CS368 MATLAB Programming Lecture 6

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Based on lecture slides by Michael O'Neill and Beck Hasti

March 3, 2022

System of Two Equations Math

- $\begin{cases} m_{11}x_1 + m_{12}x_2 = b_1 \\ m_{21}x_1 + m_{22}x_2 = b_2 \end{cases}$ is a system of two equations and two unknowns x_1 and x_2 .
- The system can be written in matrix form

$$\begin{bmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}.$$

• The system may have 0,1 or infinite number of solutions.

Two Equations Example

•
$$\begin{bmatrix} 1 & 2 \\ 3 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 4 \\ 5 \end{bmatrix}$$
 has no solution.

•
$$\begin{bmatrix} 1 & 2 \\ 3 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 4 \\ 12 \end{bmatrix}$$
 has infinite number of solutions, $x = \begin{bmatrix} 4 - 2t \\ t \end{bmatrix}, t \in \mathbb{R}.$

$$\bullet \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 5 \\ 11 \end{bmatrix} \text{ has a unique solution } x = \begin{bmatrix} 1 \\ 2 \end{bmatrix}.$$

Two Equations General Solution

• In general, for $\begin{bmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$, if $d = m_{11}m_{22} - m_{12}m_{21} = 0$, then there are either no solution or infinite number of solutions; otherwise, there is a unique solution $x = \frac{1}{d} \begin{bmatrix} m_{22}b_1 - m_{12}b_2 \\ m_{11}b_2 - m_{21}b_1 \end{bmatrix}$.

Solving Two Equations

- $[m11 \ m12; \ m21 \ m22] \setminus [b1; \ b2]$ or $[b1; \ b2] / [m11 \ m12; \ m21 \ m22]$ solves the system $\begin{bmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$ for $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$.
- The MATLAB command will always output a solution, usually close to infinity if there are none; and only output one if there are infinite number of them.
- There will be a warning about the matrix being singular.

System of Equations Math

$$\begin{cases} m_{11}x_1 + m_{12}x_2 + \ldots + m_{1n}x_n = b_1 \\ m_{21}x_1 + m_{22}x_2 + \ldots + m_{2n}x_n = b_2 \\ \ldots \\ m_{k1}x_1 + m_{k2}x_2 + \ldots + m_{kn}x_n = b_k \\ \text{equations and } n \text{ unknowns } x_1, x_2, \ldots, x_n. \end{cases}$$
 is a system of k

• The system can be written in matrix form

$$\begin{bmatrix} m_{11} & m_{12} & \dots & m_{1n} \\ m_{21} & m_{22} & \dots & m_{2n} \\ \dots & \dots & \dots & \dots \\ m_{k1} & m_{k2} & \dots & m_{kn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \dots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \dots \\ b_k \end{bmatrix}, \text{ or } Mx = b.$$

Solving a System Math

- Let Mx = b be a system of linear equations.
- x can be solved by hand using Gaussian elimination.
- It is faster to solve for x using LU decomposition.

LU Decomposition

- Every matrix M can be written in the form PM = LU.
- P is a permutation matrix (each row and each column contain one 1 and all other entries are 0s).
- ② L is a lower triangular matrix (all entries above the diagonal are 0s).
- U is a upper triangular matrix (all entries below the diagonal are 0s).
 - Mx = b can be solved by solving Ly = Pb for y then solving Ux = y for x.

Two by Two LU Decomposition Math

- $m_{11} \neq 0$, and if $m_{11} = 0$, $P = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ can be used instead.
- This makes solving Ly = b and Ux = y very fast since only forward and backward substitutions are required.

Solving Code

- $M \setminus b$ or b / M solves Mx = b for x.
- [L, U, P] = lu(M) computes the LU decomposition and $y = L \setminus (P * b)$; $x = U \setminus y$ also solves Mx = b for x.
- In the case Mx = b needs to be solved repeatedly for the same M but different b's, it is faster to find the LU decomposition once and use L, U, P on different b's.
- d = decomposition(M, 'lu'); d \ b uses the same LU decomposition approach without the need to remember how to solve for x given the decomposition.

Linear System Quiz Questions

Invertability Math

- A square matrix M is invertible if there exists M^{-1} such that $M^{-1}M = I$, and M is singular if it is not invertible.
- If M is invertible, then the solution to Mx = b is $x = M^{-1}b$.
- If M is singular, then Mx = b may not have a solution for x.

Determinant Math

- The determinant of a matrix M, denoted by det(M) or |M|, measures the magnitude of a matrix.
- det(M) = 0 if and only if M is singular.
- When det(M) is close to 0, M could be difficult to invert due to numerical errors, and MATLAB issues a warning about the matrix being close to singular.

Condition Number

- Matrices that are close to singular are also called ill-conditioned.
- The condition number of a matrix M, denoted by $\kappa(M)$, measures how much the solution x changes due to a small error in b.
- The larger the condition number, the more sensitive the solution is to the changes in *b*, which implies that numerical errors are more likely to affect the solution.
- If *M* is not invertible, the condition number of *M* is infinity.

Inversion and Condition Number

- inv(M) finds the inverse of a square matrix M.
- det(M) finds the determinant of a square matrix M.
- cond(M) finds the condition number of a matrix M.

Hilbert Matrix

- Hilbert matrix is an example of an ill-conditioned matrix.
- Row *i* column *j* of a Hilbert matrix is $H_{ij} = \frac{1}{i+j-1}$.
- For example, a 3 by 3 Hilbert matrix is $\begin{bmatrix} 1 & 1/2 & 1/3 \\ 1/2 & 1/3 & 1/4 \\ 1/3 & 1/4 & 1/5 \end{bmatrix}$,

and a 4 by 4 Hilbert matrix is
$$\begin{bmatrix} 1 & 1/2 & 1/3 & 1/4 \\ 1/2 & 1/3 & 1/4 & 1/5 \\ 1/3 & 1/4 & 1/5 & 1/6 \\ 1/4 & 1/5 & 1/6 & 1/7 \end{bmatrix}.$$

• hilb (n) creates the n by n Hilbert matrix.

Condition Number Quiz Questions

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