

# CS540 Introduction to Artificial Intelligence

## Lecture 6

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Decision Tree

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Random Forest

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Nearest Neighbor

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# Hat Game

## Quiz

# Hat Game Diagram

## Discussion

# Axes Aligned Decision Boundary

## Motivation

# Decision Tree

## Description

- Find the feature that is the most informative.
- Split the training set into subsets according to this feature.
- Repeat on the subsets until all the labels in the subset are the same.

# Binary Entropy

## Definition

- Entropy is the measure of uncertainty.
- The value of something uncertain is more informative than the value of something certain.
- For binary labels,  $y_i \in \{0, 1\}$ , suppose  $p_0$  fraction of labels are 0 and  $1 - p_0 = p_1$  fraction of the training set labels are 1, the entropy is:

$$\begin{aligned} H(Y) &= p_0 \log_2 \left( \frac{1}{p_0} \right) + p_1 \log_2 \left( \frac{1}{p_1} \right) \\ &= -p_0 \log_2 (p_0) - p_1 \log_2 (p_1) \end{aligned}$$

# Entropy

## Definition

- If there are  $K$  classes and  $p_y$  fraction of the training set labels are in class  $y$ , with  $y \in \{1, 2, \dots, K\}$ , the entropy is:

$$\begin{aligned} H(Y) &= \sum_{y=1}^K p_y \log_2 \left( \frac{1}{p_y} \right) \\ &= - \sum_{y=1}^K p_y \log_2 (p_y) \end{aligned}$$

Decision Tree

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Random Forest

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Nearest Neighbor

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# Entropy

## Quiz



# Entropy Math

## Quiz

# Entropy 2

## Quiz

# Conditional Entropy

## Definition

- Conditional entropy is the entropy of the conditional distribution. Let  $K_X$  be the possible values of a feature  $X$  and  $K_Y$  be the possible labels  $Y$ . Define  $p_x$  as the fraction of the instances that are  $x$ , and  $p_{y|x}$  as the fraction of the labels that are  $y$  among the ones with instance  $x$ .

$$H(Y|X = x) = - \sum_{y=1}^{K_Y} p_{y|x} \log_2(p_{y|x})$$

$$H(Y|X) = \sum_{x=1}^{K_X} p_x H(Y|X = x)$$

## Aside: Cross Entropy

### Definition

- Cross entropy measures the difference between two distributions.

$$H(Y, X) = - \sum_{z=1}^K p_{Y=z} \log_2 (p_{X=z})$$

- It is used in logistic regression to measure the difference between actual label  $Y_i$  and the predicted label  $A_i$  for instance  $i$ , and at the same time, to make the cost convex.

$$H(Y_i, A_i) = -y_i \log(a_i) - (1 - y_i) \log(1 - a_i)$$

# Information Gain

## Definition

- The information gain is defined as the difference between the entropy and the conditional entropy.

$$I(Y|X) = H(Y) - H(Y|X).$$

- The larger than information gain, the larger the reduction in uncertainty, and the better predictor the feature is.

# Splitting Discrete Features

## Definition

- The most informative feature is the one with the largest information gain.

$$\operatorname{argmax}_j I(Y|X_j)$$

- Splitting means dividing the training set into  $K_{X_j}$  subsets.

$$\{(x_i, y_i) : x_{ij} = 1\}, \{(x_i, y_i) : x_{ij} = 2\}, \dots, \{(x_i, y_i) : x_{ij} = K_{X_j}\}$$

# Splitting Continuous Variables Diagram

## Definition

# ID3 Algorithm (Iterative Dichotomiser 3)

## Description



# Pruning Diagram

## Discussion

# Bagging Diagram

## Discussion

# Boosting Diagram

## Discussion

# $K$ Nearest Neighbor

## Description

- Given a new instance, find the  $K$  instances in the training set that are the closest.
- Predict the label of the new instance by the majority of the labels of the  $K$  instances.

# Distance Function

## Definition

- Many distance functions can be used in place of the Euclidean distance.

$$\rho(x, x') = \|x - x'\|_2 = \sqrt{\sum_{j=1}^m (x_j - x'_j)^2}$$

- An example is Manhattan distance.

$$\rho(x, x') = \sum_{j=1}^m |x_j - x'_j|$$

# Manhattan Distance Diagram

## Definition

# 1 Nearest Neighbor

## Quiz

# 3 Nearest Neighbor

## Quiz



# *K* Fold Cross Validation

## Discussion

# 5 Fold Cross Validation Example

## Discussion

# Leave One Out Cross Validation

## Discussion

# Cross Validation

## Quiz

# Cross Validation 2

## Quiz

# Lecture Next Week

## Admin