## CS540 Introduction to Artificial Intelligence Lecture 4

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Based on lecture slides by Jerry Zhu and Yingyu Liang

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# Test Quiz (Graded)

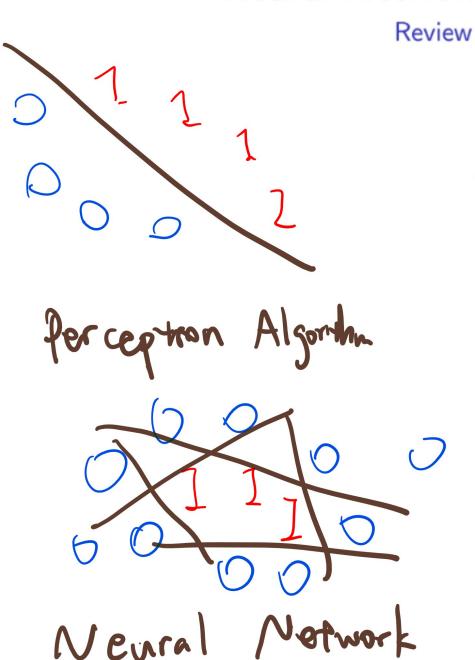
- A:
- B:
- C:
- D: Choose this.
- E:

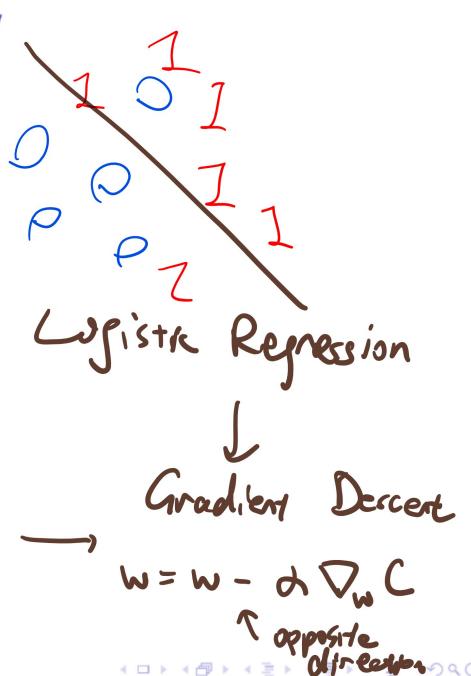
# Homework Quiz (Participation)

- Have you finished homework 1
- A: Waiting for solution.
- B: Will start soon.
- C: Started.
- D: Does not work due to bugs.
- E: Finished: 90+ percent accuracy.

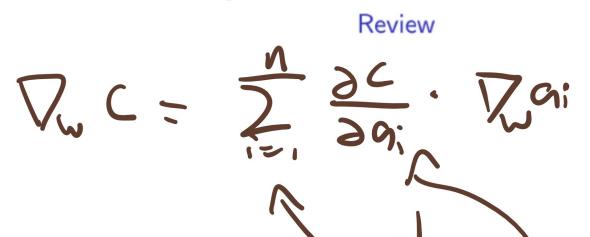
### Neural Network Diagram







## Multi-Layer Neural Network Diagram



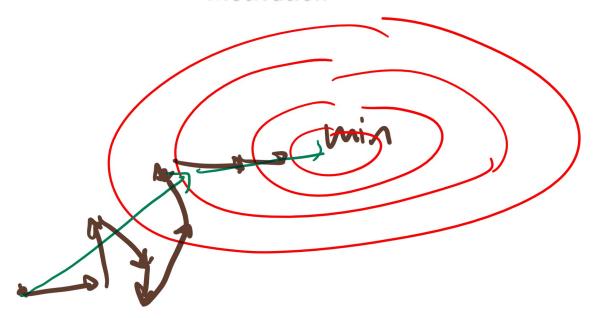
#### Stochastic Gradient Descent

#### Motivation

- Each gradient descent step requires the computation of gradients for all training instances i = 1, 2, ..., n. It is very costly.
- Stochastic gradient descent picks one instance  $x_i$  randomly, compute the gradient, and update the weights and biases.
- When a batch of instances is selected randomly each time, it is called batch gradient descent.

### Stochastic Gradient Descent Diagram

#### Motivation



# Stochastic Gradient Descent, Part 1 Algorithm

- Inputs, Outputs: same as backpropagation.
- Initialize the weights.
- Randomly permute (shuffle) the training set. Evaluate the activation functions at one instance at a time.
- Compute the gradient using the chain rule.

weight 
$$\frac{\partial C}{\partial w_{j'j}^{(l)}} = \delta_{ij}^{(l)} a_{ij'}^{(l-1)}$$

$$\frac{\partial C}{\partial b_{j}^{(l)}} = \delta_{ij}^{(l)}$$

## Stochastic Gradient Descent, Part 2

#### Algorithm

Update the weights and biases using gradient descent.

For 
$$l = 1, 2, ..., L$$

$$w_{j'j}^{(I)} \leftarrow w_{j'j}^{(I)} - \alpha \frac{\partial C}{\partial w_{j'j}^{(I)}}, j' = 1, 2, ...., m^{(I-1)}, j = 1, 2, ...., m^{(I)}$$

$$b_j^{(I)} \leftarrow b_j^{(I)} - \alpha \frac{\partial C}{\partial b_j^{(I)}}, j = 1, 2, ...., m^{(I)}$$

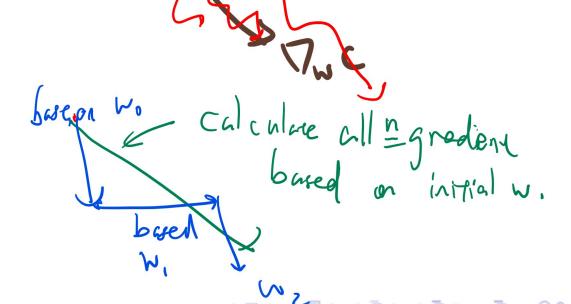
Repeat the process until convergent.

$$|C - C|^{\mathsf{prev}}| < \varepsilon$$

#### Stochastic vs Full Gradient Descent

Quiz (Participation)

- Given the same initial weights and biases, stochastic gradient descent with instances picked randomly without replacement and full gradient descent lead to the same updated weights.
- A: Do not choose this.
- B: True.
- C: Do not choose this.
- D: False.
- E: Do not choose this.



#### Generalization Error

#### Motivation

- With a large number of hidden units and small enough learning rate α, a multi-layer neural network can fit every finite training set perfectly.
- It does not imply the performance on the test set will be good.
- This problem is called overfitting.

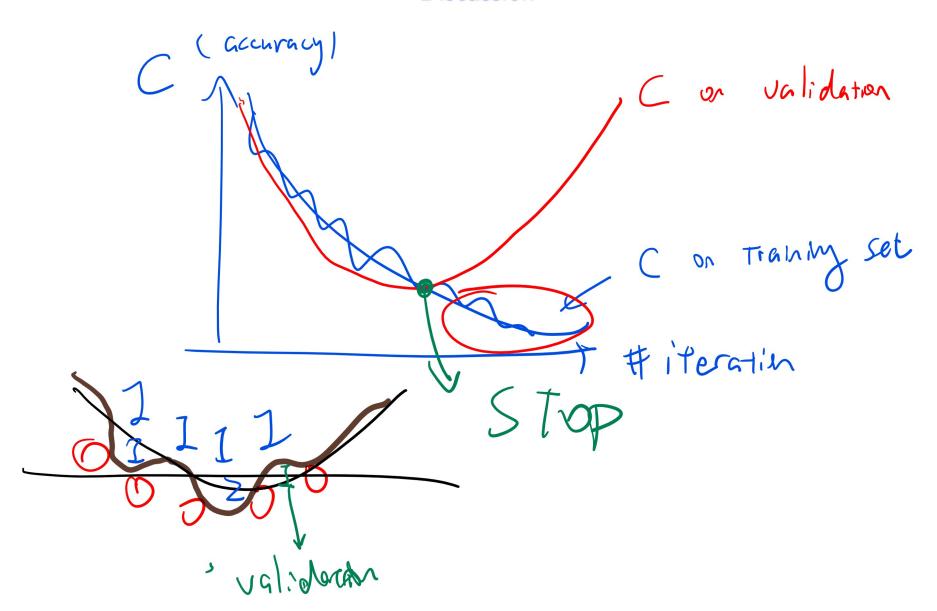
### Generalization Error Diagram

Motivation

#### Method 1, Validation Set

- Set aside a subset of the training set as the validation set.
- During training, the cost (or accuracy) on the training set will always be decreasing until it hits 0.
- Train the network until the cost (or accuracy) on the validation set begins to increase.

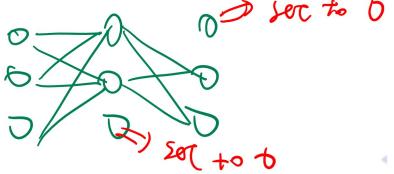
### Validation Set Diagram



### Method 2, Drop Out



- At each hidden layer, a random set of units from that layer is set to 0.
- For example, each unit is retained with probability p = 0.5. During the test, the activations are reduced by p = 0.5 (or 50 percent).
- The intuition is that if a hidden unit works well with different combinations of other units, it does not rely on other units and it is likely to be individually useful.





## Drop Out Diagram

#### Method 3, L1 and L2 Regularization



- The idea is to include an additional cost for non-zero weights.
- The models are simpler if many weights are zero.
- For example, if logistic regression has only a few non-zero weights, it means only a few features are relevant, so only these features are used for prediction.

### Method 3, L1 Regularization

#### Discussion

 For L1 regularization, add the 1-norm of the weights to the cost.

Cost.

$$C = \sum_{i=1}^{n} (a_i - y_i)^2 + \lambda \left\| \begin{bmatrix} w \\ b \end{bmatrix} \right\|_1$$

$$= \sum_{i=1}^{n} (a_i - y_i)^2 + \lambda \left( \sum_{i=1}^{m} |w_i| + |b| \right)$$
weights.

• Linear regression with L1 regularization is called LASSO (least

 Linear regression with L1 regularization is called LASSO (least absolute shrinkage and selection operator).

#### Method 3, L2 Regularization

Discussion

 For L2 regularization, add the 2-norm of the weights to the cost.

$$C = \sum_{i=1}^{n} (a_i - y_i)^2 + \frac{\lambda}{2} \left\| \begin{bmatrix} w \\ b \end{bmatrix} \right\|_{2}^{2}$$

$$|\text{earnly rate}| = \sum_{i=1}^{n} (a_i - y_i)^2 + \frac{\lambda}{2} \left( \sum_{i=1}^{m} w_i^2 + b^2 \right)$$

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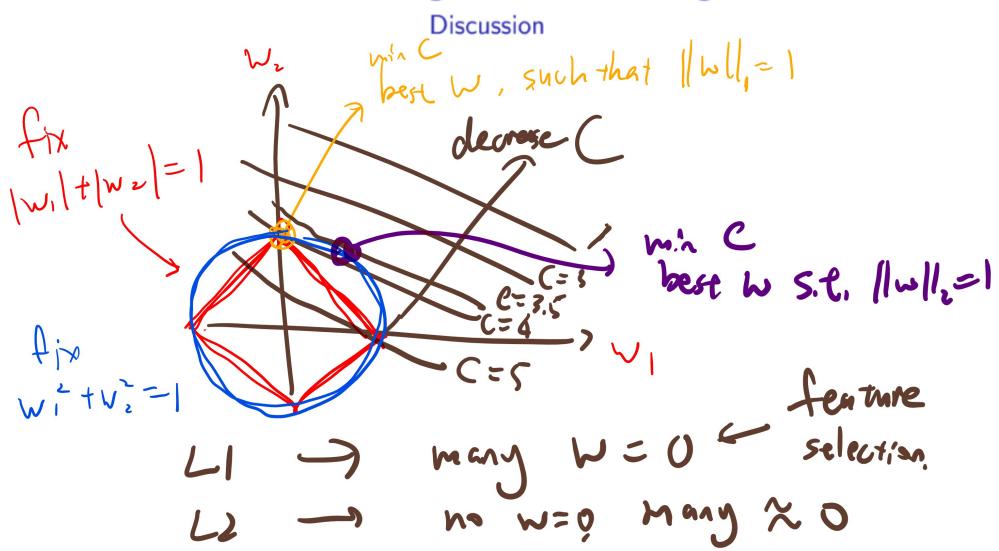
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#### L1 and L2 Regularization Comparison

- L1 regularization leads to more weights that are exactly 0. It is useful for feature selection.
- L2 regularization leads to more weights that are close to 0. It is easier to do gradient descent because 1-norm is not differentiable.

#### L1 and L2 Regularization Diagram



# Method 4, Data Augmentation

Discussion

 More training data can be created from the existing ones, for example, by translating or rotating the handwritten digits.

#### Hyperparameters

- It is not clear how to choose the learning rate  $\alpha$ , the stopping criterion  $\varepsilon$ , and the regularization parameters.
- For neural networks, it is also not clear how to choose the number of hidden layers and the number of hidden units in each layer.
- The parameters that are not parameters of the functions in the hypothesis space are called hyperparameters.

#### K Fold Cross Validation

Discussion

train on training set to find v. b

test an validation to compare performance

Partition the training set into K groups.

C, accuracy.

- Pick one group as the validation set.
- Train the model on the remaining training set.
- Repeat the process for each of the K groups.
- Compare accuracy (or cost) for models with different hyperparameters and select the best one.

## 5 Fold Cross Validation Example

Discussion

• Partition the training set S into 5 subsets  $S_1, S_2, S_3, S_4, S_5$ 

$$S_i \cap S_j = \emptyset$$
 and  $\bigcup_{i=1}^5 S_i = S$ 

Iteration	Training	Validation		
1	$S_2 \cup S_3 \cup S_4 \cup S_5$	$S_1$		
2	$S_1 \cup S_3 \cup S_4 \cup S_5$	$S_2$		
3	$S_1 \cup S_2 \cup S_4 \cup S_5$	<i>S</i> <sub>3</sub>		
4	$S_1 \cup S_2 \cup S_3 \cup S_5$	$S_4$		
5	$S_1 \cup S_2 \cup S_3 \cup S_4$	$S_5$		

get C or all taining instances.

#### Leave One Out Cross Validation

Discussion

• If K = n, each time exactly one training instance is left out as the validation set. This special case is called Leave One Out Cross Validation (LOOCV).



# Cross Validation, Part II Quiz (Graded)

March 2018 Midterm Q9

will report

• Consider the majority classifier that predict  $\hat{y} = \underline{\text{mode}}$  of the training data labels. What is the 2-fold cross validation accuracy (percentage of correct classification) on the following training set.

 x
 1
 2
 3
 4
 5
 6
 7
 8
 9
 10

 y
 1
 1
 0
 1
 1
 0
 0
 1
 0
 0

A: 0 percent, B: 10 percent, C. 20 percent

D: 50 percent, E: 100 percent

## Cross Validation, Part I

Quiz (Graded)

March 2018 Midterm Q9

• Consider the majority classifier that predict  $\hat{y} = \text{mode of the}$  training data labels. What is the LOOCV accuracy (percentage of correct classification) on the following training

set.

				1		7			
x 1	2	3	4	5	6	7	8	9	10
y 1	X	X	1	1/	0	0	1	0	0

A: 0 percent, B: 10 percent, C: 20 percent

D: 50 percent, E: 100 percent



#### Multi-Class Classification

- When there are K categories to classify, the labels can take K different values, y<sub>i</sub> ∈ {1, 2, ..., K}.
- Logistic regression and neural network cannot be directly applied to these problems.





- Train a binary classification model with labels  $y'_i = \mathbb{1}_{\{y_i = j\}}$  for each j = 1, 2, ..., K.
- Given a new test instance x<sub>i</sub>, evaluate the activation function a<sub>i</sub><sup>(j)</sup> from model j.

$$\hat{y}_i = \arg\max_j a_i^{(j)}$$

• One problem is that the scale of  $a_i^{(j)}$  may be different for different j.

# Method 2, One VS One

Discussion



- Train a binary classification model with for each of the  $\frac{K(K-1)}{2}$  pairs of labels.
- Given a new test instance  $x_i$ , apply all  $\frac{K(K-1)}{2}$  models and output the class that receives the largest number of votes.

$$\hat{y}_i = \arg\max_{j} \sum_{j' \neq j} \hat{y}_i^{(j \text{ vs } j')}$$

 One problem is that it is not clear what to do if multiple classes receive the same number of votes.

#### One Hot Encoding

- If y is not binary, use one-hot encoding for y.
- For example, if y has three categories, then

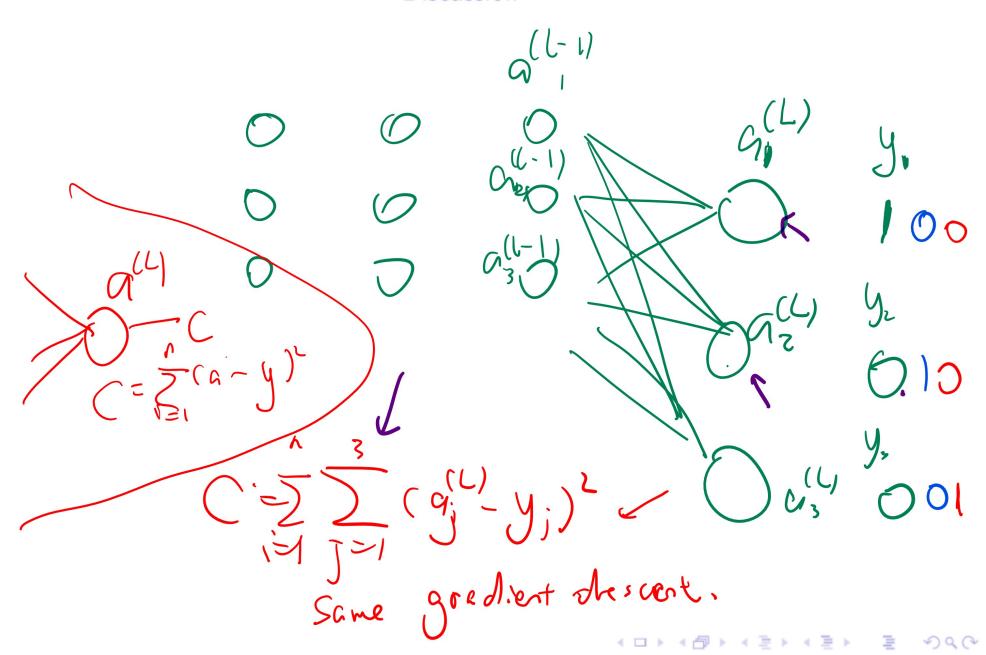
$$y_{i} \in \left\{ \begin{bmatrix} 1\\0\\0\\0 \end{bmatrix}, \begin{bmatrix} 0\\1\\0\\1 \end{bmatrix}, \begin{bmatrix} 0\\0\\1 \end{bmatrix} \right\}$$

# Method 3, Softmax Function Discussion

• For both logistic regression and neural network, the last layer will have K units,  $a_{ij}$ , for j=1,2,...,K and the softmax function is used instead of the sigmoid function.

$$a_{ij} = g\left(w_j^T x_i + b_j\right) = \frac{\exp\left(w_j^T x_i + b_j\right)}{\sum_{j'=1}^K \exp\left(w_{j'}^T x_i + b_{j'}\right)}, j = 1, 2, ..., K$$

## Softmax Function Diagram



- A multi-layer neural network with the same input and output  $y_i = x_i$  is called an autoencoder.
- The hidden layers have fewer units than the dimension of the input m.
- The hidden units form an encoding of the input with reduced dimensionality.

### Autoencode Diagram

#### Generative Adversarial Network

- Two competitive neural networks.
- Generative network input random noise and output fake images.
- ② Discriminative network input real and fake images and output label real or fake.

## Generative Adversarial Network Diagram