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CS540 Introduction to Artificial Intelligence Lecture 2

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Based on lecture slides by Jerry Zhu, Yingyu Liang, and Charles Dyer

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Zero-One Loss Function **Motivation**

An objective function is needed to select the "best" \hat{f} . An example is the zero-one loss.

$$
\hat{f} = \operatorname*{argmin}_{f} \sum_{i=1}^{n} \mathbb{1}_{\{f(x_i) \neq y_i\}}
$$

- argmin_f objective (f) outputs the function that minimizes the objective.
- The objective function is called the cost function (or the loss function), and the objective is to minimize the cost.

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Squared Loss Function **Motivation**

- Zero-one loss counts the number of mistakes made by the classifier. The best classifier is the one that makes the fewest mistakes.
- Another example is the squared distance between the predicted and the actual y value:

$$
\hat{f} = \operatorname*{argmin}_{f} \frac{1}{2} \sum_{i=1}^{n} \left(f(x_i) - y_i \right)^2
$$

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Hypothesis Space **Motivation**

- There are too many functions to choose from.
- \bullet There should be a smaller set of functions to choose \hat{f} from.

$$
\hat{f} = \operatorname*{argmin}_{f \in \mathcal{H}} \frac{1}{2} \sum_{i=1}^{n} \left(f(x_i) - y_i \right)^2
$$

• The set H is called the hypothesis space.

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Linear Regression **Motivation**

• For example, H can be the set of linear functions. Then the problem can be rewritten in terms of the weights.

$$
\left(\hat{w}_1, ..., \hat{w}_m, \hat{b}\right) = \underset{w_1, ..., w_m, b}{\text{argmin}} \frac{1}{2} \sum_{i=1}^n (a_i - y_i)^2
$$
\nwhere $a_i = w_1 x_{i1} + w_2 x_{i2} + ... + w_m x_{im} + b$

The problem is called (least squares) linear regression.

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Binary Classification **Motivation**

- \bullet If the problem is binary classification, y is either 0 or 1, and linear regression is not a great choice.
- This is because if the prediction is either too large or too small, the prediction is correct, but the cost is large.

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Activation Function **Motivation**

• Suppose H is the set of functions that are compositions between another function g and linear functions.

$$
\left(\hat{w}, \hat{b}\right) = \underset{w, b}{\operatorname{argmin}} \frac{1}{2} \sum_{i=1}^{n} \left(a_i - y_i\right)^2
$$
\nwhere $a_i = g\left(w^T x + b\right)$

 \bullet g is called the activation function.

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Linear Threshold Unit **Motivation**

• One simple choice is to use the step function as the activation function:

$$
g\left(\square\right) = \mathbb{1}_{\left\{\square \geqslant 0\right\}} = \left\{\begin{array}{ll} 1 & \text{if } \square \geqslant 0 \\ 0 & \text{if } \square < 0 \end{array}\right.
$$

This activation function is called linear threshold unit (LTU).

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Sigmoid Activation Function **Motivation**

 \bullet When the activation function g is the sigmoid function, the problem is called logistic regression.

$$
g\left(\fbox{...}\right)=\frac{1}{1+\exp\left(-\fbox{...}\right)}
$$

 \bullet This g is also called the logistic function.

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Cross-Entropy Loss Function **Motivation**

• The cost function used for logistic regression is usually the log cost function.

$$
C(f) = -\sum_{i=1}^{n} (y_i \log (f(x_i)) + (1 - y_i) \log (1 - f(x_i)))
$$

• It is also called the cross-entropy loss function.

Logistic Regression Objective **Motivation**

The logistic regression problem can be summarized as the following.

$$
\left(\hat{w}, \hat{b}\right) = \underset{w, b}{\operatorname{argmin}} - \sum_{i=1}^{n} \left(y_i \log\left(a_i\right) + (1 - y_i) \log\left(1 - a_i\right)\right)
$$
\nwhere $a_i = \frac{1}{1 + \exp\left(-z_i\right)}$ and $z_i = w^T x_i + b$

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Logistic Regression **Description**

- Initialize random weights.
- **•** Evaluate the activation function.
- Compute the gradient of the cost function with respect to each weight and bias.
- Update the weights and biases using gradient descent.
- Repeat until convergent.

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Gradient Descent Intuition Definition

- \bullet If a small increase in w_1 causes the distances from the points to the regression line to decrease: increase w_1 .
- \bullet If a small increase in w_1 causes the distances from the points to the regression line to increase: decrease w_1
- The change in distance due to change in w_1 is the derivative.
- The change in distance due to change in $\begin{bmatrix} w & w \end{bmatrix}$ b is the gradient.

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Gradient Definition

- The gradient is the vector of derivatives.
- The gradient of $f(x_i) = w^T x_i + b = w_1 x_{i1} + w_2 x_{i2} + ... + w_m x_{im} + b$ is: $\nabla_w f =$ \mathbf{I} $\begin{array}{c} \hline \end{array}$ ∂f $\partial_{\mathcal{A}}^{\mathcal{W}_{1}}$ ∂t ∂w_2
... ∂f ∂w_m $\overline{1}$ $\begin{array}{c} \hline \end{array}$ $=$ Γ $\Big\}$ x_{i1} x_{i2} ... xim T $\Bigg| = x_i$ $\nabla_b f = 1$

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Chain Rule Definition

• The gradient of $f(x_i) = g(w^T x_i + b) = g(w_1 x_i_1 + w_2 x_i_2 + ... + w_m x_i_m + b)$ can be found using the chain rule.

$$
\nabla_{w} f = g' \left(w^{T} x_{i} + b \right) x_{i}
$$

$$
\nabla_{b} f = g' \left(w^{T} x_{i} + b \right)
$$

• In particular, for the logistic function g :

$$
g\left(\frac{\cdot}{\cdot}\right) = \frac{1}{1 + \exp\left(-\frac{\cdot}{\cdot}\right)}
$$

$$
g'\left(\frac{\cdot}{\cdot}\right) = g\left(\frac{\cdot}{\cdot}\right)\left(1 - g\left(\frac{\cdot}{\cdot}\right)\right)
$$

Gradient Descent Step Definition

• For logistic regression, use chain rule twice.

$$
w = w - \alpha \sum_{i=1}^{n} (a_i - y_i) x_i
$$

\n
$$
b = b - \alpha \sum_{i=1}^{n} (a_i - y_i)
$$

\n
$$
a_i = g \left(w^T x_i + b \right), g \left(\underline{\cdot} \right) = \frac{1}{1 + \exp \left(- \underline{\cdot} \right)}
$$

 \bullet α is the learning rate. It is the step size for each step of gradient descent.

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Perceptron Algorithm Definition

Update weights using the following rule.

$$
w = w - \alpha (a_i - y_i) x_i
$$

\n
$$
b = b - \alpha (a_i - y_i)
$$

\n
$$
a_i = \mathbb{I}_{\{w^T x_i + b \ge 0\}}
$$

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Logistic Regression, Part 1 Algorithm

- Inputs: instances: $\{x_i\}_i^n$ $_{i=1}^n$ and $\{y_i\}_{i=1}^n$ $i=1$
- Outputs: weights and biases: $w_1, w_2, ..., w_m$ and b
- Initialize the weights.

$$
w_1, ..., w_m, b \sim \text{Unif } [-1, 1]
$$

• Evaluate the activation function.

$$
a_i = g\left(w^T x_i + b\right), g\left(\underline{\cdot}\right) = \frac{1}{1 + \exp\left(-\underline{\cdot}\right)}
$$

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Logistic Regression, Part 2 Algorithm

Update the weights and bias using gradient descent.

$$
w = w - \alpha \sum_{i=1}^{n} (a_i - y_i) x_i
$$

$$
b = b - \alpha \sum_{i=1}^{n} (a_i - y_i)
$$

• Repeat the process until convergent.

$$
|C - C^{\text{prev}}| < \varepsilon
$$

Stopping Rule and Local Minimum **Discussion**

- Start with multiple random weights.
- Use smaller or decreasing learning rates. One popular choice $\frac{\alpha}{\sqrt{t}}$, where t is the iteration count.
- **.** Use the solution with the lowest C.

Regression vs Classification **Discussion**

- Logistic regression is usually used to solve classification problems (y is discrete or categorical), not regression problems $(y$ is continuous).
- This course (and machine learning in general) will focus on solving classification problems.

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Other Non-linear Activation Function **Discussion**

- Activation function: $g(\lceil \cdot \rceil) = \tanh(\lceil \cdot \rceil) =$ e^{\pm} – $e^{-\pm}$ $e^{\underline{\hspace{1ex}}} + e^{-\underline{\hspace{1ex}}}$
- Activation function: $g(\lceil \cdot \rceil) = \arctan(\lceil \cdot \rceil)$
- Activation function (rectified linear unit): $g\left(\fbox{ } \right) = \fbox{ } \left[\fbox{ } \right]_{\left\{\fbox{ } \right\} \geqslant 0 \right\}}$
- All these functions lead to objective functions that are convex and differentiable (almost everywhere). Gradient descent can be used.

Convexity Discussion

- If a function is convex, gradient descent with any initialization will converge to the global minimum (given sufficiently small learning rate).
- If a function is not convex, gradient descent with different initializations may converge to different local minima.
- A twice differentiable function is convex if and only its second derivative is non-negative.
- In the multivariate case, it means the Hessian matrix is positive semidefinite.

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Positive Semidefinite **Discussion**

Hessian matrix is the matrix of second derivatives:

$$
H: H_{ij} = \frac{\partial^2 f}{\partial x_i \partial x_j}
$$

- A matrix H is positive semidefinite if $x^T H x \ge 0 \forall x \in \mathbb{R}^n$.
- A symmetric matrix is positive semidefinite if and only if all of its eigenvalues are non-negative.