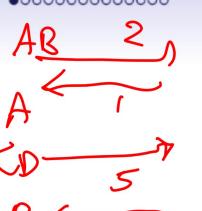
# CS540 Introduction to Artificial Intelligence Lecture 17

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Based on lecture slides by Jerry Zhu, Yingyu Liang, and Charles

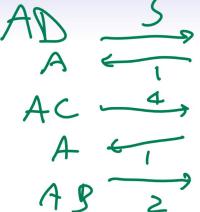
Dyer

July 26, 2021



### Bridge and Torch Game





Four people with one flashlight (torch) want to go across a river. The bridge can hold two people at a time, and they must cross with the flashlight. The time it takes for each person to cross the river:

Α	В	С	D
1	2	4	5

- What is the minimum total time required for everyone to cross the river?
- A: 10, B: 11, C: 12, D: 13, E: 14

# Remind Me to Start Recording

• The messages you send in chat will be recorded: you can change your Zoom name now before I start recording.

## Reduced Space Example 2

Quiz

go through

Triday

[1]

• 
$$\hat{\Sigma} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$
 . If one original data is  $x = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$  . What is

the new representation using only the first two principal components?

• A: 
$$\begin{bmatrix} 1 \\ 2 \end{bmatrix}$$
, B:  $\begin{bmatrix} 2 \\ 1 \end{bmatrix}$ , C:  $\begin{bmatrix} 1 \\ 3 \end{bmatrix}$ , D:  $\begin{bmatrix} 3 \\ 1 \end{bmatrix}$ , E:  $\begin{bmatrix} 2 \\ 3 \end{bmatrix}$ 

# Reduced Space Example 3

• 
$$\hat{\Sigma} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$
. If one original data is  $x = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ . What is

the reconstructed vector using only the first two principal components?

• A: 
$$\begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}$$
, B:  $\begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix}$ , C:  $\begin{bmatrix} 0 \\ 2 \\ 3 \end{bmatrix}$ , D:  $\begin{bmatrix} 2 \\ 3 \\ 1 \end{bmatrix}$ , E:  $\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ 

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#### Autoencoder

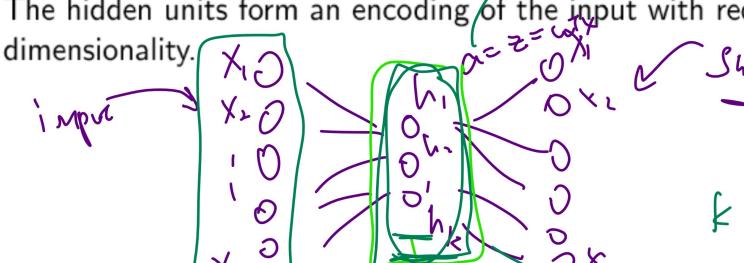
Discussion



 A multi-layer neural network with the same input and output  $y_i = x_i$  is called an autoencoder.

 The hidden layers have fewer units than the dimension of the input *m*.

the input with reduced PCA The hidden units form an encoding of





 A kernel can be applied before finding the principal components.

$$\hat{\Sigma} = \frac{1}{n-1} \sum_{i=1}^{n} \varphi(x_i) \varphi(x_i)^T$$
where the transformed feature

- The principal components can be found without explicitly computing  $\varphi(x_i)$ , similar to the kernel trick for support vector machines.
- Kernel PCA is a non-linear dimensionality reduction method.

# Learning vs Search



- In reinforcement learning, the reward and state transition need to be learned by taking actions.
- In search problems, the reward and state transitions are given.
- The problem is to find a <u>sequence</u> of actions that lead to the goal with minimum cost.

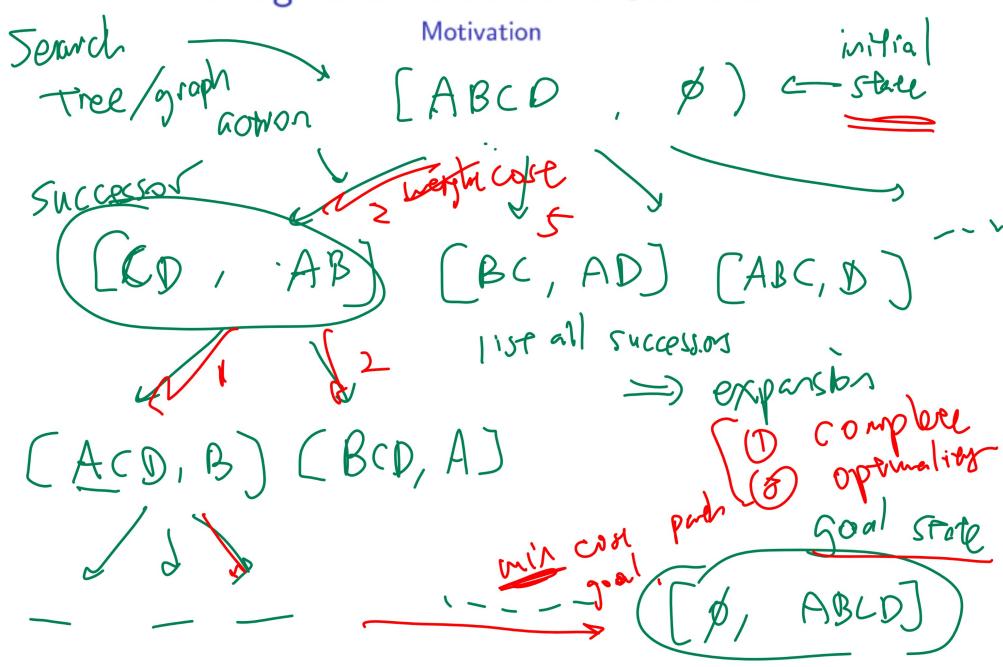
### Bridge and Torch Game Again

Motivation

 Four people with one flashlight (torch) want to go across a river. The bridge can hold two people at a time, and they must cross with the flashlight. The time it takes for each person to cross the river:

Α	В	С	D
1	2	4	5

### Bridge and Torch Game States 1



### Bridge and Torch Game States 2

Motivation

### Sizes of State Space

Motivation

Tic Tac Toe: 10<sup>3</sup>

Checkers: 10<sup>20</sup>
Chess: 10<sup>50</sup>
Go: 10<sup>170</sup>

adversaria) seach. (next neeb)

#### Performance

#### **Definition**

- A search strategy is complete if it finds at least one solution.
- A search strategy is optimal if it finds the optimal solution.
- For uninformed search, the costs are assumed to be 1 for all edges c = 1.

### Complexity

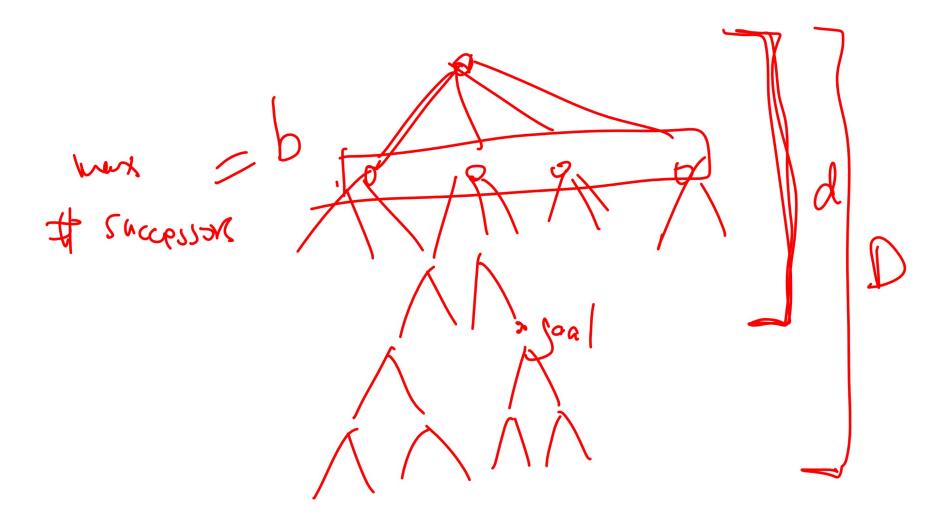
#### Definition

- The time complexity of a search strategy is the worst case maximum number of vertices expanded.
- The space complexity of a search strategy is the worst case maximum number of states stored in the frontier at a single time.
- Notation: the goals are d edges away from the initial state.
   This means assuming a constant cost of 1, the optimal solution has cost d. The maximum depth of the graph is D.
- Notation: the branching factor is b, the maximum number of actions associated with a state.

$$b = \max_{s \in V} \left| s'\left(s\right) \right|$$

### Search Tree Diagram

Definition



# Breadth First Search Description

- Use Queue (FIFO) for the frontier.
- Remove from the front, add to the back.

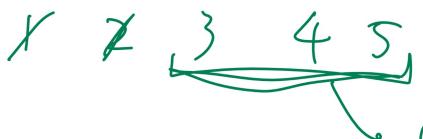
expanded expanded ...

# BFS Example 1

 Fall 2018 Midterm Q2, Fall 2017 Midterm Q13, Fall 2010 Final Q2 Costy = Suppose the states are positive integers between 1 and 10, initial state is 1, goal state is 9, successors of i is 2i and  $500^{\circ}2i + 1$  (if exist). What a BFS expansion sequence? SUECESSONS!

### BFS Example 1 Diagram

Quiz



space of 3

transluer.

## BFS Example 2

Quiz

• Suppose the states are integers between 1 and  $2^{10} = 1024$ . The initial state is 1, and the goal state is 1024. The successors of a state i are 2i and 2i + 1, if exist. How many states are expanded during a BFS search?

· A: 10 < shown length

• C: 12

D: 1023

XZX4567



## BFS Example 3

Quiz

• Suppose the states are integers between 1 and  $2^{10} - 1 = 1023$ . The initial state is 1, and the goal state is 1023. The successors of a state i are 2i and 2i + 1, if exist. How many states are expanded during a BFS search?

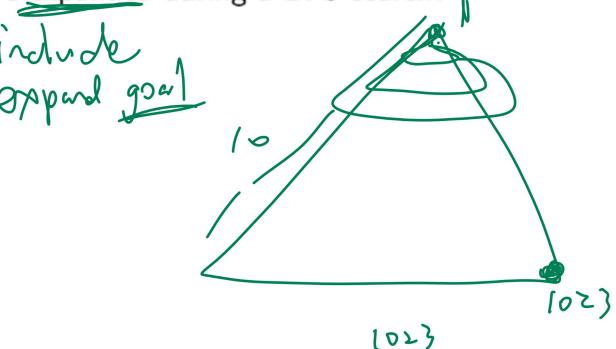
• A: 10

B: 11

• C: 12

D: 1023

E: 1024



#### Breadth First Search Performance

Discussion

- BFS is complete.
- BFS is optimal with c = 1.

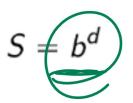
#### Breadth First Search Complexity

Discussion

 Time complexity: the worst case occurs when the goal is the last vertex at depth d.

$$T \stackrel{\swarrow}{=} b + b^2 + \dots + b^d$$

 Space complexity: the worst case is storing all vertices at depth d is in the frontier.





#### Depth First Search

Description

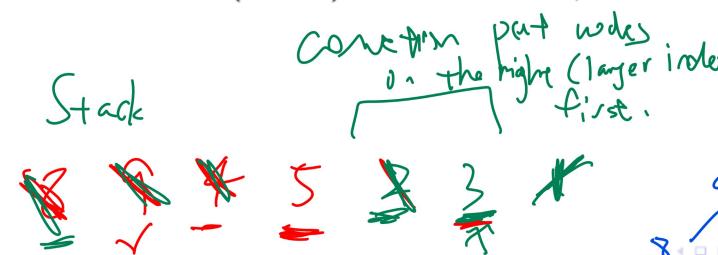
- Use Stack (LIFO) for the frontier.
- Remove from the front, add to the front.

# DFS Example 1 Quiz

Spare. 3.5,89, Aire: 1.2,4,8,9

Fall 2018 Midterm Q2, Fall 2017 Midterm Q13, Fall 2010
 Final Q2

Suppose the states are positive integers between 1 and 10, initial state is 1, goal state is 9, successors of i is 2i and 2i + 1 (if exist). What a DFS expansion sequence?



# DFS Example 1 Diagram

## DFS Example 2

Quiz

Q4 —

Suppose the states are integers between 1 and  $2^{10} = 1024$ . The initial state is 1, and the goal state is 1024. The successors of a state i are 2i and 2i + 1, if exist. How many states are expanded during a DFS search?

• A: 10

B: 11 9, 9

H. 5 ZI

pushed

• C: 12 2<sup>2</sup>

D: 1023

E: 1024

Goal is expanded



## DFS Example 3

Quiz

QJ

• Suppose the states are integers between 1 and  $2^{10} - 1 = 1023$ . The initial state is 1, and the goal state is 1023. The successors of a state *i* are 2*i* and 2*i* + 1, if exist. How many states are expanded during a DFS search?

A: 10

B: 11

• C: 12

D: 1023

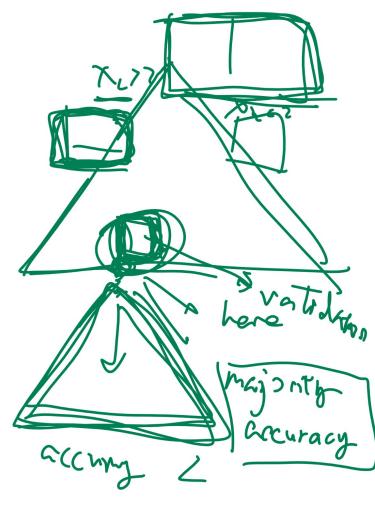
E: 1024



### Depth First Search Performance

Discussion

- DFS is incomplete if  $D = \infty$ .
- DFS is not optimal.



### Depth First Search Complexity

#### Discussion

 Time complexity: the worst case occurs when the goal is the root of the last subtree expanded in the whole graph.

$$T = b^{D-d+1}... + b^{D-1} + b^{D}$$

 Space complexity: the worst case is storing all vertices sharing the parents with vertices in the current path.

$$S = (b-1)D + 1$$

### Iterative Deepening Search

#### Description

- DFS but stop if path length > 1
- repeat DFS but stop if path length > 2
- ...
- repeat DFS but stop if path length > d

# IDS Example 1 Quiz

- Fall 2018 Midterm Q2, Fall 2017 Midterm Q13, Fall 2010
   Final Q2
- Suppose the states are positive integers between 1 and 10, initial state is 1, goal state is 9, successors of i is 2i and 2i + 1 (if exist). What a IDS expansion sequence?

# IDS Example 1 Diagram

#### Iterative Deepening Search

#### Algorithm

- Input: a weighted digraph (V, E, c), initial states I and goal states G.
- Output: a path from I to G.
- Perform DFS on the digraph restricted to vertices with depth
   ≤ 1 from the initial state.
- Perform DFS on the digraph restricted to vertices with depth
   ≤ 2 from the initial state.
- Repeat until the goal is deQueued.

## Iterative Deepening Search Performance

Discussion

- IDS is complete.
- IDS is optimal with c = 1.

### Iterative Deepening Search Complexity

#### Discussion

 Time complexity: the worst case occurs when the goal is the last vertex at depth d.

$$T = db + (d-1)b^{2} + \dots + 3b^{d-2} + 2b^{d-1} + 1b^{d}$$

Space complexity: it has the same space complexity as DFS.

$$S = (b-1) d$$

## Configuration Space

Discussion