# CS540 Introduction to Artificial Intelligence Lecture 12

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Based on lecture slides by Jerry Zhu, Yingyu Liang, and Charles Dyer

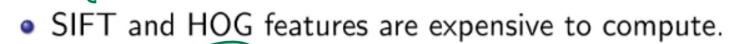
July 8, 2022

#### Discussion Admin

- M3 bug to be fixed, no need to resubmit.
- D1 grades still not fixed.
  - Please do not sign up for homework not assigned. The first two (correct) posts will get the points (regardless of the sign up).

#### SIFT and HOG Features

Motivation



 Simpler features should be used for real-time face detection tasks.

#### Real-Time Face Detection

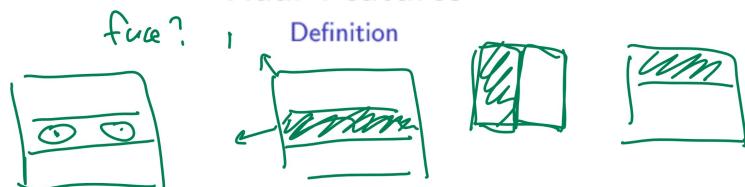
Motivation

- Each image contains 10000 to 500000 locations and scales.
  Faces occur in 0 to 50 per image.
  Want a very small number of false positives.

### Haar Features Diagram

Motivation

#### Haar Features



 Haar features are differences between sums of pixel intensities in rectangular regions. Some examples include convolution with the following filters.

$$\begin{bmatrix}1&1\\-1&-1\end{bmatrix},\begin{bmatrix}1&-1\\1&-1\end{bmatrix},\begin{bmatrix}1&-1&1\\1&-1&1\end{bmatrix},\begin{bmatrix}1&-1\\-1&1\end{bmatrix}...$$

#### Weak Classifiers

#### Definition

PL

Each weak classifier is a decision stump (decision tree with / only one split) using one Haar feature x.

$$f(x) = \mathbb{I}_{\{x > \theta\}}$$

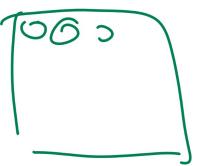
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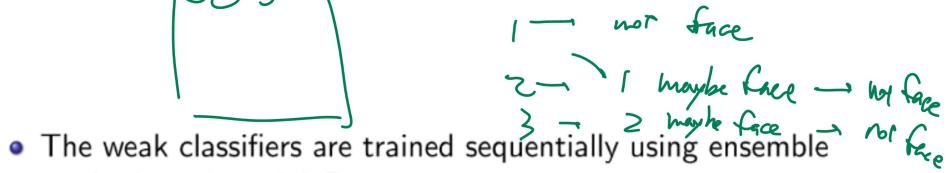
• Finding the threshold by comparing the information gain from all possible splits is too expensive, so  $\theta$  is usually computed as the average of the mean values of the feature for each class.

$$\theta = \frac{1}{2} \left( \frac{1}{n_0} \sum_{i: y_i = 0} x_i + \frac{1}{n_1} \sum_{i: y_i = 1} x_i \right)$$

### Strong Classifiers

#### Definition





- methods such as AdaBoost.
- A sequence of T weak classifiers is called aT -strong classifier.
- Multiple T -strong classifiers can be trained for different values of T and combined into a cascaded classifier.

#### Cascaded Classifiers

#### Definition

- Start with aT -strong classifier with small T, and use it reject obviously negative regions (regions with no faces).
- Train and use aT -strong classifier with larger T on only the regions that are not rejected.
- Repeat this process with stronger classifiers.

### Cascading

Definition

• For example, at T=1, the classifier achieves a100 percent detection rate and a50 percent false-positive rate.

- At T = 5, the classifier achieves a100 percent detection rate and a40 percent false-positive rate.
- At T = 20, the classifier achieves a100 percent detection rate and a10 percent false-positive rate.
- The result is a cascaded classifier with 100 percent detection rate and  $0.5 \cdot 0.4 \cdot 0.1 = 2$  percent false positive rate.



Discussion

boosting

Haar A Deeson Strong

- Each classifier operates on a 24 by 24 region of the image.
- Multiple scales of the image with a scaling factor of 1.25 are used. The classifiers can be scaled instead in practice so that the integral image only needs to be calculated once.
- The detector is moved around the image with stride 1.
- Nearby detections of faces are combined into a single detection.

### Viola-Jones Diagram

Discussion

### Learning Convolution Motivation

weights

 The convolution filters used to obtain the features can be learned in a neural network. Such networks are called convolutional neural networks and they usually contain multiple convolutional layers with fully connected and softmax layers near the end.

### Convolutional Layers

#### Definition

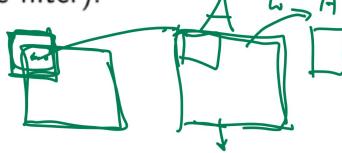
 In the (fully connected) neural networks discussed previously, each input unit is associated with a different weight.

$$a = g\left(w^{T}x + b\right)$$

$$chot product$$

 In the convolutional layers, one single filter (a multi-dimensional array of weights) is used for all units (arranged in an array the same size as the filter).

$$A = g \left( \frac{W * X + b}{\bigcirc } \right)$$



## 2D Convolutional Layer Diagram Definition

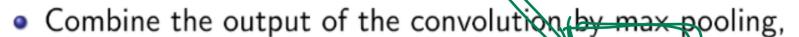
## 3D Convolutional Layer Diagram Definition



Definition

W

w,



$$a = \max\{x_1...x_m\}$$

Combine the output of the convolution by average pooling,

$$a = \frac{1}{m} \sum_{i=1}^{m} x_i$$



## Pooling Diagram Definition

### Training Convolutional Neural Networks, Part I

#### Discussion

- The training is done by gradient descent.
- The gradient for the convolutional layers with respect to the filter weights is the convolution between the inputs to that layer and the output gradient from the next layer.

 The gradient for the convolutional layers with respect to the inputs is the convolution between the 180 degrees rotated filter and the output gradient from the next layer.

$$\frac{\partial C}{\partial X} = \text{rot } W * \frac{\partial C}{\partial O}$$

### Training Convolutional Neural Networks, Part II

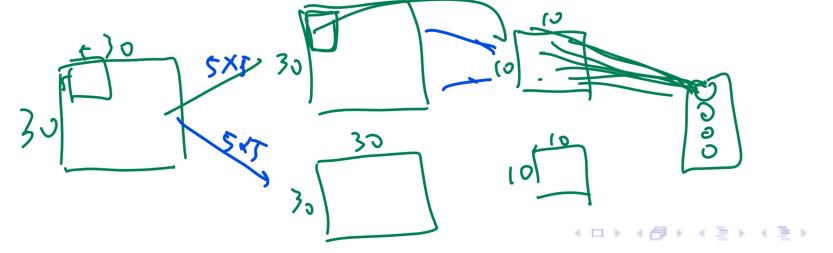
- There are usually no weights in the pooling layers.
- The gradient for the max-pooling layers is 1 for the maximum input unit and 0 for all other units.
- The gradient for the average pooling layers is  $\frac{1}{m}$  for each of the m units.

### LeNet Diagram and Demo

Discussion

## Convolutional Neural Network Weights 1 Quiz

Given a <u>CNN</u> with 30 × 30 input images, with 5 × 5 filters, zero-padding, stride 1, and two activation maps in the first layer, then 3 × 3 max pooling, no padding, stride 3 in the second layer, 4 output units in the last fully-connected layer. What is the number of weights (not including biases) that need to be trained.



### Convolutional Neural Network Weights 2

Quiz

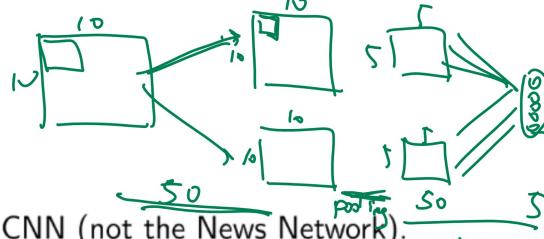
Given a CNN with 10 × 10 input images, with 5 × 5 filters, zero-padding, stride 1, and two activation maps in the first layer, then 2 × 2 max pooling, no padding, stride 2 in the second layer, 5 output units in the last fully-connected layer. What is the number of weights (not including biases) that need to be trained.

 $\bullet$  A: 25 + 0 + 125

B:50+0+250

• C: 25+4+125

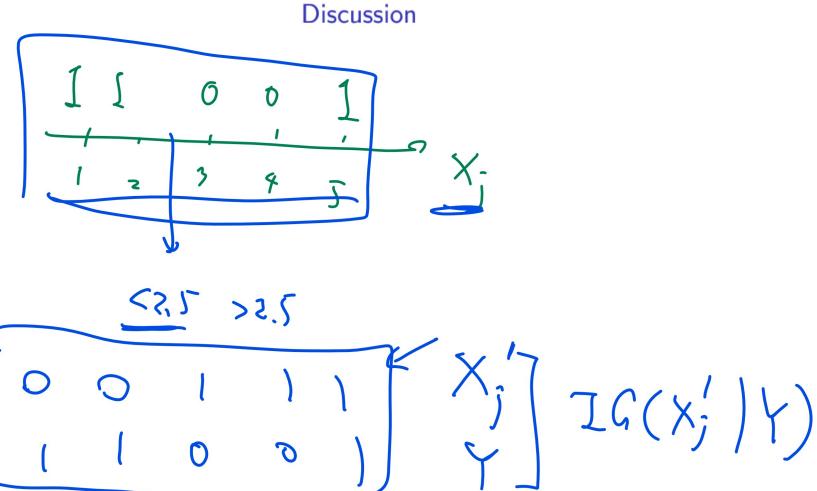
• D:50+8+250



 $\bullet$  E: I don't understand CNN (not the News Network)

#### AlexNet Diagram





## VGG, GoogleNet, ResNet Discussion