



# Support Vector Machines Part 1

CS 760@UW-Madison





# Goals for the lecture

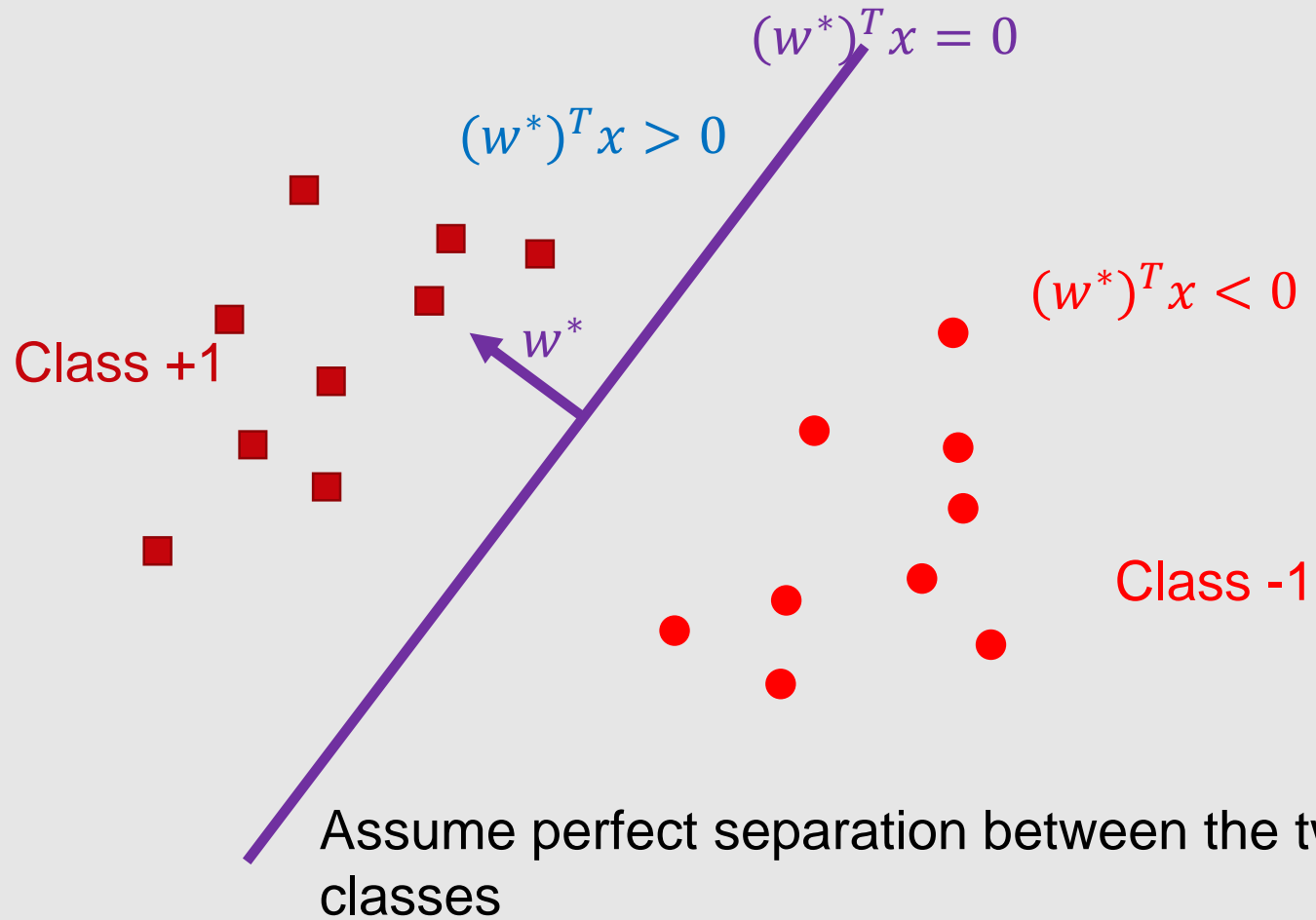
you should understand the following concepts

- the margin
- the linear support vector machine
- the primal and dual formulations of SVM learning
- support vectors
- VC-dimension and maximizing the margin



# Motivation

# Linear classification

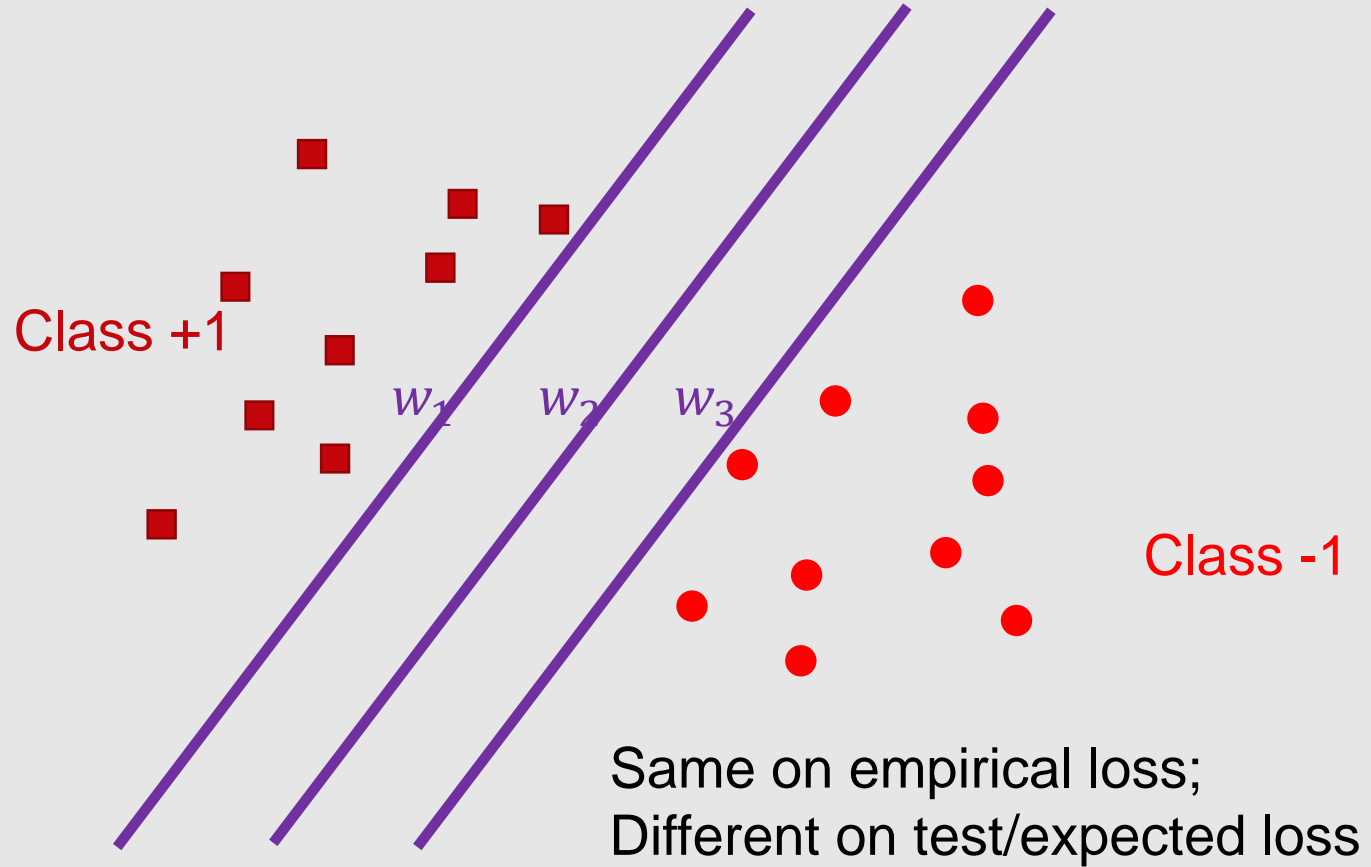


# Attempt

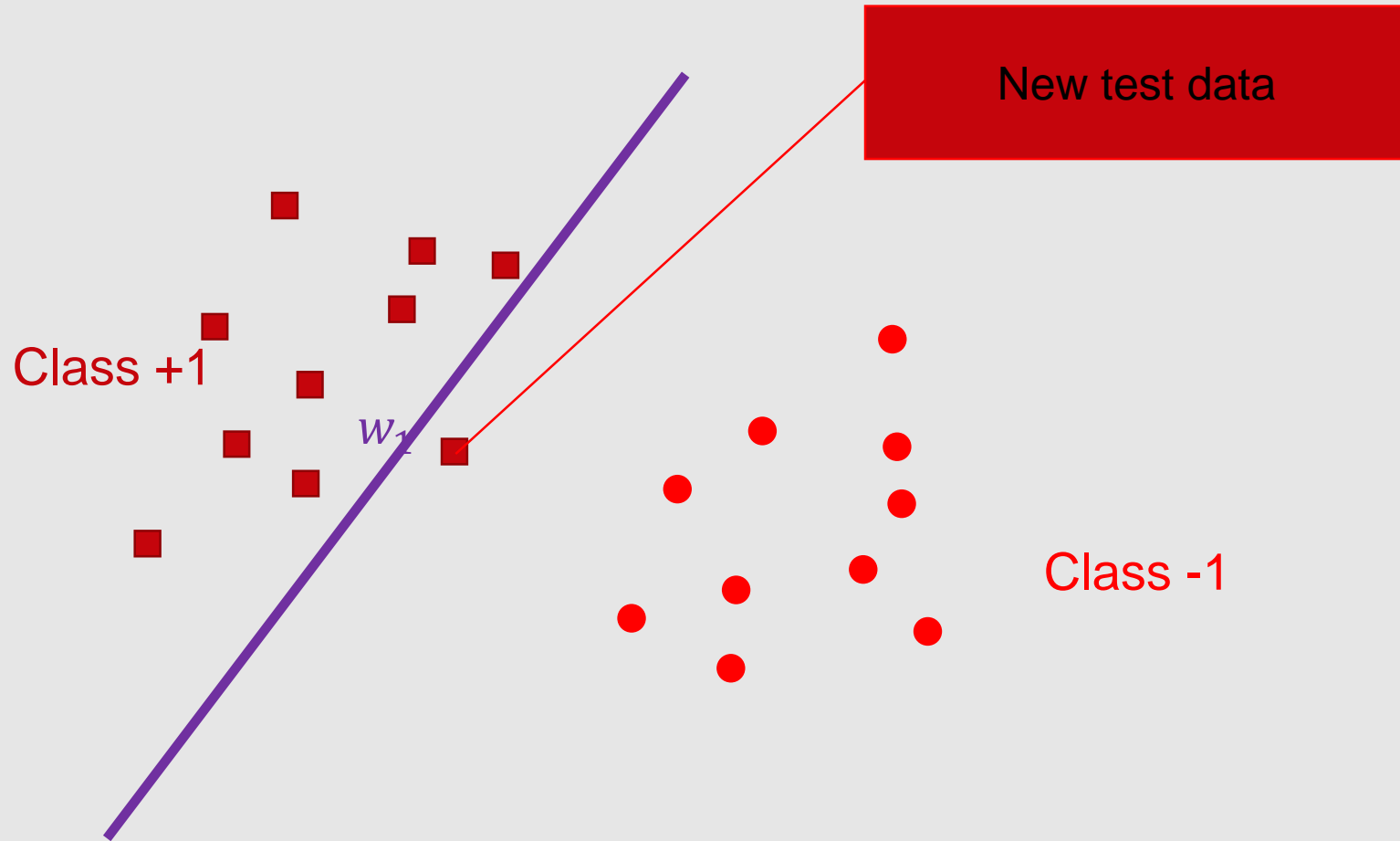


- Given training data  $\{(x_i, y_i): 1 \leq i \leq n\}$  i.i.d. from distribution  $D$
- Hypothesis  $y = \text{sign}(f_w(x)) = \text{sign}(w^T x)$ 
  - $y = +1$  if  $w^T x > 0$
  - $y = -1$  if  $w^T x < 0$
- Let's assume that we can optimize to find  $w$

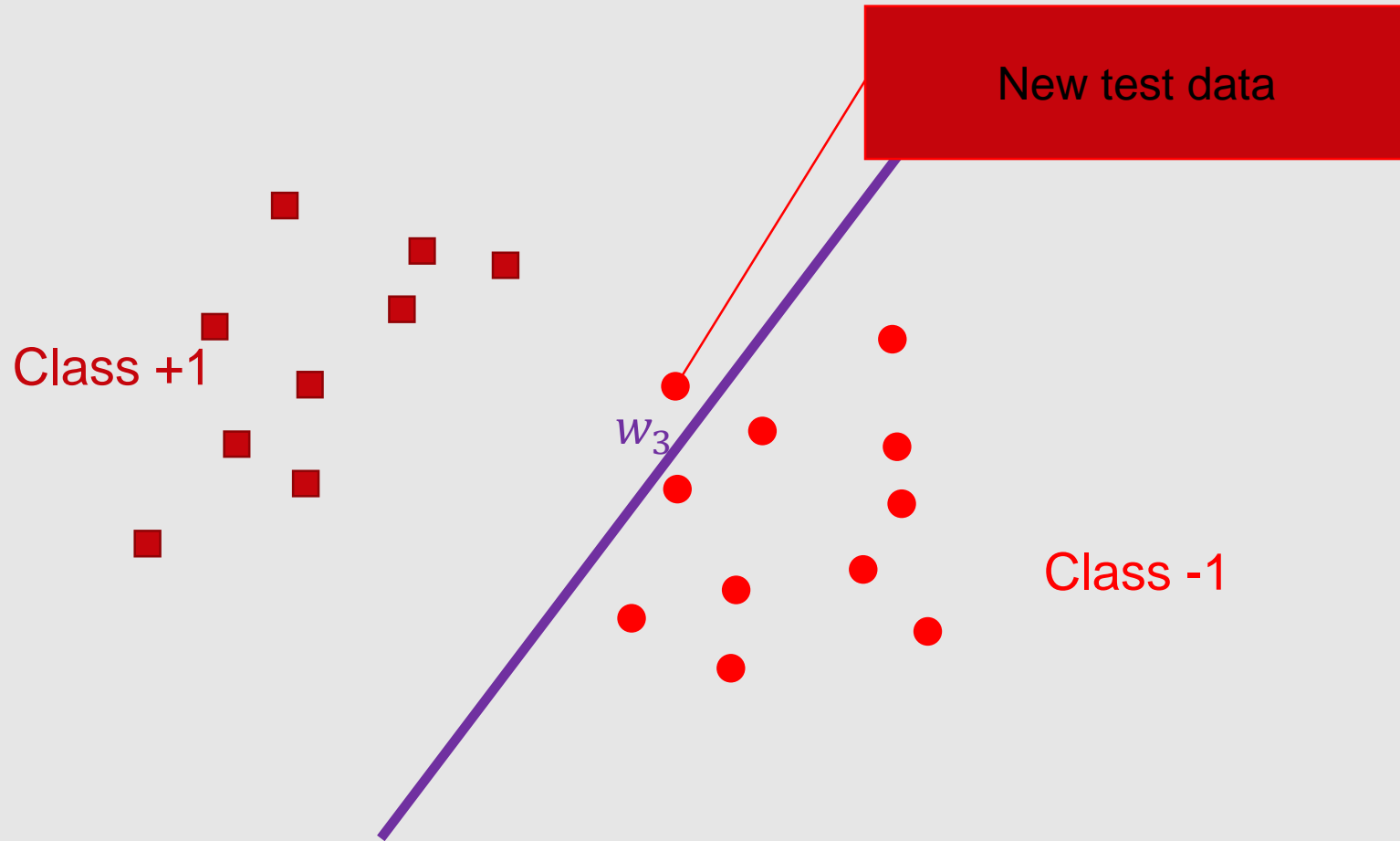
# Multiple optimal solutions?



# What about $w_1$ ?

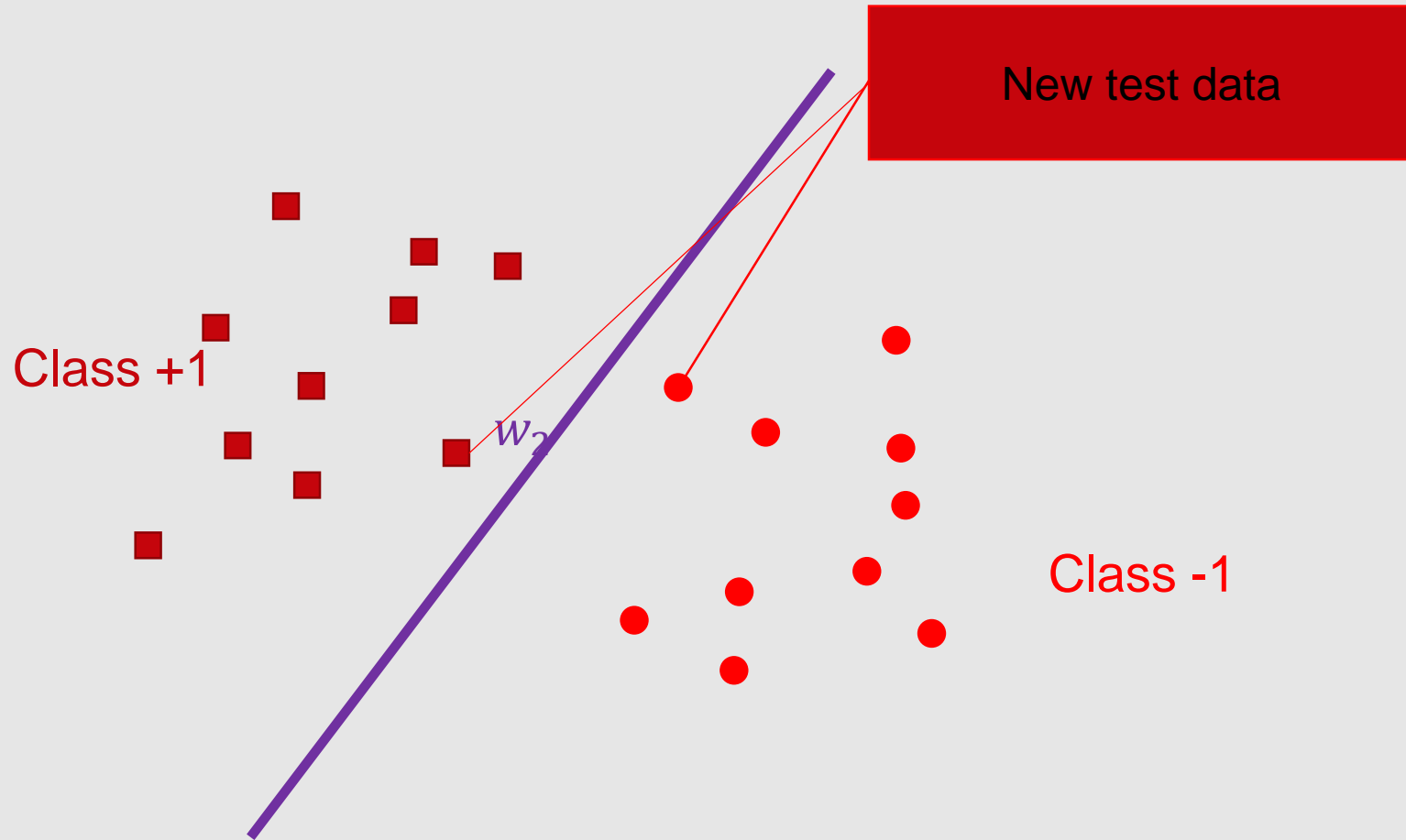


# What about $w_3$ ?

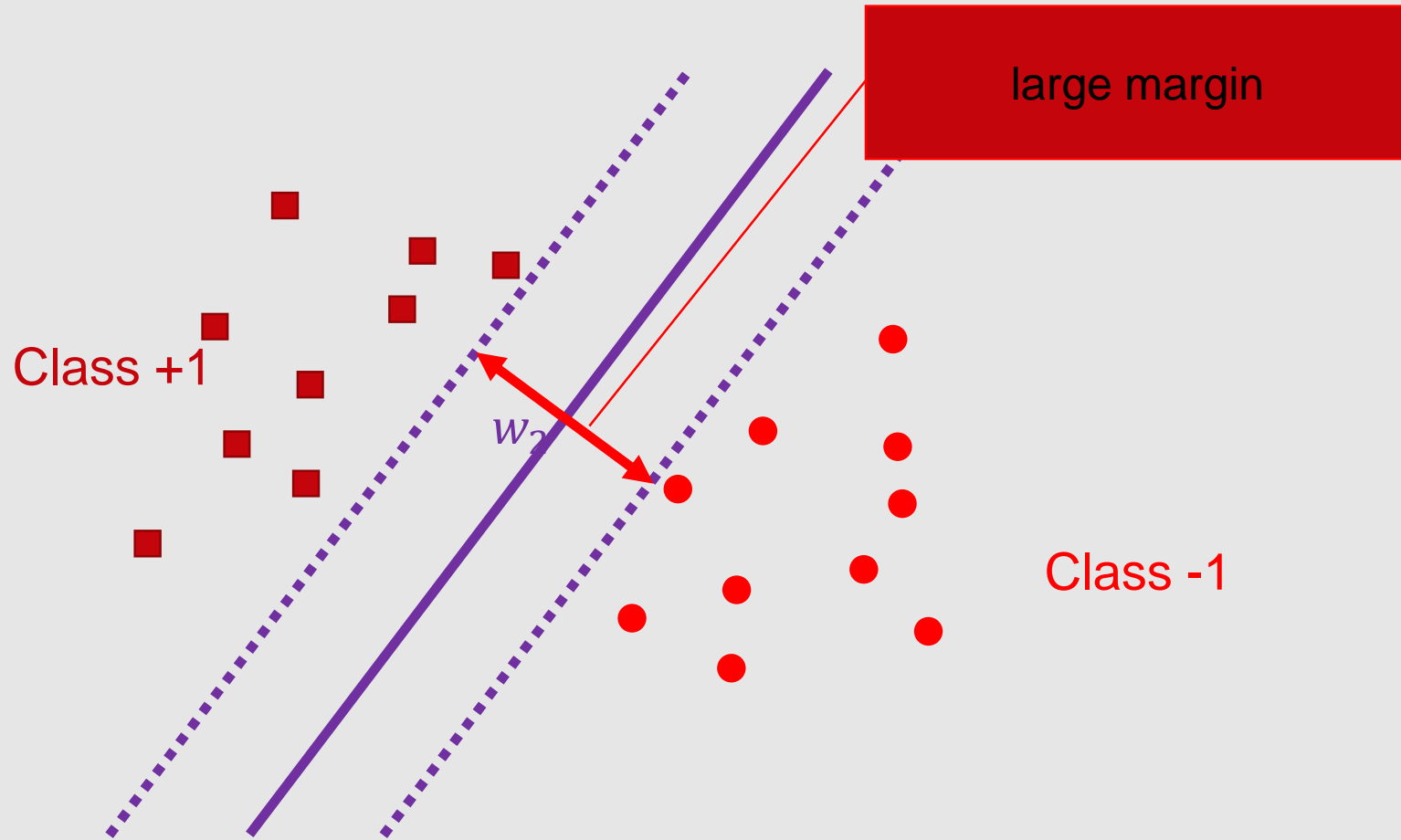




# Most confident: $w_2$



# Intuition: margin





Margin

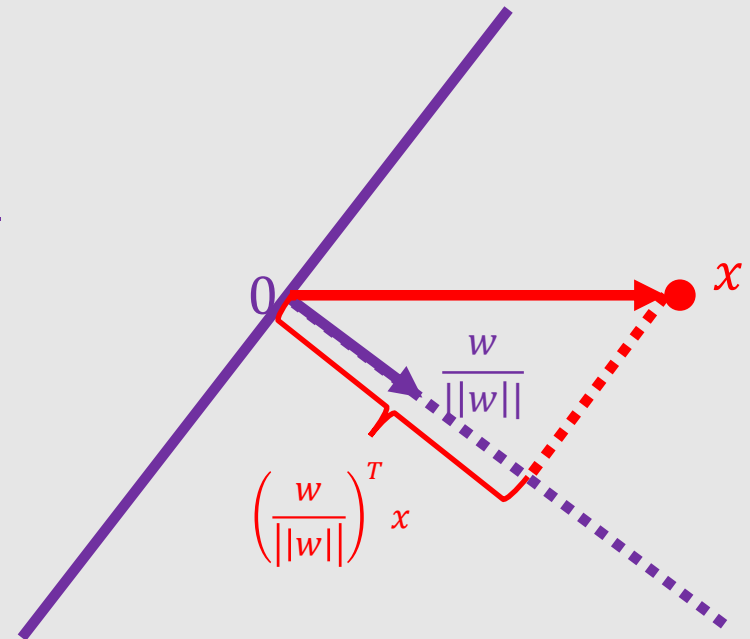


# Margin

- Lemma 1:  $x$  has distance  $\frac{|f_w(x)|}{\|w\|}$  to the hyperplane  $f_w(x) = w^T x = 0$

Proof:

- $w$  is orthogonal to the hyperplane
- The unit direction is  $\frac{w}{\|w\|}$
- The projection of  $x$  is  $\left(\frac{w}{\|w\|}\right)^T x = \frac{f_w(x)}{\|w\|}$





# Margin: with bias

- Claim 1:  $w$  is orthogonal to the hyperplane  $f_{w,b}(x) = w^T x + b = 0$

Proof:

- pick any  $x_1$  and  $x_2$  on the hyperplane
- $w^T x_1 + b = 0$
- $w^T x_2 + b = 0$
  
- So  $w^T (x_1 - x_2) = 0$



# Margin: with bias

- Claim 2:  $0$  has distance  $\frac{|b|}{\|w\|}$  to the hyperplane  $w^T x + b = 0$

Proof:

- pick any  $x_1$  the hyperplane
- Project  $x_1$  to the unit direction  $\frac{w}{\|w\|}$  to get the distance
- $\left(\frac{w}{\|w\|}\right)^T x_1 = \frac{-b}{\|w\|}$  since  $w^T x_1 + b = 0$

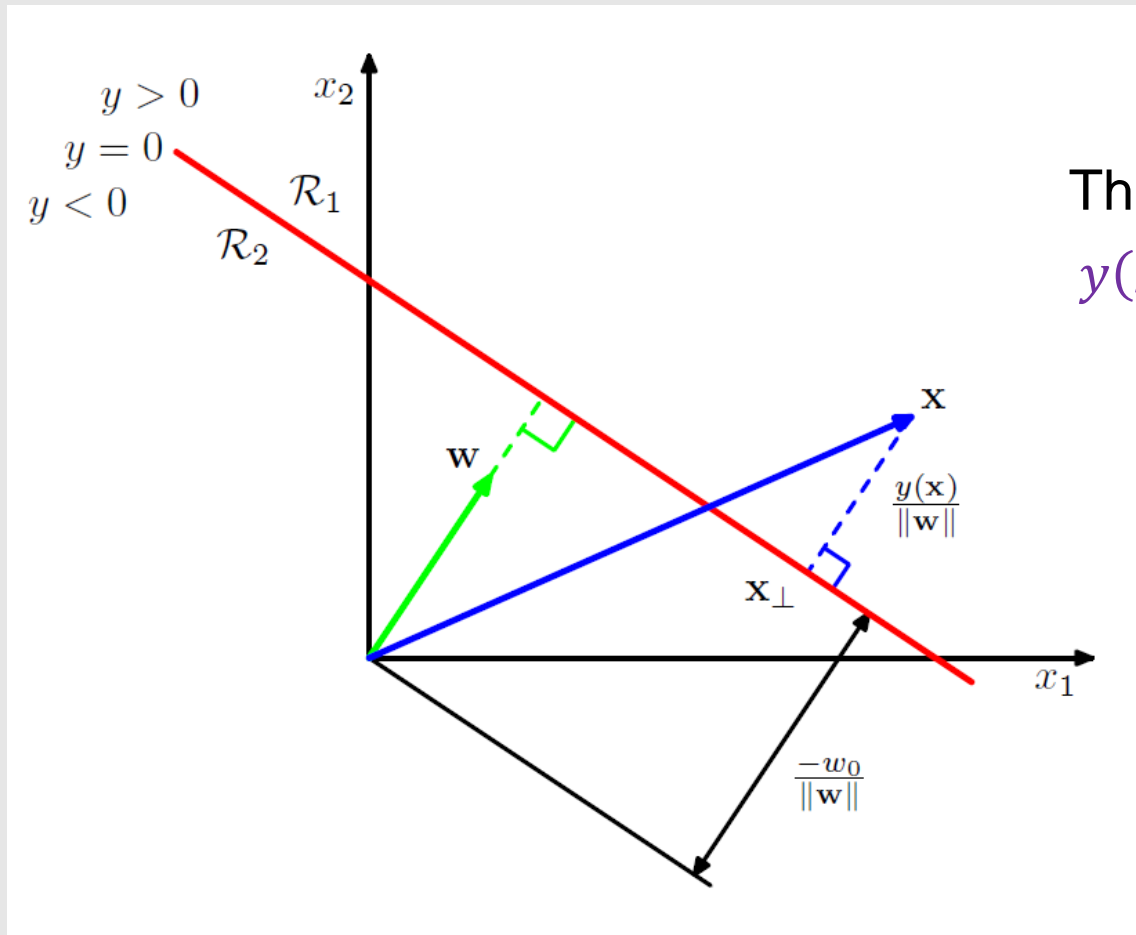


# Margin: with bias

- Lemma 2:  $x$  has distance  $\frac{|f_{w,b}(x)|}{\|w\|}$  to the hyperplane  $f_{w,b}(x) = w^T x + b = 0$

Proof:

- Let  $x = x_{\perp} + r \frac{w}{\|w\|}$ , then  $|r|$  is the distance
- Multiply both sides by  $w^T$  and add  $b$
- Left hand side:  $w^T x + b = f_{w,b}(x)$
- Right hand side:  $w^T x_{\perp} + r \frac{w^T w}{\|w\|} + b = 0 + r \|w\|$



The notation here is:  
 $y(x) = w^T x + w_0$

Figure from *Pattern Recognition and Machine Learning*, Bishop





# Support Vector Machine (SVM)

# SVM: objective



- Margin over all training data points:

$$\gamma = \min_i \frac{|f_{w,b}(x_i)|}{\|w\|}$$

- Since only want correct  $f_{w,b}$ , and recall  $y_i \in \{+1, -1\}$ , we have

$$\gamma = \min_i \frac{y_i f_{w,b}(x_i)}{\|w\|}$$

- If  $f_{w,b}$  incorrect on some  $x_i$ , the margin is negative

# SVM: objective



- Maximize margin over all training data points:

$$\max_{w,b} \gamma = \max_{w,b} \min_i \frac{y_i f_{w,b}(x_i)}{\|w\|} = \max_{w,b} \min_i \frac{y_i (w^T x_i + b)}{\|w\|}$$

- A bit complicated ...

# SVM: simplified objective



- Observation: when  $(w, b)$  scaled by a factor  $c$ , the margin unchanged

$$\frac{y_i(cw^T x_i + cb)}{\|cw\|} = \frac{y_i(w^T x_i + b)}{\|w\|}$$

- Let's consider a fixed scale such that

$$y_{i^*}(w^T x_{i^*} + b) = 1$$

where  $x_{i^*}$  is the point closest to the hyperplane

# SVM: simplified objective



- Let's consider a fixed scale such that

$$y_{i^*}(w^T x_{i^*} + b) = 1$$

where  $x_{i^*}$  is the point closet to the hyperplane

- Now we have for all data

$$y_i(w^T x_i + b) \geq 1$$

and at least for one  $i$  the equality holds

- Then the margin is  $\frac{1}{\|w\|}$

# SVM: simplified objective



- Optimization simplified to

$$\min_{w,b} \frac{1}{2} \|w\|^2$$

$$y_i(w^T x_i + b) \geq 1, \forall i$$

- How to find the optimum  $\hat{w}^*$ ?
- Solved by Lagrange multiplier method



# Lagrange multiplier

# Lagrangian



- Consider optimization problem:

$$\min_w f(w)$$

$$h_i(w) = 0, \forall 1 \leq i \leq l$$

- Lagrangian:

$$\mathcal{L}(w, \boldsymbol{\beta}) = f(w) + \sum_i \beta_i h_i(w)$$

where  $\beta_i$ 's are called Lagrange multipliers



# Lagrangian



- Consider optimization problem:

$$\min_w f(w)$$

$$h_i(w) = 0, \forall 1 \leq i \leq l$$

- Solved by setting derivatives of Lagrangian to 0

$$\frac{\partial \mathcal{L}}{\partial w_i} = 0; \quad \frac{\partial \mathcal{L}}{\partial \beta_i} = 0$$

# Generalized Lagrangian



- Consider optimization problem:

$$\min_w f(w)$$

$$g_i(w) \leq 0, \forall 1 \leq i \leq k$$

$$h_j(w) = 0, \forall 1 \leq j \leq l$$

- Generalized Lagrangian:

$$\mathcal{L}(w, \alpha, \beta) = f(w) + \sum_i \alpha_i g_i(w) + \sum_j \beta_j h_j(w)$$

where  $\alpha_i, \beta_j$ 's are called Lagrange multipliers

# Generalized Lagrangian



- Consider the quantity:

$$\theta_P(w) := \max_{\alpha, \beta: \alpha_i \geq 0} \mathcal{L}(w, \alpha, \beta)$$

- Why?

$$\theta_P(w) = \begin{cases} f(w), & \text{if } w \text{ satisfies all the constraints} \\ +\infty, & \text{if } w \text{ does not satisfy the constraints} \end{cases}$$

- So minimizing  $f(w)$  is the same as minimizing  $\theta_P(w)$

$$\min_w f(w) = \min_w \theta_P(w) = \min_w \max_{\alpha, \beta: \alpha_i \geq 0} \mathcal{L}(w, \alpha, \beta)$$

# Lagrange duality



- The primal problem

$$p^* := \min_w f(w) = \min_w \max_{\alpha, \beta: \alpha_i \geq 0} \mathcal{L}(w, \alpha, \beta)$$

- The dual problem

$$d^* := \max_{\alpha, \beta: \alpha_i \geq 0} \min_w \mathcal{L}(w, \alpha, \beta)$$

- Always true:

$$d^* \leq p^*$$

# Lagrange duality



- The primal problem

$$p^* := \min_w f(w) = \min_w \max_{\alpha, \beta: \alpha_i \geq 0} \mathcal{L}(w, \alpha, \beta)$$

- The dual problem

$$d^* := \max_{\alpha, \beta: \alpha_i \geq 0} \min_w \mathcal{L}(w, \alpha, \beta)$$

- Interesting case: when do we have

$$d^* = p^*?$$

# Lagrange duality



- Theorem: under **proper conditions**, there exists  $(w^*, \alpha^*, \beta^*)$  such that

$$d^* = \mathcal{L}(w^*, \alpha^*, \beta^*) = p^*$$

Moreover,  $(w^*, \alpha^*, \beta^*)$  satisfy Karush-Kuhn-Tucker (**KKT**) **conditions**:

$$\frac{\partial \mathcal{L}}{\partial w_i} = 0, \quad \alpha_i g_i(w) = 0$$

$$g_i(w) \leq 0, \quad h_j(w) = 0, \quad \alpha_i \geq 0$$



# Lagrange duality

- Theorem: under proper conditions, there exists  $(w^*, \alpha^*, \beta^*)$  such that

$$d^* = \mathcal{L}(w^*, \alpha^*, \beta^*) = p^*$$

dual  
complementarity

Moreover,  $(w^*, \alpha^*, \beta^*)$  satisfy Karush-Kuhn-Tucker (KKT) conditions:

$$\frac{\partial \mathcal{L}}{\partial w_i} = 0, \quad \alpha_i g_i(w) = 0$$

$$g_i(w) \leq 0, \quad h_j(w) = 0, \quad \alpha_i \geq 0$$



# Lagrange duality

- Theorem: under proper conditions, there exists  $(w^*, \alpha^*, \beta^*)$  such that

$$d^* = \mathcal{L}(w^*, \alpha^*, \beta^*) = p^*$$

primal constraints

satisfy Karush-Kuhn-Tu

dual constraints

conditions:

$$\frac{\partial \mathcal{L}}{\partial w_i} = 0, \quad \alpha_i g_i(w) = 0$$

$$g_i(w) \leq 0, \quad h_j(w) = 0, \quad \alpha_i \geq 0$$



# Lagrange duality



- What are the proper conditions?
- A set of conditions (Slater conditions):
  - $f, g_i$  convex,  $h_j$  affine, and exists  $w$  satisfying all  $g_i(w) < 0$
- There exist other sets of conditions
  - Check textbooks, e.g., Convex Optimization by Boyd and Vandenberghe



# SVM: optimization

# SVM: optimization



- Optimization (Quadratic Programming):

$$\min_{w,b} \frac{1}{2} \|w\|^2$$
$$y_i(w^T x_i + b) \geq 1, \forall i$$

- Generalized Lagrangian:

$$\mathcal{L}(w, b, \alpha) = \frac{1}{2} \|w\|^2 - \sum_i \alpha_i [y_i(w^T x_i + b) - 1]$$

where  $\alpha$  is the Lagrange multiplier

# SVM: optimization



- KKT conditions:

$$\frac{\partial \mathcal{L}}{\partial w} = 0, \rightarrow w = \sum_i \alpha_i y_i x_i \quad (1)$$

$$\frac{\partial \mathcal{L}}{\partial b} = 0, \rightarrow 0 = \sum_i \alpha_i y_i \quad (2)$$

- Plug into  $\mathcal{L}$ :

$$\mathcal{L}(w, b, \alpha) = \sum_i \alpha_i - \frac{1}{2} \sum_{ij} \alpha_i \alpha_j y_i y_j x_i^T x_j \quad (3)$$

combined with  $0 = \sum_i \alpha_i y_i, \alpha_i \geq 0$



# SVM: optimization

Only depend on inner products

- Reduces to dual problem:

$$\mathcal{L}(w, b, \alpha) = \sum_i \alpha_i - \frac{1}{2} \sum_{ij} \alpha_i \alpha_j y_i y_j x_i^T x_j$$

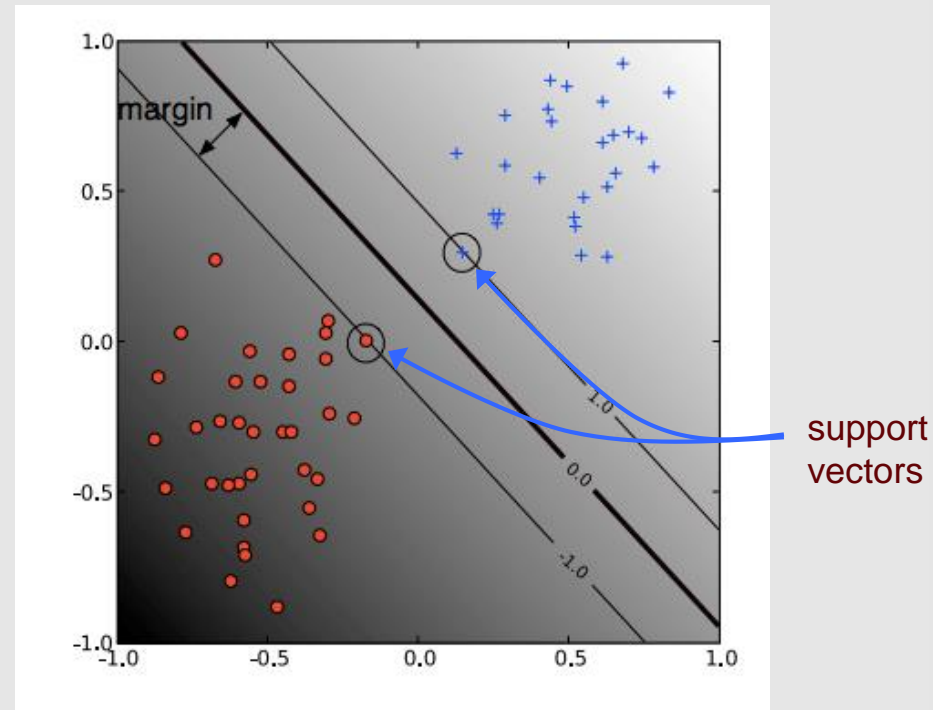
$$\sum_i \alpha_i y_i = 0, \alpha_i \geq 0$$

- Since  $w = \sum_i \alpha_i y_i x_i$ , we have  $w^T x + b = \sum_i \alpha_i y_i x_i^T x + b$

# Support Vectors



- final solution is a sparse linear combination of the training instances
- those instances with  $\alpha_i > 0$  are called *support vectors*
  - they lie on the margin boundary
- solution NOT changed if delete the instances with  $\alpha_i = 0$



# Learning theory justification



$$\text{error}(h) \leq \text{error}_D(h) + \sqrt{\frac{VC \left( \log \frac{2m}{VC} + 1 \right) + \log \frac{4}{\delta}}{m}}$$

error on true distribution      training set error      VC: VC-dimension of hypothesis class

- Vapnik showed a connection between the margin and VC dimension

$$VC \leq \frac{4R^2}{\text{margin}_D(h)}$$

constant dependent on training data

- thus to minimize the VC dimension (and to improve the error bound) → maximize the margin



# THANK YOU

Some of the slides in these lectures have been adapted/borrowed from materials developed by Mark Craven, David Page, Jude Shavlik, Tom Mitchell, Nina Balcan, Elad Hazan, Tom Dietterich, and Pedro Domingos.

