# CS540 Introduction to Artificial Intelligence Lecture 17

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## Bridge and Torch Game

## Due Dates and Grades

## Bridge and Torch Game States Motivation

### Search Problem Applications

Motivation

## Wolf, Sheep, Cabbage Example Motivation

### 8 Puzzle Example

Motivation

## Sizes of State Space

• Tic Tac Toe:  $10^3$ 

• Checkers:  $10^{20}$ 

• Chess: 10<sup>50</sup>

• Go: 10<sup>170</sup>

## Water Jugs Example Definition

### Performance Definition

- A search strategy is complete if it finds at least one solution.
- A search strategy is optimal if it finds the optimal solution.
- For uninformed search, the costs are assumed to be 1 for all edges c=1.

## Complexity

- The time complexity of a search strategy is the worst case maximum number of vertices expanded.
- The space complexity of a search strategy is the worst case maximum number of states stored in the frontier at a single time.
- Notation: the goals are d edges away from the initial state.
   This means assuming a constant cost of 1, the optimal solution has cost d. The maximum depth of the graph is D.
- Notation: the branching factor is *b*, the maximum number of actions associated with a state.

$$b = \max_{s \in V} \left| s'(s) \right|$$

## Breadth First Search Description

- Use Queue (FIFO) for the frontier.
- Remove from the front, add to the back.

# BFS Example 1

## BFS Example 1 Diagram

# BFS Example 2

# BFS Example 3

#### Breadth First Search Performance

Discussion

- BFS is complete.
- BFS is optimal with c = 1.

#### Breadth First Search Complexity

Discussion

• Time complexity: the worst case occurs when the goal is the last vertex at depth *d*.

$$T = b + b^2 + ... + b^d$$

• Space complexity: the worst case is storing all vertices at depth *d* is in the frontier.

$$S = b^d$$

## Depth First Search Description

- Use Stack (LIFO) for the frontier.
- Remove from the front, add to the front.

# DFS Example 1

## DFS Example 1 Diagram

# DFS Example 2

# DFS Example 3

### Depth First Search Performance

- DFS is incomplete if  $D = \infty$ .
- DFS is not optimal.

#### Depth First Search Complexity

Discussion

• Time complexity: the worst case occurs when the goal is the root of the last subtree expanded in the whole graph.

$$T = b^{D-d+1}... + b^{D-1} + b^{D}$$

• Space complexity: the worst case is storing all vertices sharing the parents with vertices in the current path.

$$S = (b-1)D + 1$$

## Iterative Deepening Search Description

- $\bullet$  DFS but stop if path length > 1
- repeat DFS but stop if path length > 2
- ...
- repeat DFS but stop if path length > d

## IDS Example 1

## IDS Example 1 Diagram

### Iterative Deepening Search Performance

- IDS is complete.
- IDS is optimal with c = 1.

### Iterative Deepening Search Complexity

Discussion

• Time complexity: the worst case occurs when the goal is the last vertex at depth *d*.

$$T = db + (d-1)b^2 + ... + 3b^{d-2} + 2b^{d-1} + 1b^d$$

• Space complexity: it has the same space complexity as DFS.

$$S = (b-1) d$$

### Configuration Space

Discussion

### Summary

Discussion