

CS540 Introduction to Artificial Intelligence

Lecture 1

Young Wu

Based on lecture slides by Jerry Zhu, Yingyu Liang, and Charles Dyer

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Generative Adversarial Network

Motivation

- Generative Adversarial Network (GAN):
 - ① Generative part: input random noise and output fake images.
 - ② Discriminative part: input real and fake images and output labels real or fake.
 - ③ The two parts compete with each other.

Supervised Learning Example 1

Motivation

Data	images of cats and dogs
Features (Input)	height, length, eye color, ...
Labels (Output)	cat or dog

Data	images of 1000 object classes
Features (Input)	pixel information ...
Labels (Output)	turtle or rifle

Supervised Learning Example 2

Motivation

Data	handwritten characters
Features (Input)	pixel intensity, stroke, ...
Labels (Output)	δ or σ , φ or ψ

Data	voice recording
Features (Input)	signal, sound (phoneme), ...
Labels (Output)	recognize speech or wreck a nice beach

Supervised Learning Example 3

Motivation

Data	medical records
Features (Input)	scan, blood, and test results, ...
Labels (Output)	cancer or no cancer

Data	patient information
Features (Input)	age, pre-existing conditions, ...
Labels (Output)	cancer or no cancer

Supervised Learning Example 4

Motivation

Data	emails
Features (Input)	word count, capitalization, ...
Labels (Output)	spam or ham

Data	comments
Features (Input)	word count, capitalization, ...
Labels (Output)	offensive or not

Supervised Learning Example 5

Motivation

Data	face images
Features (Input)	edges, corners, ...
Labels (Output)	face or non-face

Data	self-driving car data
Features (Input)	color, distance (depth), movement, ...
Labels (Output)	road or car or pedestrian

Supervised Learning Example 6

Motivation

Data	book or movie reviews
Features (Input)	word count, capitalization, ...
Labels (Output)	positive or negative

Data	financial transactions
Features (Input)	amount, frequency, ...
Labels (Output)	fraud or not

Supervised Learning Example 7

Motivation

Data	painting
Features (Input)	appearance, price, ...
Labels (Output)	art or garbage

Data	essay
Features (Input)	length, key words, ...
Labels (Output)	A+ or <i>F</i>

Supervised Learning

Motivation

- Supervised learning:

Data	Features	Labels	-
Sample	$\{(x_{i1}, \dots, x_{im})\}_{i=1}^n$	$\{y_i\}_{i=1}^n$	find "best" \hat{f}
-	observable	known	-
New	(x'_1, \dots, x'_m)	y'	guess $\hat{y} = \hat{f}(x')$
-	observable	unknown	-

Training and Test Sets

Motivation

- Supervised learning:

Data	Features	Labels	-
Training	$\{(x_{i1}, \dots, x_{im})\}_{i=1}^{n'}$	$\{y_i\}_{i=1}^{n'}$	find "good" \hat{f}
-	observable	known	-
Validation	$\{(x_{i1}, \dots, x_{im})\}_{i=n'+1}^n$	$\{y_i\}_{i=n'+1}^n$	find "best" \hat{f}
-	observable	known	-
Test	(x'_1, \dots, x'_m)	y'	guess $\hat{y} = \hat{f}(x')$
-	observable	unknown	-

Linear Classifier

Motivation

- One possible guess is in the form of a linear classifier.

$$\begin{aligned}\hat{y} &= \mathbb{1}_{\{w_1x_1 + w_2x_2 + \dots + w_mx_m + b \geq 0\}} \\ &= \mathbb{1}_{\{w^T x + b \geq 0\}}\end{aligned}$$

- The $\mathbb{1}$ (open number 1) is the indicator function.

$$\mathbb{1}_E = \begin{cases} 1 & \text{if } E \text{ is true} \\ 0 & \text{if } E \text{ is false} \end{cases}$$

Linear Threshold Unit

Motivation

- This simple linear classifier is also called a Linear Threshold Unit (LTU) Perceptron.
- w_1, w_2, \dots, w_m are called the weights, and b is called the bias.
- The function that makes the prediction based on $w^T x + b$ is called the activation function.
- For an LTU Perceptron, the activation function is the indicator function.

$$g(\square) = \mathbb{1}_{\{\square \geq 0\}}$$

Equation of a Line

Motivation

- In $1D$, $w_1x_1 + b \geq 0$ is just a threshold rule: $x_1 \geq -\frac{b}{w_1}$ implies $\hat{y} = 1$.
- In $2D$, $w_1x_1 + w_2x_2 + b \geq 0$ can be written as $\begin{bmatrix} w_1 & w_2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + b \geq 0$. Note that $w_1x_1 + w_2x_2 + b = 0$ is the equation of a line, usually written as $x_2 = -\frac{w_1}{w_2}x_1 - \frac{b}{w_2}$.

Equation of a Hyperplane

Motivation

- In $3D$, $w_1x_1 + w_2x_2 + w_3x_3 + b \geq 0$ can be written as

$$\begin{bmatrix} w_1 & w_2 & w_3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + b \geq 0. \text{ Note that}$$

$w_1x_1 + w_2x_2 + w_3x_3 + b = 0$ is the equation of a plane, and

$\begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix}$ is normal vector of the plane.

- The normal vector is perpendicular to all vectors on the plane.

LTU Perceptron Training

Motivation

- Given the training set $\{(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)\}$, the process of figuring out the weights and the bias is called training an LTU Perceptron.
- A training data point x_i is also called an instance.
- One algorithm to train an LTU Perceptron is called the Perceptron Algorithm.

Perceptron Algorithm

Description

- Initialize random weights.
- Evaluate the activation function at one instance x_i to get \hat{y}_i .
- If the prediction \hat{y}_i is 0 and actual y_i is 1, increase the weights by x_i .
- If the prediction \hat{y}_i is 1 and actual y_i is 0, decrease the weights by x_i .
- Repeat for all data points and until convergent.

Perceptron Algorithm, Part 1

Algorithm

- Inputs: instances: $\{x_i\}_{i=1}^n$ and $\{y_i\}_{i=1}^n$
- Outputs: weights and biases: w_1, \dots, w_m , and b .
- Initialize the weights.

$$w_1, \dots, w_m, b \sim \text{Unif}[-1, 1]$$

Unif $[l, u]$ means picking a random number between l and u .

- Evaluate the activation function at a single data point x_i .

$$a_i = \mathbb{1}_{\{w^T x_i + b \geq 0\}}$$

Perceptron Algorithm, Part 2

Algorithm

- Update weights using the following rule.

$$w = w - \alpha (a_i - y_i) x_i$$

$$b = b - \alpha (a_i - y_i)$$

- Repeat the process for every $x_i, i = 1, 2, \dots, n$.
- Repeat until $a_i = y_i$ for every $i = 1, 2, \dots, n$.

Learning Rate

Discussion

- The learning rate α controls how fast the weights are updated.
- They can be constant for each update or they can change (usually decrease) for each update.
- For perceptron learning, it is typically set to 1.