

CS540 Introduction to Artificial Intelligence

Lecture 1

Young Wu

Based on lecture slides by Jerry Zhu, Yingyu Liang, and Charles Dyer

May 9, 2020

Lecture Format

Admin

- Pre-recorded lectures will be posted on the course website.
- University-assigned lecture time will be used to go over examples and for participation quizzes.
- The remaining lecture time will be used as office hours.

Quizzes

Admin

- Download Socrative, the room number is CS540E or CS540C.
- Default login for Socrative is your wisc email ID.
- If someone else tries to hack your account, please email or post on Piazza.
- Quiz questions can show up any time during the lecture.
- Missing one or two questions due to technical difficulty is okay.
- If you select obviously false answers, you might lose points.

Math Homework

Admin

- Officially: due in 1 week Sunday.
- Unofficially: any time before the midterm or the final.
- Auto-graded: submit the output on Canvas.

Programming Homework

Admin

- Officially: due in 2 weeks Sunday.
- Unofficially: any time before the final.
- Solution: posted in 1 week Sunday.
- Auto-graded: submit the output on Canvas.
- Code: any language.

Python Java

Midterm and Final

Admin

- Synchronous exam: morning and evening one, choose one to take.

(Not recommended) Ways to Get B+ Admin

- Not attending any lecture.
- Not doing any math homework.
- Not doing half of the programming homework.
- Not taking any of the exams (only this summer).

Only Way to Get A Admin

- Do everything.

Textbook

Admin

- Lecture slides and videos will be sufficient.
- RN is a good background reading, does not cover everything.
- SS is very theoretical, useful if you are planning to take 760, 761, 861.

Admin

Admin

- Math and Stat Review posted under W1.
- Annotated slides will not be posted (because my handwriting is not recognizable).
- Unofficially: all homework are already posted (lots of mistakes and bugs).
- Officially: homework will be posted two to three days after the corresponding lecture.

Is This Face Real

Quiz

- Which face is real?
- A: Left
- B: Right
- C: Do not choose this
- D: Do not choose this
- E: Do not choose this

Generative Adversarial Network

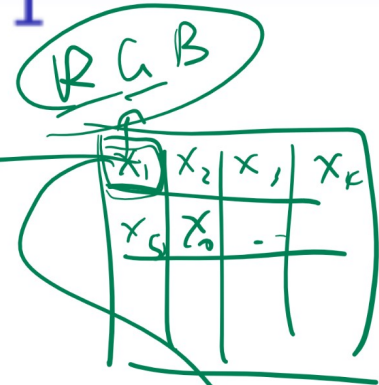
Motivation

- Generative Adversarial Network (GAN):

- ① Generative part: input random noise and output fake images.
- ② Discriminative part: input real and fake images and output labels real or fake.
- ③ The two parts compete with each other.

Supervised Learning Example 1

Motivation



$$f(\vec{x}) = \hat{y}$$

Data	← images of cats and dogs
Features (Input)	← height, length, eye color, ...
-	← pixel intensity
Output	← cat or dog

$$f(\vec{X}) = \hat{y}$$

Supervised Learning Example 2

Motivation

$$f(x) = \hat{y}$$

Data	medical records
Features (Input)	scan, blood, and other test results
Output	disease or no

Data	patient information
Features (Input)	age, pre-existing conditions, ...
Output	likelihood of death

Supervised Learning Example 3

Motivation

Data	face images
Features (Input)	edges, corners, ...
Output	face or non-face

2D

CNN

Data	^{3D} self-driving car data ^{4D}
Features (Input)	<u>distance (depth), movement, ...</u>
Output	road or non-road

Supervised Learning Example 4

Motivation

$$f(x_1, x_2, x_3, \dots)$$

$$f(x) = \hat{y}$$

Data	emails
Features (Input)	word count, capitalization, ...
Output	spam or ham

Data	comments
Features (Input)	word count, capitalization, ...
Output	offensive or not

RNW

Supervised Learning Example 6

Motivation

$\delta \sigma$ $\phi \psi$ ρ_1

Data	handwritten letters
Features (Input)	<u>pixel</u> , <u>stroke</u>
Output	<u>δ or σ</u> , <u>ϕ or ψ</u>

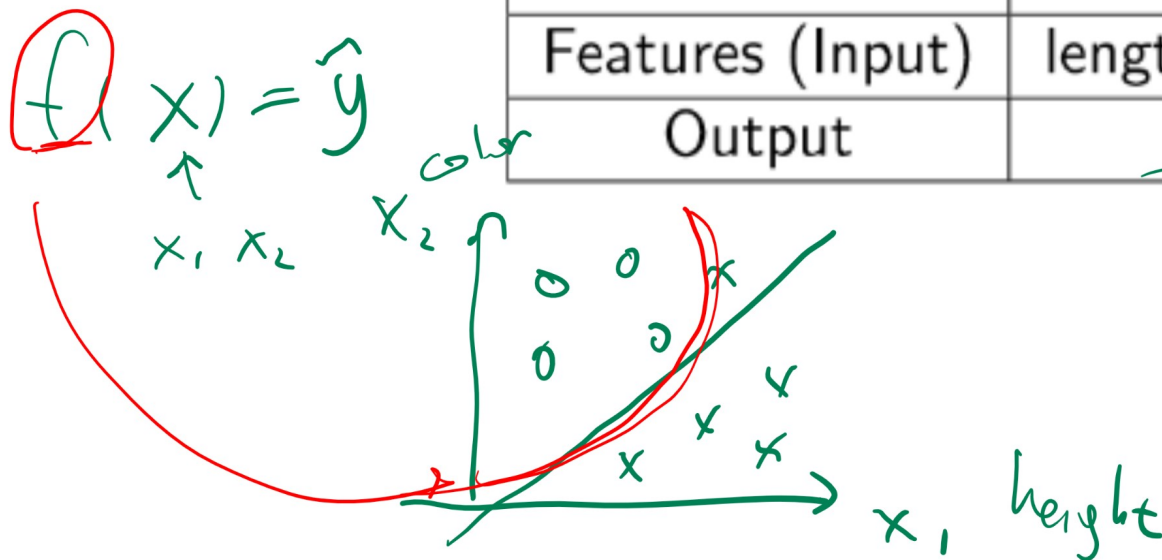
Data	voice recording
Features (Input)	<u>signal</u> , <u>sound</u> (phoneme)
Output	<u>recognize speech</u> or <u>wreck a nice beach</u>

Supervised Learning Example 7

Motivation

Data	painting
Features (Input)	appearance, price, ...
Output	art or garbage

Data	essay
Features (Input)	length, key words
Output	<u>A+</u> or F



Supervised Learning

Motivation

$$\hat{f}(x) \approx y$$

- Supervised learning:

Data	Features (Input)	Output	-
Sample	$\{(x_{i1}, \dots, x_{im})\}_{i=1}^n$	$\{y_i\}_{i=1}^n$	find "best" \hat{f}
-	observable	known	-
New	(x'_1, \dots, x'_m)	y'	guess $\hat{y} = \hat{f}(x')$
-	observable	unknown	-

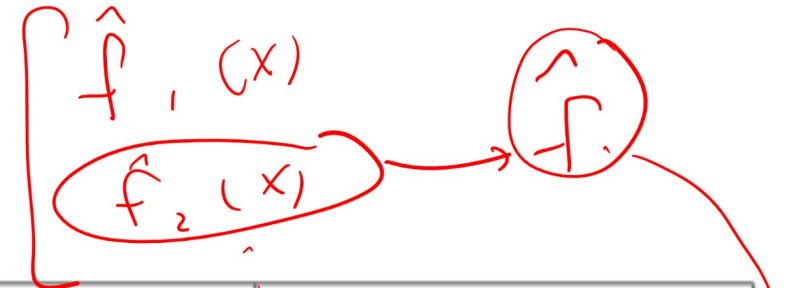
m # pixel
 n # images
 n # label



Training and Test Sets

Motivation

- Supervised learning:

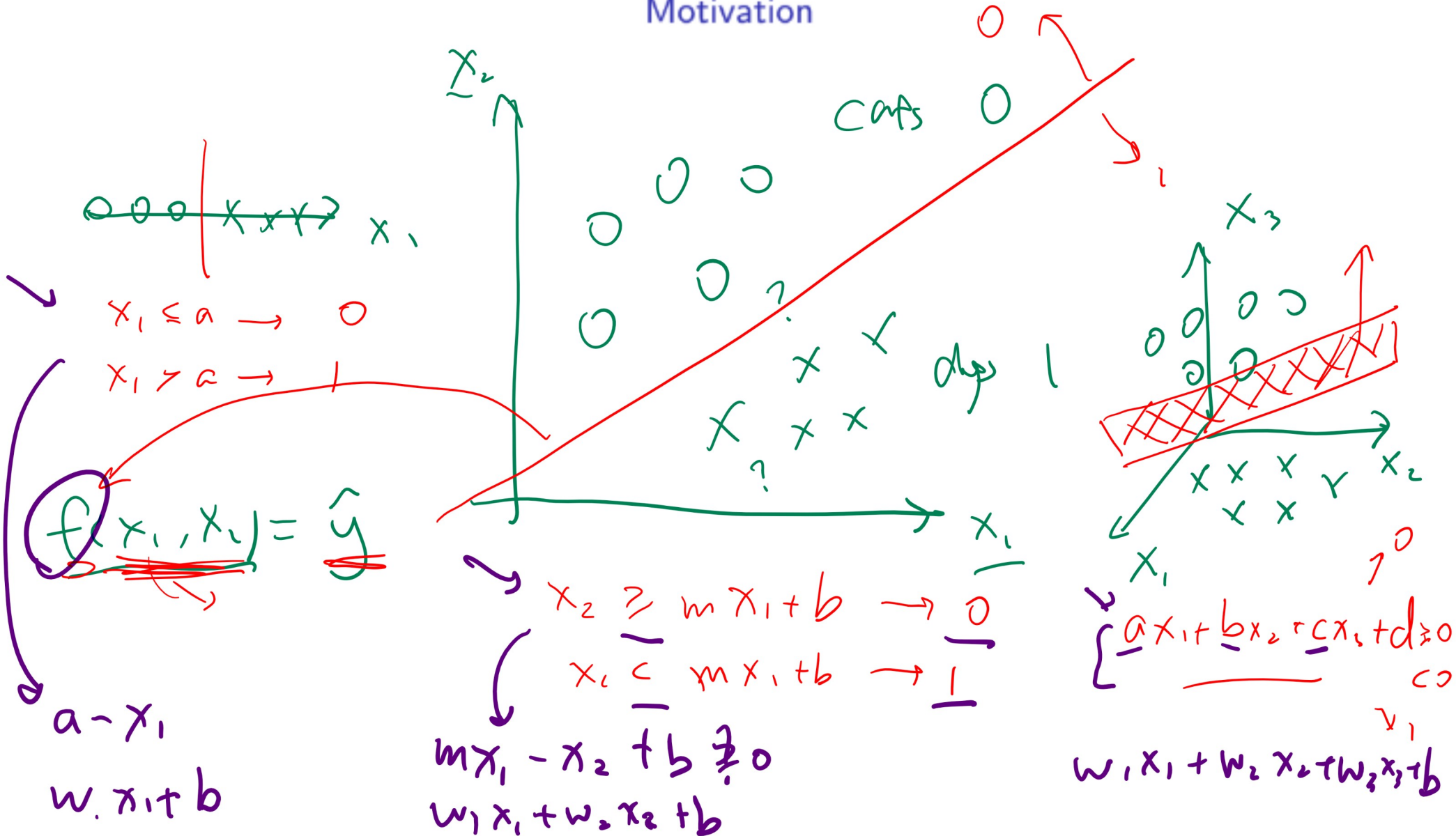


Sample

Data	Features (Input)	Output	-
Training	$\{(x_{i1}, \dots, x_{im})\}_{i=1}^{n'}$	$\{y_i\}_{i=1}^{n'}$	find "good" \hat{f}
-	observable	known	-
Validation	$\{(x_{i1}, \dots, x_{im})\}_{i=n'+1}^n$	$\{y_i\}_{i=n'+1}^n$	find "best" \hat{f}
-	observable	known	-
Test	(x'_1, \dots, x'_m)	y'	guess $\hat{y} = \hat{f}(x')$
-	observable	unknown	-

Simple 2D Example Diagram

Motivation



Linear Classifier

Motivation

- One possible guess is in the form of a linear classifier.

$$\hat{y} = \mathbb{1}_{\{w_1 x_1 + w_2 x_2 + \dots + w_m x_m + b \geq 0\}}$$

$$= \mathbb{1}_{\{w^T x + b \geq 0\}}$$

m-D hyperplane
↑
features

$$w = \begin{pmatrix} w_1 \\ w_2 \\ \vdots \\ w_m \end{pmatrix}$$

- The $\mathbb{1}$ (open number 1) is the indicator function.

$$w^T = (w_1, w_2, \dots, w_m)$$

$$\mathbb{1}_E = \begin{cases} 1 & \text{if } E \text{ is true} \\ 0 & \text{if } E \text{ is false} \end{cases}$$

$$w^T x + b = (w_1, w_2, \dots, w_m) \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \end{pmatrix} + \underline{b} = w_1 x_1 + w_2 x_2 + \dots + x_m w_m + b$$

Linear Threshold Unit

Motivation

- This simple linear classifier is also called a Linear Threshold Unit (LTU) Perceptron.
- w_1, w_2, \dots, w_m are called the weights, and b is called the bias.
- The function that makes the prediction based on $w^T x + b$ is called the activation function.
- For an LTU Perceptron, the activation function is the indicator function.

$$g(\cdot) = \mathbb{1}_{\{\cdot \geq 0\}}$$

$$\hat{y} = g(w^T x + b)$$

Equation of a Line

Motivation

- In $1D$, $w_1x_1 + b \geq 0$ is just a threshold rule: $x_1 \geq -\frac{b}{w_1}$ implies $\hat{y} = 1$.
- In $2D$, $w_1x_1 + w_2x_2 + b \geq 0$ can be written as $\begin{bmatrix} w_1 & w_2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + b \geq 0$. Note that $w_1x_1 + w_2x_2 + b = 0$ is the equation of a line, usually written as $x_2 = -\frac{w_1}{w_2}x_1 - \frac{b}{w_2}$.

Equation of a Hyperplane

Motivation

- In $3D$, $w_1x_1 + w_2x_2 + w_3x_3 + b \geq 0$ can be written as

$$\begin{bmatrix} w_1 & w_2 & w_3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + b \geq 0. \text{ Note that}$$

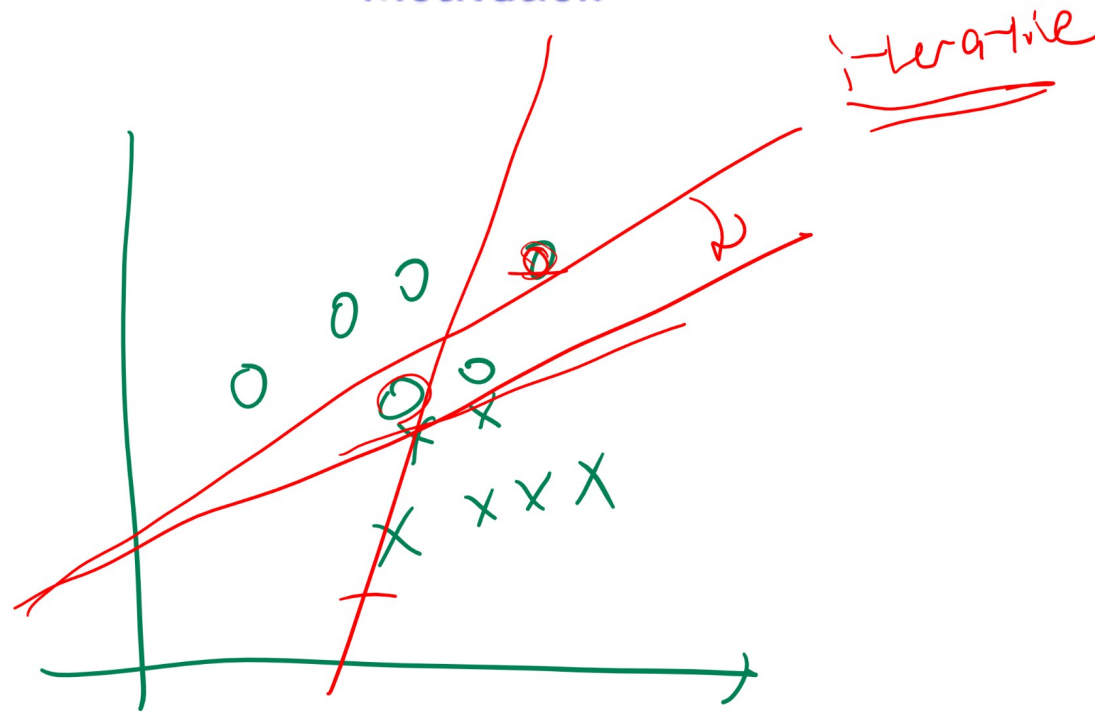
$w_1x_1 + w_2x_2 + w_3x_3 + b = 0$ is the equation of a plane, and

$\begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix}$ is normal vector of the plane.

- The normal vector is perpendicular to all vectors on the plane.

Brute Force LTU Learning

Motivation



Perceptron Algorithm

Description

- Initialize random weights.
- Evaluate the activation function at one instance x_i to get \hat{y}_i .
- If the prediction \hat{y}_i is 0 and actual y_i is 1, increase the weights by x_i .
- If the prediction \hat{y}_i is 1 and actual y_i is 0, decrease the weights by x_i .
- Repeat for all data points and until convergent.

Handwritten notes:

x_i, y_i

① $y_i \rightarrow \hat{y}_i$ do nothing

②

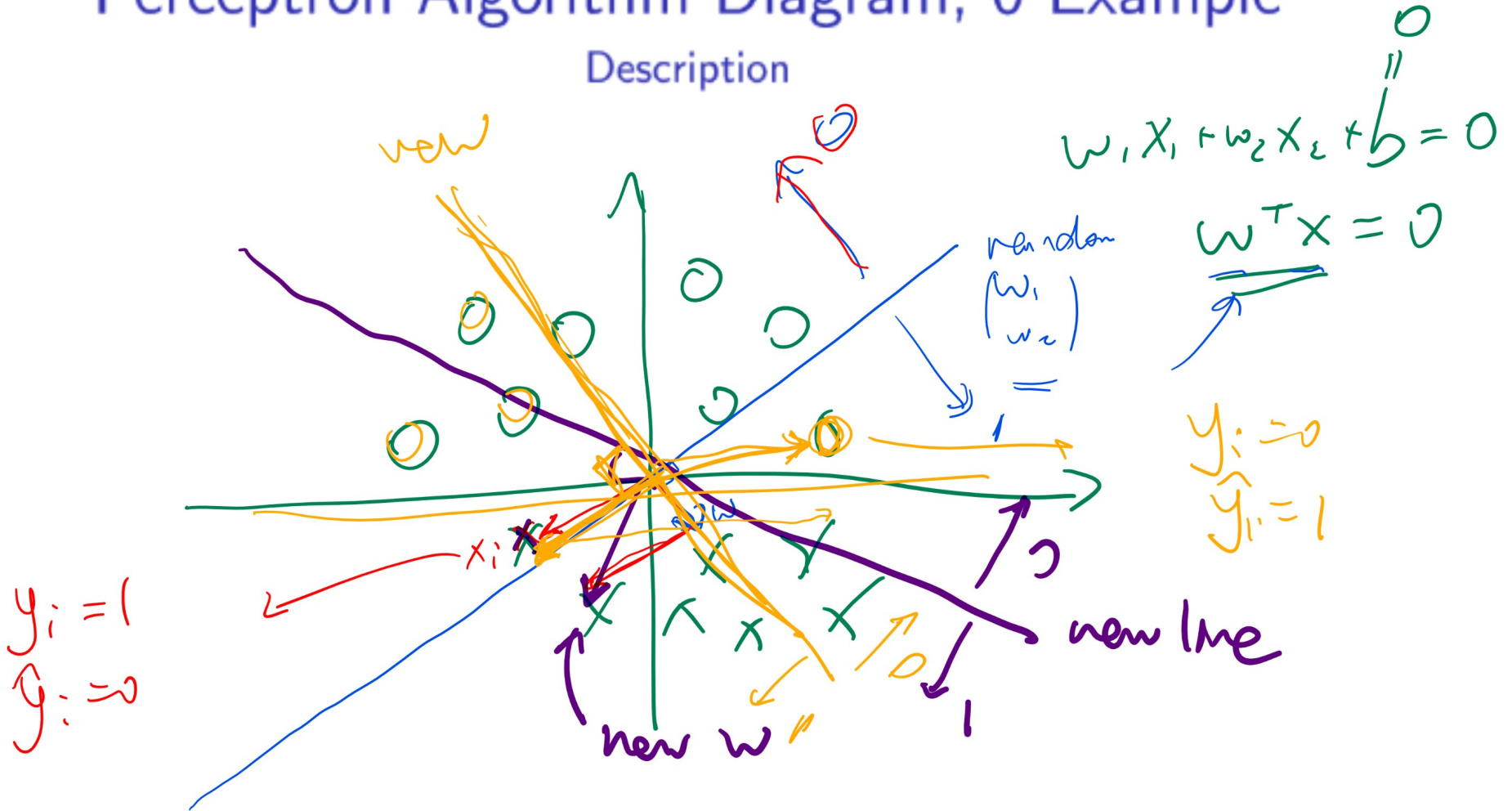
$w + x_i$

$w - x_i$

(Red circles and arrows highlight key terms and flow between steps.)

Perceptron Algorithm Diagram, 0 Example

Description



Perceptron Algorithm Diagram, 1 Example

Description

Perceptron Algorithm, Part 2

Algorithm

- Update weights using the following rule.

$$w = w - \alpha (a_i - y_i) x_i$$

$$b = b + \alpha (a_i - y_i)$$

(Handwritten notes: The equations are circled in yellow. The coefficient α in the first equation is circled in red. A red arrow points from the circled α to the circled $(a_i - y_i)$ term in the second equation.)

- Repeat the process for every $x_i, i = 1, 2, \dots, n$.
- Repeat until $a_i = y_i$ for every $i = 1, 2, \dots, n$.

(Handwritten notes in yellow ink):

y_i ↓

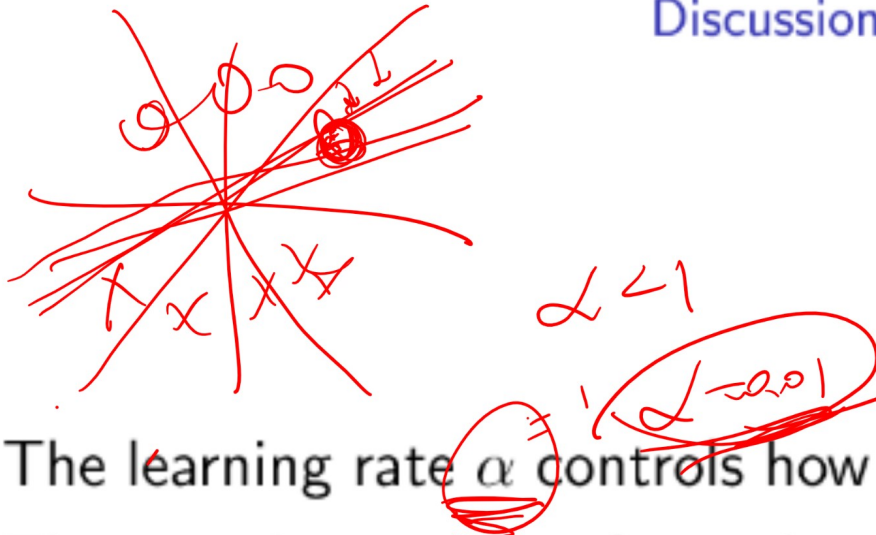
$a_i = y_i = 0, 1$
 $w = w$ ✓

$a_i = 1, y_i = 0$
 $w = w - x_i$

$a_i = 0, y_i = 1$
 $w = w + x_i$

Learning Rate

Discussion



- The learning rate α controls how fast the weights are updated.
- They can be constant for each update or they can change (usually decrease) for each update.
- For perceptron learning, it is typically set to 1.

Perceptron Algorithm

Quiz