CS 839: Theoretical Found	lations of Deep Learning	Spring 2022
Lecture 19 Complexity I: Training a 3-Node is NP-Hard		
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1 Intro to NP-Completeness

Assume that I have problems A, B. We say that that B is as hard as A, if there exists a polynomial reduction from A to B. Meaning that if I can solve B then I can solve A. We write $A \leq_P B$. One known NP-complete problem is called "Set-Splitting" and is the following: **Set-Spliting(SS):**

Given: S, a collection of subsets $C = \{C_i | C_i \subset S\}$.

Question: Does there exists S_1, S_2 with $S_1 \cap S_2 = \emptyset$, such that $S_1 \cup S_2 = S_i$ for all i, it holds $C_i \not\subset S_1$ and $C_i \not\subset S_2$.

In the section below, we are going to reduce the "Set-Spliting" to the training a 3-node NN. This was proved in [1].

2 Training a 3-Node Network

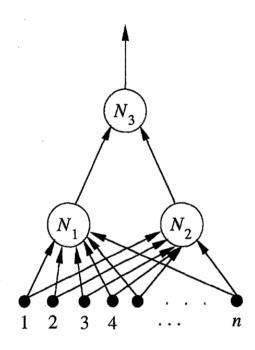


Figure 1: The 3-Node network

Let $a = [a_1, \ldots, a_n] \in \mathbb{R}^n$ and $a_0 \in \mathbb{R}$. We define the following threshold function:

$$f_i(z) = \begin{cases} 1 & \text{if } a \cdot z > a_0 \\ -1 & \text{o.w.} \end{cases}$$

This is equivalent to $f_i(z) = \operatorname{sign}(a \cdot z - a_0)$. The main question is the following: Question: Given a set of O(n) examples $(x, y) \in \{0, 1\}^n \times \{\pm 1\}$. Do there exists, f_1, f_2, f_3 such that the 3-node network has training error 0?

In fact, we are going to show that this problem is hard and in fact it is NP-Complete, by showing a reduction from Set-Spliting problem. Hence, we show the following:

Theorem 1. Training 3-node NN is NP-Complete.

Proof. First, we provide a geometric intuition for this problem: Each point is a point of the *n*-dimensional hypercube. The two functions f_1 , f_2 are linear thresholds functions, therefore, each one define a hyperplane. Therefore, if they are not parallel, they divide the space into four quadrants. Because the f_3 is a linear threshold, it can distinguish between points on different quadrants. So, the problem of training a 3-node, is equivalent to the following problem:

Given a set of labeled points in the n-dimensional hypercube does there exists:

Case 1: A simple plane separates ± 1 .

Case 2: Two planes such that either one quadrant contains all positive labels (+1) and no negative points, or one quadrant contains all negative labels (-1) and no positive points.

We are going to show that case 2 is the hard one, which means that this problem is NP-complete.

Problem 2LCPBE: Given *n*-labeled points. Do there exist planes f_1, f_2 such that one quadrant contains all positive points and no negative labeled points?

We are going to reduce the problem of Set-Splitting to 2LCPBE. Given an instance of Set-Splitting: $S = \{s_1, s_2, \ldots, s_n\}, C = \{C_1, C_2, \ldots\}$ and $\{C_j \subseteq S\}$, we are going to convert it to the following instance of 2LCPBE:

- Let the origin: $(0, 0, \ldots, 0)$ have the label +.
- for each s_i , we make a point $p_i = (0, ..., 1, ..., 0)$, where the 1 is in the *i*-th position, and we label it -.
- for all $C_j = \{s_{j1}, \ldots, s_{jk}\}$, we put at the point that has 1 at the positions $j1, j2, \ldots, jk$ and the + label, that point is $p_{j1} + p_{j2}, \ldots, p_{j,k}$.

For example consider the instance: $S = \{s_1, s_2, s_3\}, C_1 = \{s_1, s_2\}, C_2 = \{s_2, s_3\}$. We have [(0, 0, 0), 1] and [(1, 0, 0), -1], [(0, 1, 0), -1], [(0, 0, 1), -1] and [(1, 1, 0), 1], [(0, 1, 1), 1].

Lemma 2. The instance of SS has a solution is equalivalent to constructed instance of 2LCPBE has.

Proof. For the first direction. Given S_1, S_2 from the solution of set splitting, we consider the following:

Consider the hyperplanes: P_1, P_2 with the following form: $P_j: a_1x_1 + \ldots + a_nx_n + 1/2 = 0$, where

$$a_i = \begin{cases} -1 & \text{if } s_i \in S_j \\ n & \text{ow} \end{cases}$$

You can see that the following hold:

- P_i predicts + for (0, 0, ..., 0)
- P_i predicts + for training point with +
- P_i predicts for p_i if $s_i \in S_i$.

Therefore, the intersection (the quadrant) of hyperplanes: $P_1 \ge 0, P_2 \ge 0$, contains all the points with + and no point with -.

Let S_1 (resp. S_2) be the set that contains that only in P_1 (resp. P_2) get –. Place the rest of the points that both planes separates with – arbitrary in S_1 or S_2 . $S_1 \cup S_2 = S$ as all the points are either in S_1 or S_2 .

Let $C_j = \{s_{j1}, \ldots, s_{jk}\}$, it remains to show that $C_j \not\subset S_1, S_2$. P_1 predicts positive for $p_{j1} + \ldots + p_{jk}$ if $c_j \subset S_1$ but then this points would not be in one quadrant with only positive points which contradicts the assumption of 2LCPBE. Similarly for P_2 and S_2 .

Now we have shown that the training 3-node is NP-complete if one quadrant contains all the positive points, so the f_3 should be the AND function between f_1 and f_2 . Now, we will add some more points to make the output to always require that conditions. We extend the dimension of our points to n+3 and put 0 in the new components of the previous points. We add the points $[(0, \ldots, 1, 0, 0), -1], [(0, \ldots, 0, 1, 0), -1], [(0, \ldots, 0, 0, 1), -1], [(0, \ldots, 1, 1, 1), -1]$ $and also the points <math>[(0, \ldots, 1, 0, 1), 1], [(0, \ldots, 0, 1, 1), 1]$. Now given any solution to 2LCPBE, with P_1 and P_2 , we expand them as follows $P'_1 = P_1 + x_{n+1} + x_{n+2} - x_{n+3}$ and $P'_2 = P_2 - x_{n+1} - x_{n+2} + x_{n+3}$. So P'_1 separates the $[(0, \ldots, 0, 0, 1), -1]$ from the new positive points and P'_2 separates the rest – points from the new positive points. Moreover, now there does not exist a single plane that separates all the positive points from the negative ones and have all the negative points in all quadrant.

References

 Avrim L Blum and Ronald L Rivest. Training a 3-node neural network is np-complete. Neural Networks, 5(1):117–127, 1992.