



CS 540 Introduction to Artificial Intelligence

Statistics & Math Review

Yudong Chen
University of Wisconsin-Madison

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Announcements

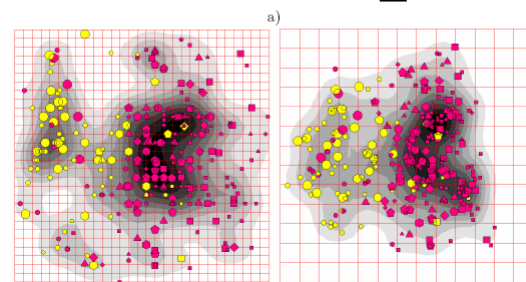
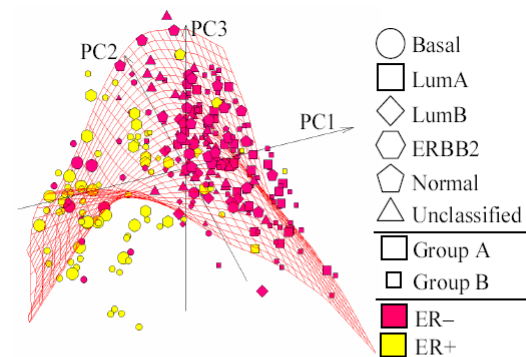
- **Homeworks:**
 - HW2 due Tuesday---get started early!
- **Class roadmap:**

Tuesday, Sep 14	Probability
Thursday, Sep 16	Linear Algebra and PCA
Tuesday, Sep 21	Statistics and Math Review
Thursday, Sep 23	Introduction to Logic
Tuesday, Sep 28	Natural Language Processing

} Fundamentals

Outline

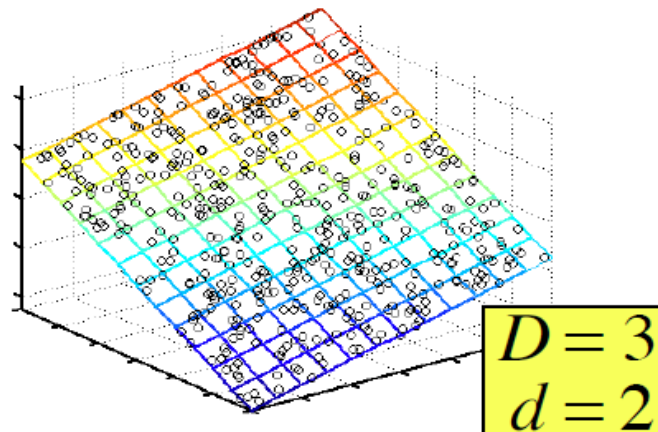
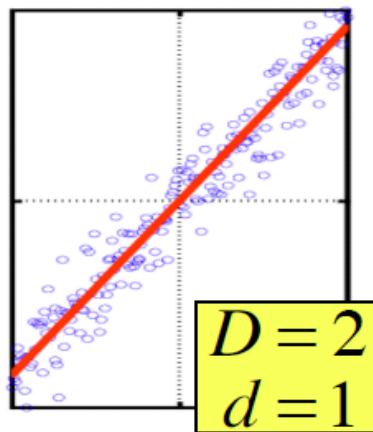
- Finish last lecture: **PCA**
- Review of probability
- Statistics: sampling & estimation



Wikipedia

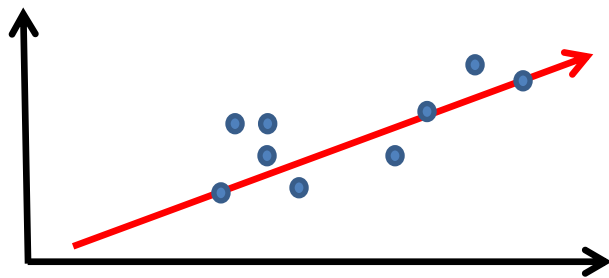
Principal Components Analysis (PCA)

- A type of dimensionality reduction approach
 - For when data is **approximately lower dimensional**
- Goal: find a low-dimensional subspace
 - Will project to this subspace; want to minimize loss of information



Principal Components Analysis (PCA)

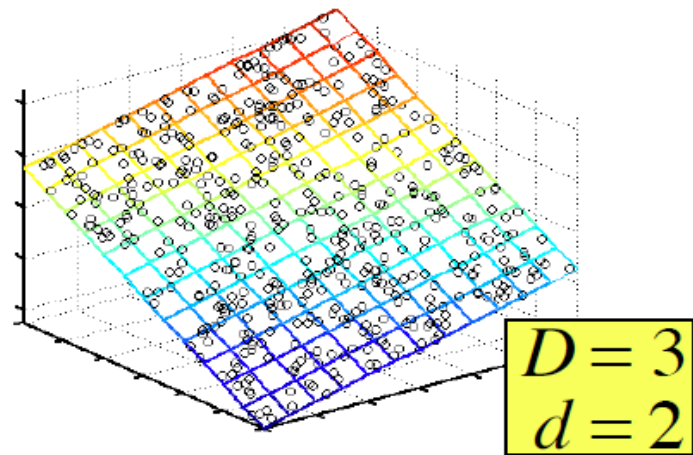
- From 2D to 1D:
 - Find a $v_1 \in \mathbb{R}^d$ so that we maximize “variability”



- New representations are along this vector (1D!)

Principal Components Analysis (PCA)

- From d dimensions to r dimensions:
 - Sequentially get orthogonal vectors $v_1, v_2, \dots, v_r \in \mathbb{R}^d$
 - Maximize variability when projecting to them
 - The vectors are the **principal components**



PCA Setup

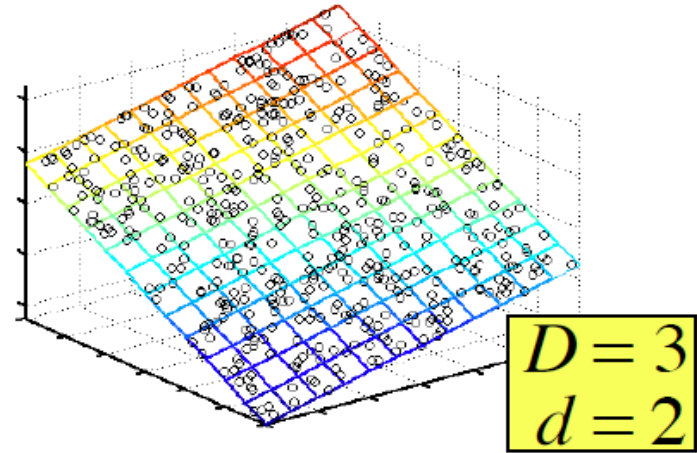
- **Inputs**

- Data: $x_1, x_2, \dots, x_n, x_i \in \mathbb{R}^d$
- Can arrange into $X \in \mathbb{R}^{n \times d}$

- **Centered!** $\frac{1}{n} \sum_{i=1}^n x_i = 0$

- **Outputs**

- $v_1, v_2, \dots, v_r \in \mathbb{R}^d$
(principle components, orthogonal)



PCA Setup

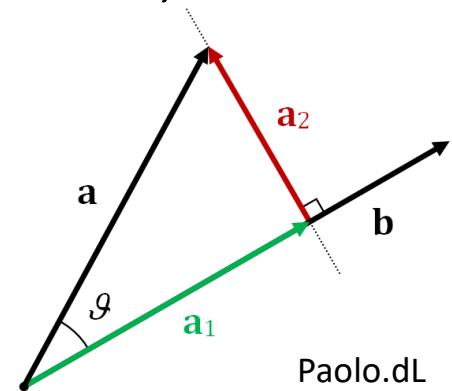
- Want directions (unit vectors) so that projecting data maximizes variance
 - What's projection? To project a onto unit vector b ,

$$\langle a, b \rangle b \leftarrow \text{Direction}$$

↑
Length

- Variance of projection:

$$\sum_{i=1}^n \langle x_i, v \rangle^2 = \|Xv\|^2$$



PCA First Step

- First component:

$$\begin{aligned} v_1 &= \arg \max_{\|v\|=1} \sum_{i=1}^n \langle v, x_i \rangle^2 \\ &= \arg \max_{\|v\|=1} \|Xv\|^2 \end{aligned}$$

PCA: k^{th} step

- Once we have $k-1$ components, compute

$$\hat{X}_k = X - \sum_{i=1}^{k-1} X v_i v_i^T$$

Deflation



- Then do the same thing

$$v_k = \arg \max_{\|v\|=1} \|\hat{X}_k w\|^2$$

- Deflation ensures v_k is orthogonal to v_1, \dots, v_{k-1}

PCA: Connection to Eigenvectors

- v_k is the k^{th} eigenvector of $\frac{1}{n} X^T X$
 - Proof: linear algebra! (omitted)
- $\frac{1}{n} X^T X \in \mathbb{R}^{d \times d}$ is sample covariance matrix of data
 - When data is centered (has 0 mean)
- Therefore, PCA can be done via eigendecomposition of sample covariance

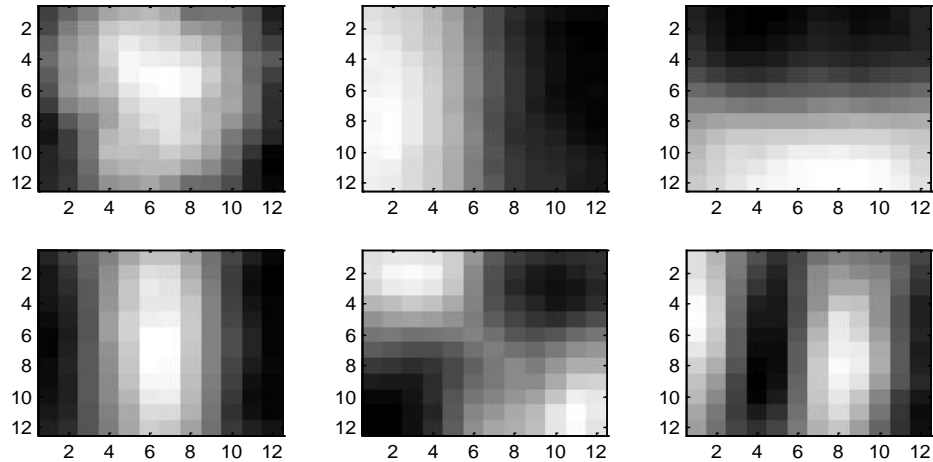
Application: Image Compression

- Original image:
- Divide into 12x12 patches
- Each patch is a 144-D vector x_i
- Want to reduce to 6-D



Application: Image Compression

- 6 most important components (as an image)



Application: Image Compression

- Project to 6D,



Compressed



Original

Break & Quiz

Q 1.1: What is the projection of $[1 \ 2]^T$ onto $[0 \ 1]^T$?

- A. $[1 \ 2]^T$
- B. $[-1 \ 1]^T$
- C. $[0 \ 0]^T$
- D. $[0 \ 2]^T$

Break & Quiz

Q 1.2: We wish to run PCA on 10-dimensional data in order to produce r -dimensional representations. Which is the most accurate (least loss of information)?

- A. $r = 3$
- B. $r = 9$
- C. $r = 10$
- D. $r = 20$

Probability Review: Outcomes & Events

- Outcomes: possible results of an **experiment**
- **Events**: subsets of outcomes we're interested in

$$\text{Ex: } \Omega = \underbrace{\{1, 2, 3, 4, 5, 6\}}$$

outcomes

$$\mathcal{F} = \underbrace{\{\emptyset, \{1\}, \{2\}, \dots, \{1, 2\}, \dots, \Omega\}}$$

events



Review: Probability Distribution

- We have outcomes and events.
- Now assign probabilities For $E \in \mathcal{F}$, $P(E) \in [0, 1]$

Back to our example:

$$\mathcal{F} = \underbrace{\{\emptyset, \{1, 3, 5\}, \{2, 4, 6\}, \Omega\}}_{\text{events}}$$

$$P(\{1, 3, 5\}) = 0.2, P(\{2, 4, 6\}) = 0.8$$



Review: Random Variables

- Map outcomes to real values $X : \Omega \rightarrow \mathbb{R}$
- Probabilities for a random variable:

$$P(X = 3) := P(\{\omega : X(\omega) = 3\})$$

- Cumulative Distribution Function (CDF)

$$F_X(x) := P(X \leq x)$$

Review: Random Variables

- Back to our example: $\mathcal{F} = \{\emptyset, \{1, 3, 5\}, \{2, 4, 6\}, \Omega\}$
 $P(\{1, 3, 5\}) = 0.2, P(\{2, 4, 6\}) = 0.8$
- Consider random variable: $X(\omega) = \begin{cases} 1, & \omega = 1, 3, 5 \\ 0, & \omega = 2, 4, 6 \end{cases}$
- $P(X = 1) = P(\{\omega: X(\omega) = 1\}) = P(\{1, 3, 5\}) = 0.2$
- $P(X = 0) = 0.8$
- CDF $F_X(x)$?

Review: Expectation & Variance

- Expectation: $E[X] = \sum_a a \times P(x = a)$
 - The “average”
- Variance: $Var[X] = E[(X - E[X])^2]$
 - A measure of spread

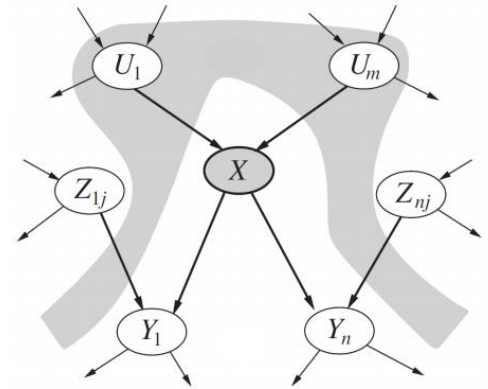
Review: Conditional Probability

- For when we know something,

$$P(X = a|Y = b) = \frac{P(X = a, Y = b)}{P(Y = b)}$$

- Conditional independence

$$P(X, Y|Z) = P(X|Z)P(Y|Z)$$



Credit: **Devin Soni**

Review: Bayes Rule

- Bayes rule:

$$P(H|E_1, E_2, \dots, E_n) = \frac{\overset{\text{Likelihood}}{P(E_1, \dots, E_n|H)} \overset{\text{Prior}}{P(H)}}{\text{Posterior}}{P(E_1, E_2, \dots, E_n)}$$

- Assuming **conditional independence**:

$$P(H|E_1, E_2, \dots, E_n) = \frac{P(E_1|H)P(E_2|H) \cdots P(E_n|H)P(H)}{P(E_1, E_2, \dots, E_n)}$$

Review: Classification

$$P(H|E_1, E_2, \dots, E_n) = \frac{P(E_1|H)P(E_2|H) \cdots P(E_n|H)P(H)}{P(E_1, E_2, \dots, E_n)}$$

- Called **Naïve Bayes Classifier**
 - HW2: applied to document classification
- H : some class we'd like to infer from evidence E_1, \dots, E_n
 - Estimate prior $P(H)$ from data
 - Estimate likelihood $P(E_i|H)$ from data
 - How?

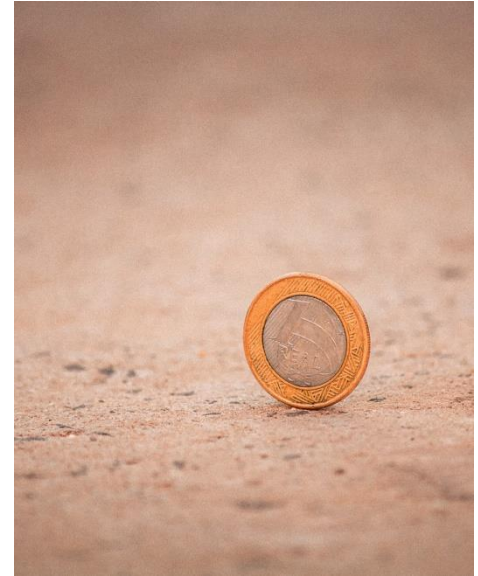
Samples and Estimation

- Usually, we don't know the distribution P
 - Instead, we see a bunch of samples
- Typical statistics problem: **estimate parameters** from samples
 - Estimate probability $P(H)$
 - Estimate the mean $E[X]$
 - Estimate parameters $P_{\theta}(X)$



Samples and Estimation

- Typical statistics problem: **estimate parameters** from samples
 - Estimate probability $P(H)$
 - Estimate the mean $E[X]$
 - Estimate parameters $P_{\theta}(X)$
- Example: Bernoulli with parameter p
 - $p = E[X] = P(X = 1)$



Examples: Sample Mean

- Bernoulli with parameter/mean p
- See samples x_1, x_2, \dots, x_n
 - Estimate mean with **sample mean**

$$\hat{\mathbb{E}}[X] = \frac{1}{n} \sum_{i=1}^n x_i$$

- Counting heads



Break & Quiz

Q 2.1: You see samples of X given by $[0,1,1,2,2,0,1,2]$. Empirically estimate $E[X^2]$

- A. $9/8$
- B. $15/8$
- C. 1.5
- D. There aren't enough samples to estimate $E[X^2]$

Break & Quiz

Q 2.2: You are empirically estimating $P(X)$ for some random variable X that takes on 100 values. You see 50 samples. How many of your $P(X=a)$ estimates might be 0?

- A. None.
- B. Between 5 and 50, exclusive.
- C. Between 50 and 100, inclusive.
- D. Between 50 and 99, inclusive.

Estimation Theory

- Is sample mean is a good estimate of true mean?
 - Law of large numbers: $\hat{\mathbb{E}}[X] \xrightarrow{n \rightarrow \infty} \mathbb{E}[X]$
 - Central limit theorem: limit distribution of $\hat{\mathbb{E}}[X]$
 - Concentration inequalities

$$P(|\mathbb{E}[X] - \hat{\mathbb{E}}[X]| \geq t) \leq \exp(-2nt^2)$$

- Covered in advanced ML/stat courses

