

# CS 540 Introduction to Artificial Intelligence Games II 

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## Announcements

- Homeworks:
- HW 9 deadline extended to next Tuesday (Dec 7)
- HW 10 to be released on Thursday. Due Dec 14 Tuesday
- Class roadmap:
- Today: Game II
- Next: Reinforcement Learning


## Outline

- Review of game theory basics
- Properties, mathematical setup, simultaneous games
- Sequential games
- Game trees, minimax, search approaches
- Speeding up sequential game search
- Pruning, heuristics


## Review of Games: Multiple Agents

Games setup: multiple agents


- Strategic decision making.


## Review of Games: Properties

Let's work through properties of games

- Number of agents/players
- State \& action spaces: discrete or continuous
- Finite or infinite
- Deterministic or random
- Sum: zero or positive or negative
- Sequential or simultaneous



## Review: Prisoner's Dilemma

## Famous example from the '50s.

Two prisoners A \& B. Can choose to betray the other or not.

- A and B both betray, each of them serves two years in prison
- One betrays, the other doesn't: betrayer free, other three years
- Both do not betray: one year each

Properties: 2-player, discrete, finite,
deterministic, negative-sum, simultaneous


## Review: Normal Form

Mathematical description of simult. games. Has:

- $n$ players $\{1,2, \ldots, n\}$
- Player $i$ strategy $a_{i}$ from $A_{i}$. All: $a=\left(a_{1}, a_{2}, \ldots, a_{n}\right)$
- Player $i$ gets rewards $u_{i}(a)$ for any outcome
- Note: reward depends on other players!
- Setting: all of these spaces, rewards are known


## Review: Example of Normal Form

Ex: Prisoner's Dilemma

| Player 2 |  |  |
| :---: | :--- | :--- |
| Player 1 | Stay silent | Betray |
| Stay silent | $-1,-1$ | $-3,0$ |
| Betray | $0,-3$ | $-2,-2$ |

- 2 players, 2 actions: yields $2 \times 2$ matrix
- Strategies: \{Stay silent, betray\} (i.e, binary)
- Rewards: $\{0,-1,-2,-3\}$


## Review: Dominant Strategies

Let's analyze such games. Some strategies are better

- Dominant strategy: if $a_{i}$ better than $a_{i}^{\prime}$ regardless of what other players do, $a_{i}$ is dominant
- l.e.,

$$
\begin{aligned}
& u_{i}\left(a_{i}, a_{-i}\right) \geq u_{i}\left(a_{i}^{\prime}, a_{-i}\right) \forall a_{i}^{\prime} \neq a_{i} \text { and } \forall a_{-i} \\
& \quad \begin{array}{l}
\text { All of the other entries } \\
\text { of } a \text { excluding } i
\end{array}
\end{aligned}
$$

- Doesn’t always exist!
$=\left(a_{1}^{*}, \cdots, a_{n}^{*}\right)$


## Review: Equilibrium

$a^{*}$ is an equilibrium if all the players do not have an incentive to unilaterally deviate

$$
u_{i}\left(a_{i}^{*}, a_{-i}^{*}\right) \geq u_{i}\left(a_{i}, a_{-i}^{*}\right) \quad \forall a_{i} \in A_{i}
$$

$$
\operatorname{tasi}
$$

- All players dominant strategies -> equilibrium
- Converse doesn't hold (don't need dominant strategies to get an equilibrium)


## Review: Pure and Mixed Strategies

So far, all our strategies are deterministic: "pure"

- Take a particular action, no randomness

Can also randomize actions: "mixed"

- Assign probabilities $x_{i}$ to each action

$$
x_{i}\left(a_{i}\right), \text { where } \sum_{a_{i} \in A_{i}} x_{i}\left(a_{i}\right)=1, x_{i}\left(a_{i}\right) \geq 0
$$

- Note: have to now consider expected rewards


## Review: Nash Equilibrium

Consider the mixed strategy $x^{*}=\left(x_{1}{ }^{*}, \ldots, x_{n}{ }^{*}\right)$

- This is a Nash equilibrium if

$$
u_{i}\left(x_{i}^{*}, x_{-1}^{*}\right) \geq u_{i}\left(x_{i}, x_{-i}^{*}\right) \quad \forall x_{i} \in \Delta_{A_{i}}, \forall i \in\{1, \ldots, n\}
$$



Better than doing anything else, "best response"

Space of probability
distributions

- Intuition: nobody can increase expected reward by changing only their own strategy. A type of solution!


## Break \& Quiz

Q 1.1: Which of the following is false

- A. The set of mixed strategies includes pure strategies.
- B. A game can be simultaneous but have imperfect information.
- C. A game may not have any dominating strategies.
- D. All finite two player games have pure Nash equilibria.


## Break \& Quiz

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## Break \& Quiz

Q 1.1: Which of the following is false

- A. The set of mixed strategies includes pure strategies. (Yes: deterministic is a subset of random---such strategies have all the probability mass on one outcome.)
- B. A game can be simultaneous but have imperfect information. (Example: RPS. There're sequential games with imperfect info. as well, e.g., Battleship.)
- C. A game may not have any dominating strategies. (RPS).
- D. All finite two player games have pure Nash equilibria. (This is false---they all have mixed equilibria, but not necessarily pure.)


## Sequential Games

More complex games with multiple moves

- Instead of normal form, extensive form
- Represent with a tree
- Find strategies: perform search over the tree
- Can still look for Nash equilibrium
- Or, other criteria like minimax



## II-Nim: Example Sequential Game

2 piles of sticks, each with 2 sticks.

- Each player takes one or more sticks from one of the piles
- Take last stick: lose
- Two players: Max and Min
- If Max wins, the score is +1 ; otherwise - 1
- Min's score is -Max's
- Use Max's as the score of the game


## Game Trajectory

(ii, ii)

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(ii, ii)
Max takes one stick from one pile
(i, ii)

## Game Trajectory

(ii, ii)
Max takes one stick from one pile
(i, ii)
Min takes two sticks from the other pile
(i,-)

## Game Trajectory

(ii, ii)
Max takes one stick from one pile
(i, ii)

Min takes two sticks from the other pile
(i,-)
Max takes the last stick

$$
(-,-)
$$

Max gets score -1

## Game tree for II-Nim

Two players:
Max and Min


Convention: score is w.r.t. the first player Max. Min's score $=-$ Max

Max wants the largest score Min wants the smallest score

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## Game tree for II-Nim

Two players: Max and Min


Max wants the largest score
Min wants the smallest score

## Game tree for II-Nim



## Strategies \& Rewards

sequentiol -
Let's stick to zero-sum two-player games

- Strategies: player 1 (Max): $s$, player 2 (Min): $t$
- Player 1 (Max): reward $u(s, t)$, player 2 (Min): $-u(s, t)$
- Max goal: maximize $u(s, t)$
- Goal: find strategies $s, t$ that do this.



## Minimax Theorem

## Famous result of von Neumann

- Says: there are strategies $s^{*}$ and $t^{*}$ and a value $u^{*}$, the minimax value so that
- If Min uses $t^{*}$, then Max's reward $\leq u^{*}$ (i.e., $\max _{s} u\left(s, t^{*}\right)=u^{*}$ )
- If Max uses $s^{*}$, then Nifax's reward $\geq u^{*}$ (i.e., $\min _{t} u\left(s^{*}, t\right)=u^{*}$ )
- So: $u\left(s^{*}, t^{*}\right)=u^{*}$
- Also: if game has perfect information, there are pure strategies $s^{*}, t^{*}$ that satisfy the result


## Finding The Strategies

## Back to our game tree

- Write down all the pure strategies (e.g., the big tree) and select the $s^{*}$ and $t^{*}$

$$
s^{*}=\arg \max _{s \in S} \min _{t \in T} u(s, t) \quad t^{*}=\arg \min _{t \in T} \max _{s \in S} u(s, t)
$$

- Big search, since for branching factor $b$, height $h$, need to look at ${ }^{\sim} b^{h}$ strategies


## Game tree for II-Nim



## Game tree for II-Nim



## Game tree for II-Nim



## Game tree for II-Nim

Two players:


## Game tree for II-Nim



## Game tree for II-Nim



## Game tree for II-Nim

Two players: Max and Min


## Break \& Quiz

Q 2.1: We are playing a game where Player $A$ goes first and has 4 moves. Player B goes next and has 3 moves. Player A goes next and has 2 moves. Player B then has one move.

How many nodes are there in the minimax tree, including termination nodes (leaves)?

- A. 23
- B. 65
- C. 41
- D. 2


## Break \& Quiz

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## Break \& Quiz



Q 2.1: We are playing a game where Player $A$ goes first and has 4 moves. Player B goes next and has 3 moves. Player A goes next and has 2 moves. Player B then has one move.
How many nodes are there in the minimax tree, including termination nodes (leaves)?

- A. 23
- B. $65(1+4+4 * 3+4 * 3 * 2+4 * 3 * 2$ = 65. Note the root and leaf nodes.)
- C. 41
- D. 2


## Break \& Quiz

Q 2.2: During minimax tree search, must we examine every node?

- A. Always
- B. Sometimes
- C. Never


## Break \& Quiz

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## Break \& Quiz

Q 2.2: During minimax tree search, must we examine every node?
see pruning (later)

- A. Always (No: consider layer $k$, where we take the max of all the mins of its children at layer $k+1$. If the current value of a min node at $k+1$ already smaller than the current max, we don't need to continue the minimization.)
- B. Sometimes
- C. Never (No: the event above may simply not happen).


## Our Approach So Far

We find the minimax value/strategy bottom up

- Minimax value: score of terminal node when both players play optimally
- Max's turn, take max of children
- Min's turn, take min of children
- Can implement this as depth-first search: minimax algorithm


## Minimax Algorithm

```
function Max-Value(s)
inputs:
    s: current state in game, Max about to play
output: best-score (for Max) available from s
    if (s is a terminal state )
    then return (terminal value of s )
    else
        \alpha:= - infinity
        for each s' in Succ(s)
    \alpha := max( \alpha , Min-value(s'))
return \alpha
else
\[
\begin{aligned}
& \alpha:=- \text { infinity } \\
& \text { for each } s^{\prime} \text { in Succ(s) } \\
& \quad \alpha:=\max (\alpha, \operatorname{Min}-\text { value(s's)) }
\end{aligned}
\]
return \(\alpha\)
```

```
function Min-Value(s)
```

function Min-Value(s)
output: best-score (for Min) available from s
output: best-score (for Min) available from s
if (s is a terminal state )
if (s is a terminal state )
then return (terminal value of s)
then return (terminal value of s)
else
else
\beta:= infinity
\beta:= infinity
for each s' in Succs(s)
for each s' in Succs(s)
\beta:= min( }\beta\mathrm{ , Max-value(s'))
\beta:= min( }\beta\mathrm{ , Max-value(s'))
return }

```
return }
```

Time complexity?

- O(bm)

Space complexity?

- O(bm)


## Minimax algorithm in execution


min

Minimax algorithm in execution
$\max$
$\min$
max

min

## Minimax algorithm in execution



Minimax algorithm in execution
max
min
max

$\min$

Minimax algorithm in execution

min

Minimax algorithm in execution

min

Minimax algorithm in execution

min

Minimax algorithm in execution

min

Minimax algorithm in execution

min

Minimax algorithm in execution

min

Minimax algorithm in execution

min

Minimax algorithm in execution

min

Minimax algorithm in execution

min

## Can We Do Better?

One downside: we had to examine the entire tree
An idea to speed things up: pruning

- Goal: want the same minimax value, but faster
- We can get rid of bad branches
- Same principle as quiz question



## Alpha-beta pruning

```
function Max-Value (s,\alpha,\beta)
inputs:
    s: current state in game, Max about to play
    \alpha: best score (highest) for Max along path to s
    \beta: best score (lowest) for Min along path to s
output: min( }\beta\mathrm{ , best-score (for Max) available from s)
    if ( }s\mathrm{ is a terminal state )
    then return ( terminal value of s )
    else for each s' in Succ(s)
        \alpha:= max(\alpha,Min-value(s',\alpha,\beta))
        if (\alpha\geq\beta) then return \beta /* alpha pruning */
    return \alpha
function Min-Value(s,\alpha,\beta)
output: max(\alpha, best-score (for Min) available from s )
    if (s is a terminal state )
    then return (terminal value of s)
    else for each s' in Succs(s)
    \beta:= min}(\beta\mathrm{ , Max-value(s', , , ))
    if (\alpha\geq\beta) then return \alpha /* beta pruning */
    return \beta
```


## Alpha-Beta Pruning

## How effective is alpha-beta pruning?



- Depends on the order of successors!
- Best case, the \#of nodes to search is $O\left(b^{m / 2}\right)=O\left((\sqrt{b})^{n}\right.$
- Happens when each player's best move is the leftmost child.
- The worst case is no pruning at all.
- In DeepBlue, the average branching factor was about 6 with alpha-beta instead of 35-40 without.


## Minimax With Heuristics

## Note that long games are yield huge computation

- To deal with this: limit d for the search depth
- $\mathbf{Q}$ : What to do at depth $d$, but no termination yet?
- A: Use a heuristic evaluation function $e(x)$

```
function Minimax(x,d) returns an estimate of x's utility value
    inputs: x, current state in game
            d, an upper bound on the search depth
    if }x\mathrm{ is a terminal state then return Max's payoff at }
    else if d}=0\mathrm{ then return }e(x
    else if it is Max's move at }x\mathrm{ then
        return max {}\operatorname{Minimax}(y,d-1):y\mathrm{ is a child of }x
    else return min{\operatorname{Minimax}(y,d-1):y\mathrm{ is a child of }x}
```


## Heuristic Evaluation Functions

- $e(x)$ often a weighted sum of features (like our linear models)

$$
e(x)=w_{1} f_{1}(x)+w_{2} f_{2}(x)+\ldots+w_{n} f_{n}(x)
$$

- Chess example: $f_{i}(x)=$ difference between number of white and black, with $i$ ranging over piece types.
- Set weights according to piece importance
- E.g., 1(\# white pawns - \# black pawns) + 3(\#white knights - \# black knights)


## Going Further

- Monte Carlo tree search (MCTS)
- Uses random sampling of the search space
- Choose some children (heuristics to figure out \#)
- Record results, use for future play
- Self-play
- AlphaGo and other big results!


The agent (Black) learns to capture walls and corners in the early game
= all we've talk about (fanning)



The agent (Black) learns to force passes in the late game

## Summary

- Review of game theory
- Properties, Mathematical formulation for simultaneous games Normal form, dominance, equilibria, mixed vs pure
- Sequential games
- Game trees, minimax value, minimax algorithm
- Improving our search
- Using heuristics, pruning, random search

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