F}}^{2}.$$

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Let ÎV = WH, the inner maximization problem can be rewritten as a minimization problem as

$$\mathbf{R}^* = \underset{\mathbf{R}: \mathbf{V} + \mathbf{R} > \mathbf{0}}{\arg\min} - \|\mathbf{V} + \mathbf{R} - \hat{\mathbf{V}}\|_{\mathrm{F}}^2 + \lambda \|\mathbf{R}\|_{\mathrm{F}}^2$$

Let $\hat{\mathbf{V}} = \mathbf{W}\mathbf{H}$, the inner maximization problem can be rewritten as a minimization problem as

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Objective separates into FN independent terms

$$g(\mathbf{R}) = \sum_{f,n} \left[-(v_{fn} + r_{fn} - \hat{v}_{fn})^2 + \lambda r_{fn}^2 \right].$$

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Suffices to minimize each term inside over r_{fn} . By re-arranging:

$$\min_{\mathbf{r}_{fn}: v_{fn} + r_{fn} \ge 0} (\lambda - 1) \mathbf{r}_{fn}^2 - 2\mathbf{r}_{fn} (v_{fn} - \hat{v}_{fn})$$

• Can be solved in closed-form. For $\lambda \in [0, 1]$, $r_{fn} = \infty$; for $\lambda > 1$,

$$\mathbf{R}^* = \max\left\{\frac{\mathbf{V} - \hat{\mathbf{V}}}{\lambda - 1}, -\mathbf{V}\right\}$$

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■ After update of **R** to **R**^{*},

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fix $U := V + R^*$.

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■ After update of **R** to **R**^{*},

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fix $U := V + R^*$.

 Use majorization-minimization (MM) (Hunter and Lange, 2000) to update

$$\mathbf{H} \leftarrow \mathbf{H} \cdot \frac{\mathbf{W}^\top \mathbf{U}}{\mathbf{W}^\top \mathbf{W} \mathbf{H}} \quad \text{and} \quad \mathbf{W} \leftarrow \mathbf{W} \cdot \frac{\mathbf{U} \mathbf{H}^\top}{\mathbf{W} \mathbf{H} \mathbf{H}^\top}$$

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- \blacksquare Initialization of (\mathbf{W},\mathbf{H})
 - Sample each entry independently from Half-Normal distribution (with variance parameter $\gamma = 1$);
 - \blacksquare Run 5 standard MM steps on V to obtain W_{init} and $H_{\text{init}}.$

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- Initialization of (W, H)
 - Sample each entry independently from Half-Normal distribution (with variance parameter $\gamma = 1$);
 - \blacksquare Run 5 standard MM steps on V to obtain \mathbf{W}_{init} and $\mathbf{H}_{init}.$
- Termination (described in paper)

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Adversarially-Trained NMF

- $\alpha \in \{0.1, 0.2, \cdots, 0.8, 0.9\}$ denotes the fraction of held-out entries.
- $\Gamma \subset \{1, \cdots, F\} \times \{1, \cdots, N\}$ is the set of held-out entries of **V**.
- \hat{v}_{fn} is the prediction of v_{fn} .

Synthetic Dataset: Setup

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Synthetic Dataset: Metric and Results

Our performance metric is the root mean-squared error (RMSE)

$$\mathsf{RMSE} := \sqrt{\frac{1}{|\Gamma|} \sum_{(f,n) \in \Gamma} \left(v_{fn} - \hat{v}_{fn} \right)^2}$$

Systhetic dataset of F = 100, N = 50, and K = 5.

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	RMSE	of S	ynthetic	dataset
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α	NMF	ANMF	AT-NMF (2)	AT-NMF (3)	AT-NMF (5)
0.3	5.37 ± 0.02	6.78 ± 0.17	5.41 ± 0.12	5.11 ± 0.03	5.20 ± 0.02
0.4	5.62 ± 0.03	6.92 ± 0.17	5.54 ± 0.08	5.32 ± 0.09	5.42 ± 0.04
0.5	6.41 ± 0.01	7.44 ± 0.09	6.27 ± 0.11	6.05 ± 0.03	6.18 ± 0.02
0.6	6.74 ± 0.02	7.61 ± 0.09	6.47 ± 0.07	6.39 ± 0.03	6.53 ± 0.02
0.7	7.30 ± 0.01	7.99 ± 0.06	7.02 ± 0.04	6.94 ± 0.01	7.10 ± 0.02
0.8	7.87 ± 0.01	8.30 ± 0.06	7.69 ± 0.04	7.61 ± 0.03	7.71 ± 0.00
0.9	8.45 ± 0.01	8.58 ± 0.06	8.44 ± 0.02	8.34 ± 0.02	8.35 ± 0.02

CBCL Face Dataset: Parts Learned

• N = 2429 facial images with F = 361 pixels.

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CBCL Face Dataset: Parts Learned

• N = 2429 facial images with F = 361 pixels.

Parts learnt when $\alpha = 0.1$



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CBCL Face Dataset: Image Restoration

Image Restoration by AT-NMF



- (a) (b) (c) (d) (e) (f)
- (a) Original Image V;
- (b) Masked training image V;
- (c) Adversary's added-on masked image \mathbf{R}^* ;

(d) AT-masked image $V + R^*$ [Features (eyes, nose, lower cheeks) become more distinctive];

(e) Restored image using AT-NMF with $\lambda = 2$;

(f) Restored image using NMF.

CBCL Face Dataset: Training Losses

Training losses when $\alpha = 0.5$



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Hyperspectral Datasets

■ It includes the Moffet (Jet Propulsion Lab) and Madonna (Sheeren et al., 2011) datasets with F = 165 and F = 160 respectively and N = 2500.

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Hyperspectral Datasets

- It includes the Moffet (Jet Propulsion Lab) and Madonna (Sheeren et al., 2011) datasets with F = 165 and F = 160 respectively and N = 2500.
 - Effect of λ on the RMSE



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Formulation and algorithm for Adversarially-Trained NMF:

 $\min_{\mathbf{W},\mathbf{H}\geq\mathbf{0}} \max_{\mathbf{R}\in\mathcal{R}} \|\mathbf{V}+\mathbf{R}-\mathbf{W}\mathbf{H}\|_{\mathrm{F}}^{2}$

where $\mathcal{R} = \{\mathbf{R} : \|\mathbf{R}\|_F^2 \le \epsilon, \mathbf{V} + \mathbf{R} \ge \mathbf{0}\}$ or $\min_{\mathbf{W}, \mathbf{H} \ge \mathbf{0}} \max_{\mathbf{R}: \mathbf{V} + \mathbf{R} \ge \mathbf{0}} \|\mathbf{V} + \mathbf{R} - \mathbf{W}\mathbf{H}\|_F^2 - \lambda \|\mathbf{R}\|_F^2.$

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 Other divergence measures beyond the Frobenius norm , e.g., β-divergence (Févotte et al., 2009).

Formulation and algorithm for Adversarially-Trained NMF:

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■ Different bounded sets \mathcal{R} , e.g., $\{\mathbf{R} : \|\mathbf{R}\|_{p,q} \le \epsilon, \mathbf{V} + \mathbf{R} \ge \mathbf{0}\}$.

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Formulation and algorithm for Adversarially-Trained NMF:

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- Other divergence measures beyond the Frobenius norm , e.g., β-divergence (Févotte et al., 2009).
- Different bounded sets \mathcal{R} , e.g., $\{\mathbf{R} : \|\mathbf{R}\|_{p,q} \le \epsilon, \mathbf{V} + \mathbf{R} \ge \mathbf{0}\}$.
- Online NMF (Lefèvre et al., 2011; Mairal, 2015)?

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