CS540 Introduction to Artificial Intelligence Lecture 4

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Based on lecture slides by Jerry Zhu, Yingyu Liang, and Charles Dyer

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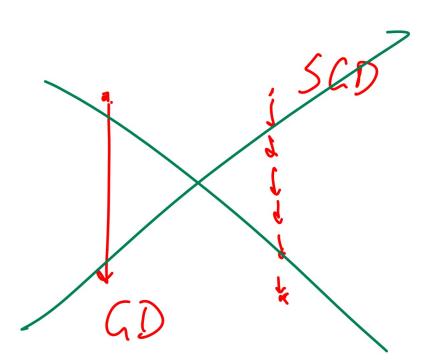
Perceptron Algorithm vs Logistic Regression

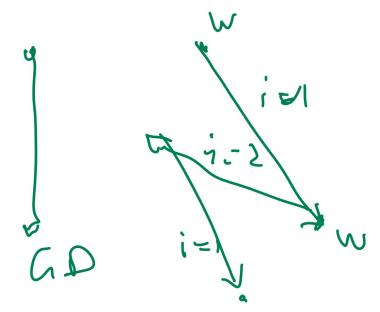
- For LTU Perceptrons, w is updated for each instance x_i sequentially. $w = w \alpha (a_i y_i) x_i$
- For Logistic Perceptrons, w is updated using the gradient that involves all instances in the training data.

stances in the training data.
$$w = w - di \sum_{i=1}^{n} (a_i - y_i) x_i \qquad \longleftarrow \qquad \frac{\partial}{\partial \omega}$$

Stochastic Gradient Descent Diagram

Motivation





Stochastic Gradient

 Full gradient descent computes the gradient with respect to all instances.

$$w = w - \alpha \frac{\partial C}{\partial w} = w - \alpha \sum_{i=1}^{n} \frac{\partial C_i}{\partial w}$$

 Stochastic gradient descent repeatedly select a random instance i and computes the gradient with respect to that instance.

$$w = w - \alpha \frac{\partial C_i}{\partial w}$$

 Usually, random sampling is done without replacement by shuffling the training set instead of sampling with replacement, so that all instances are included in each iteration (called an epoch).

Choice of Learning Rate

- Changing the learning rate α as the weights get closer to the optimal weights could speed up convergence.
- Popular choices of learning rate include $\frac{\alpha}{\sqrt{t}}$ and $\frac{\alpha}{t}$, where t is the current number of iterations.
- Other methods of choosing step size include using the second derivative (Hessian) information, such as Newton's method and BFGS, or using information about the gradient in previous steps, such as adaptive gradient methods like AdaGrad and Adam.

Multi-Class Classification

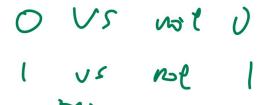
Motivation

J(w7x+b) +
[0,1]

- When there are K categories to classify, the labels can take K different values, y_i ∈ {1, 2, ..., K}.
- Logistic regression and neural network cannot be directly applied to these problems.

Method 1, One VS All

Discussion



- Train a binary classification model with labels $y_i' = \mathbb{1}_{\{y_i = j\}}$ for each j = 1, 2, ..., K.
- Given a new test instance x_i, evaluate the activation function a_i^(j) from model j.

$$\hat{y}_i = \underset{j}{\operatorname{argmax}} \underline{a}_i^{(j)}$$

 One problem is that the scale of a_i^(j) may be different for different j.

Method 2, One VS One

Discussion

- Train a binary classification model for each of the $\frac{K(K-1)}{2}$ pairs of labels.
- Given a new test instance x_i , apply all $\frac{K(K-1)}{2}$ models and output the class that receives the largest number of votes.

$$\hat{y}_i = \underset{j}{\operatorname{argmax}} \sum_{j' \neq j} \hat{y}_i^{(j \text{ vs } j')}$$

 One problem is that it is <u>not clear</u> what to do if multiple classes receive the same number of votes.

One Hot Encoding

$$(y-\alpha)^2$$

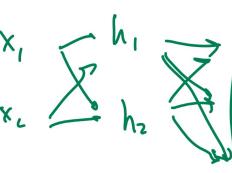
- If y is not binary, use one-hot encoding for y.
- For example, if y has three categories, then

$$y_i \in \left\{ \begin{bmatrix} 1\\0\\0 \end{bmatrix}, \begin{bmatrix} 0\\1\\0 \end{bmatrix}, \begin{bmatrix} 0\\0\\1 \end{bmatrix} \right\}$$

Method 3, Softmax Function

Snnzl

Discussion



 For both logistic regression and neural network, the last layer will have K units, a_{ij}, for j = 1, 2, ..., K, and the softmax function is used instead of the sigmoid function.

$$a_{ij} = g\left(w_j^T x_i + b_j\right) = \frac{\exp\left(-w_j^T x_i - b_j\right)}{\sum_{j'=1}^K \exp\left(-w_{j'}^T x_i - b_{j'}\right)}, j = 1, 2, ..., K$$

$$\sum_{j'=1}^J \exp\left(-w_{j'}^T x_i - b_{j'}\right)$$

$$C = \sum_{j=1}^J o_j y_j$$

Softmax Derivatives

Discussion

- Cross entropy loss is also commonly used with a softmax activation function.
- The gradient of cross-entropy loss with respect to a_{ij}, component j of the output layer activation for instance i has the same form as the one for logistic regression.

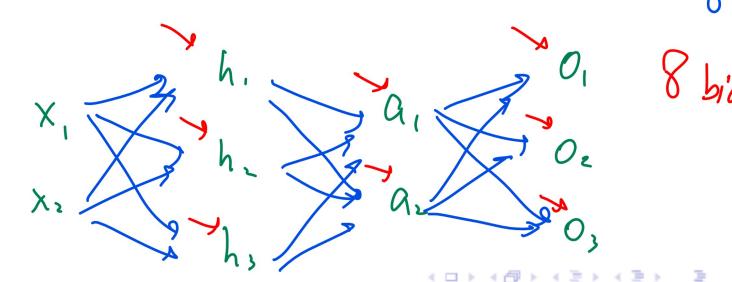
$$\frac{\partial C}{\partial a_{ij}} = a_{ij} - y_{ij} \Rightarrow \nabla_{a_i} C = a_i - y_i$$

 The gradient with respect to the weights can be found using the chain rule.

Softmax Diagram

Weight Count

• How many weights and biases are there in a (fully connected) three-layer neural network with 2 input units, 3 hidden units in the first hidden layer, 2 hidden units in the second hidden layer, and 3 output units?



Weight Count 2

Quiz

QT

 How many weights (not including bias) are there in a (fully connected) two-layer neural network with 10 input units, 5 hidden units, and 10 output units.

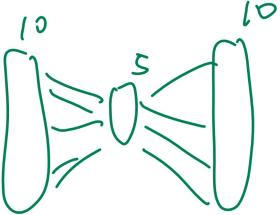
A:50

B:55

• C: 100

D: 110

• E:500



Weight Count 3

Quiz

Qb

 How many biases are there in a (fully connected) two-layer neural network with 10 input units, 5 hidden units, and 10 output units.

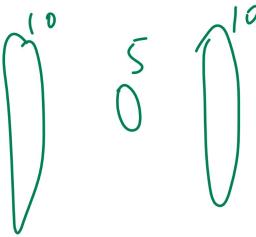
A:5

B: 10

• C:15

D: 20

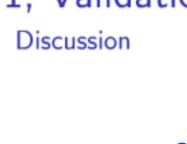
E: 25

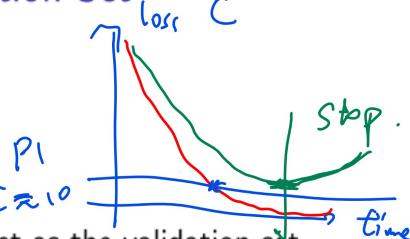


Generalization Error Diagram

Motivation

Method 1, Validation Set





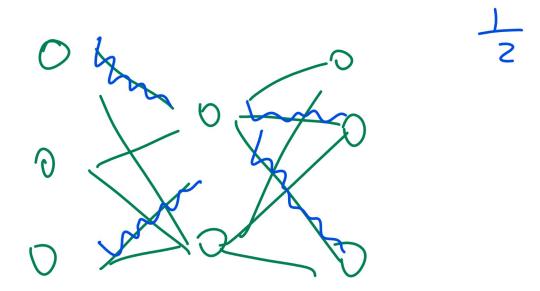
- Set aside a subset of the training set as the validation set.
- During training, the cost (or accuracy) on the training set will always be decreasing until it hits 0.
- Train the network until the cost (or accuracy) on the validation set begins to increase.

Validation Set Diagram

Method 2, Drop Out

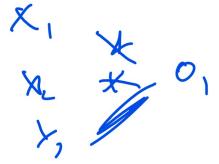
- At each hidden layer, a random set of units from that layer is set to 0.
- For example, each unit is retained with probability p = 0.5.
 During the test, the activations are reduced by p = 0.5 (or 50 percent).
- The intuition is that if a hidden unit works well with different combinations of other units, it does not rely on other units and it is likely to be individually useful.

Drop Out Diagram



Method 3, L1 and L2 Regularization Discussion

- The idea is to include an additional cost for non-zero weights.
- The models are simpler if many weights are zero.
- For example, if logistic regression has only a few non-zero weights, it means only a few features are relevant, so only these features are used for prediction.



Method 3, L1 Regularization

Discussion

 For L1 regularization, add the 1-norm of the weights to the cost.

$$C = \sum_{i=1}^{n} (a_i - y_i)^2 + \lambda \left\| \begin{bmatrix} w \\ b \end{bmatrix} \right\|_1$$
$$= \sum_{i=1}^{n} (a_i - y_i)^2 + \lambda \left(\sum_{i=1}^{m} |w_i| + |b| \right)$$

 Linear regression with L1 regularization is called LASSO (least absolute shrinkage and selection operator).

Method 3, L2 Regularization

Discussion

 For L2 regularization, add the 2-norm of the weights to the cost.

$$C = \sum_{i=1}^{n} (a_i - y_i)^2 + \lambda \left\| \begin{bmatrix} w \\ b \end{bmatrix} \right\|_2^2$$

$$= \sum_{i=1}^{n} (a_i - y_i)^2 + \lambda \left\| \left(\sum_{i=1}^{m} w_i^2 + b^2 \right) \right\|$$

$$\mathcal{L} = \mathcal{L} - \mathcal{L} \frac{\partial \mathcal{L}}{\partial w} - \mathcal{L} \mathcal{L}$$

Method 4, Data Augmentation

Discussion

 More training data can be created from the existing ones, for example, by translating or rotating the handwritten digits.

Pixel Intensity Features

Recognizing Handwritten Digits Demo

Questions about P1

Admin



- Cost function? Any is okay.
- Learning rate? Try things.
- Stopping criterion? Discuss on Piazza (cost, gradient, max iterations). (CCIO)

 • Stochastic vs regular gradient descent? Either. ~5 min
- Regularization? If you want.
- Use test set to train? NO.
- Other questions?

